

SoSECIE Webinar

Welcome to the
2020 System of Systems Engineering Collaborators
Information Exchange (SoSECIE)



We will start at 11AM Eastern Time

You can download today's presentation from the SoSECIE Website:

<https://mitre.tahoe.appsembler.com/blog>

To add/remove yourself from the email list or suggest a future topic or speaker, send an email to sosecie@mitre.org

NDIA System of Systems SE Committee

- **Mission**

- To provide a forum where government, industry, and academia can share lessons learned, promote best practices, address issues, and advocate systems engineering for Systems of Systems (SoS)
- To identify successful strategies for applying systems engineering principles to systems engineering of SoS

- **Operating Practices**

- Face to face and virtual SoS Committee meetings are held in conjunction with NDIA SE Division meetings that occur in February, April, June, and August

NDIA SE Division SoS Committee Industry Chairs:

Mr. Rick Poel, Boeing

Ms. Jennie Horne, Raytheon

OSD Liaison:

Dr. Judith Dahmann, MITRE

Simple Rules of Engagement

- I have muted all participant lines for this introduction and the briefing.
- If you need to contact me during the briefing, send me an e-mail at sosecie@mitre.org.
- Download the presentation so you can follow along on your own
- We will hold all questions until the end:
 - I will start with questions submitted online via the CHAT window in Teams.
 - I will then take questions via telephone; State your name, organization, and question clearly.
- If a question requires more discussion, the speaker(s) contact info is in the brief.

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2021-2022 System of Systems Engineering Collaborators Information Exchange Webinars

Sponsored by MITRE and NDIA SE Division

January 26, 2021

***Addressing the Sustainable Development Goals with a System-of-Systems for Monitoring
Arctic Coastal Regions***

Evelyn Honoré-Livermore, Roger Birkeland and Cecilia Haskins

February 23, 2021

Interface Management- the Neglected Orphan of Systems Engineering

Paul Davies

March 9, 2021

Distributed Architecture for Monitoring Urban Air Quality: A Systems Engineering Approach

Adrián Unger, Tom McDermott and Philip Dewire

April 6, 2021

Holistic architecture description for a future Global Health Assurance Systems of Systems

Adrián Unger



30th Annual **INCOSE**
international symposium

Virtual Event
July 20 - 22, 2020

July 22, 2020: 17:50-18:30 South Africa Standard Time (Track 2, Session 9.2.3)

Case Study: Achieving System Integration through Interoperability in a large System of Systems (SoS)

Oliver Hoehne, PMP, CSEP, CSM
Technical Fellow, Systems Engineering
WSP USA
oliver.hoehne@wsp.com

www.incose.org/symp2020



AGENDA



❖ Introduction

- System of Systems (SoS)
- California High-Speed Rail System (CHSRS) Program
- CHSRS as a System of Systems

❖ SoSE Challenges Faced

- Traditional Industry Approach to Systems Integration
- SoS Engineering Challenges

❖ SoSE Activities Performed

- International Best Practice Analysis of HSR System Integration
- SoS Integration Strategy
- Step by Step Process Description

❖ Summary, Achieved Outcomes & Conclusion

INTRODUCTION: SYSTEM OF SYSTEMS

SoS DEFINITION & CHARACTERISTICS



ISO/IEC/IEEE 15288:2015(E)

Annex G
(informative)

ISO/IEC/IEEE 15288,
2015, ANNEX G

Application of system life cycle processes to a system of systems

G.1 Introduction

A system of systems (SoS) is a system-of-interest (SOI) whose elements are themselves systems. A SoS brings together a set of systems for a task that none of the systems can accomplish on its own. Each constituent system keeps its own management, goals, and resources while coordinating within the SoS and adapting to meet SoS goals. In the context of terminology discussed in subclause 5.2.3 (as shown in Figure 3), the composite set of systems including the original SOI, enabling systems and interacting systems, together constitute an SoS. Where there are concerns that affect the composite set, the system of systems becomes the SOI, which is considered to satisfy some business or mission objective that cannot be satisfied by the individual constituent systems, or to understand emergent behavior of the combination.

This annex addresses the application of system life cycle processes to such SoS. It describes general characteristics, the common types of SoS, and the implications throughout the life cycle.

G.2 SoS characteristics and types

SoS are characterized by managerial and operational independence of the constituent systems, which in many cases were developed and continue to support originally identified users concurrently with users of the SoS. In other contexts, each constituent system itself is a SOI; its existence often predates the SoS, while its characteristics were originally engineered to meet the needs of their initial users. As constituents of the SoS, their consideration is expanded to encompass the larger needs of the SoS. This implies added complexity particularly when the systems continue to evolve independently of the SoS. The constituent systems also typically retain their original stakeholders and governance mechanisms, which limits alternatives to address the needs of the SoS.

SoS have been characterized into four types based on the governance relationships between the constituent systems and the SoS (Figure G.1). The strongest governance relations apply to directed system of systems, where the SoS organization has authority over the constituent systems despite the fact that the constituent systems may not have originally been engineered to support the SoS. Somewhat less control is afforded for acknowledged SoS, where allocated authority between the constituent systems and the systems of systems has an impact on application of some of the systems engineering processes. In collaborative SoS, which lack system of systems authorities, application of systems engineering depends on cooperation among the constituent systems. Virtual systems of systems are largely self organizing and offer much more limited opportunity for systems engineering of the SoS.

Emergence is a key characteristic of SoS – the unanticipated effects at the systems of systems level attributed to the complex interaction dynamics of the constituent systems. In SoS, constituent systems are intentionally considered in their combination, so as to obtain and analyze outcomes not possible to obtain with the systems alone. The complexity of the constituent systems and the fact they may have been designed without regard to their role in the SoS, can result in new, unexpected behaviors. Identifying and addressing unanticipated emergent results is a particular challenge in engineering SoS.

Definition: A system of systems (SoS) is a system-of-interest (SOI) whose elements are themselves systems.

A SoS brings together a set of systems for a task that none of the systems can accomplish on its own.

Each constituent system (CS) retains its own management, goals, and resources while coordinating within the SoS and adapting to meet SoS goals.

SoS Characteristics: SoS are characterized by managerial and operational independence of the constituent systems, which in many cases were developed and continue to support originally identified users of the constituent concurrently with users of the overall SoS.

INTRODUCTION: SYSTEM OF SYSTEMS

SoS TYPES



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SoS Types

Governance Relationships between SoS & CS

Directed SoS

- ❖ SoS created to fulfill specific purpose
- ❖ Dedicated SoS manager
- ❖ Subordinated constituent systems

Acknowledged SoS

- ❖ Recognized SoS objectives
- ❖ Designated SoS manager & resources
- ❖ Independent constituent systems

Collaborative SoS

- ❖ Agreed upon central purpose
- ❖ Voluntary interaction
- ❖ Independent constituent systems

Virtual SoS

- ❖ Lacks central management
- ❖ Lacks agreed upon purpose
- ❖ Large scale emergent behavior

INTRODUCTION: SYSTEM OF SYSTEMS

SoS EMERGENCE



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INTRODUCTION: SYSTEM OF SYSTEMS

INCOSE SoS PRIMER – FURTHER READING



INCOSE Systems of Systems Primer



INCOSE-TP-2018-003-01.0

| Systems tend to... | Systems tend to... |
|--|--|
| Have a clear set of stakeholders | Have a clear set of stakeholders and purposes |
| Have clear objectives and purpose | Have clear objectives and purposes |
| Have a clear management structure and clear accountabilities | Have a clear management structure and clear accountabilities |
| Have clear operational priorities, with escalation to resolve priorities | Have clear operational priorities, with escalation to resolve priorities |
| Have a single lifecycle | Have a single lifecycle |
| Have clear ownership with the ability to move resources between elements | Have clear ownership with the ability to move resources between elements |

Types of SoS

A taxonomy has evolved (proposed by Maier 1998, and extended and been widely used to categorise SoS into four different types based on noting that SoS are often complex, and may be classed differently depending on how they are viewed at, or their current operating mode at any one time.

Directed SoS are built and managed to fulfill specific purposes to ensure goals are met. Although constituent systems may accept that their normal operational mode is to be independent, they may collaborate to deliver metro services in order to participate.

Acknowledged SoS have objectives recognized by a central manager, and dedicated SoS resources. Constituent systems have objectives, funding, development and sustainment based on agreed collaboration. Air traffic control and safe airspaces globally all recognise their shared objectives and adhere to regulations and protocols.

Collaborative SoS comprise constituent systems with some central purposes, which can evolve based on shared objectives. An electrical grid is an example. Autonomous collaboration means electricity to consumers. Unlike an acknowledged SoS, constituent systems adhere to standards and protocols, but do not have a central authority or working practices.

Virtual SoS have no central authority, nor an explicit central purpose. SoS can exhibit large-scale emergent behavior, which is not designed for. The Internet is an example. The Internet Engine standards and protocols. Independent service providers. No management or governance is either required or provided. There is no central purpose for all parties.

INCOSE Systems of Systems Primer

SoS Authority

How do we handle collaboration and agreement when there is no overall director? Effective patterns for collaboration are needed, but are often difficult to recognise or establish. The defense sector tackles this with a focus on finding ways to balance the values & needs of constituent systems with those of the SoS. Other application domains tackle this through incentivizing constituent systems, creating an environment where they can meet their own goals whilst collaborating to support SoS goals.

SoS Principles

What are the key SoS thinking principles? Surveys of SoS practitioners have identified areas where basic principles are lacking. These include: lack of formalized SoS processes; lack of SoS success stories; and information about workflows. Much more research on SoS working contexts is needed to develop a body of recognized best practice.



Leadership

What are the roles & characteristics of effective SoS leaders? The increasingly complex collection of independent systems in an SoS typically straddles disciplines, application domains, organizations and even national boundaries, and each constituent system is capable of following their own interests and agenda. As a result, effective means of leadership are important. Structure and directorship usually found in SE projects is often absent for SoS, and other methods are needed to ensure coherence and direction.

Constituent Systems

How to integrate constituent systems? Each constituent system has its own agenda and goals, and can act autonomously. Some may be legacy systems not designed for SoS contexts, not easily adapted, resulting in interoperability challenges. Operating an SoS means finding means to coordinate, incentivize and manage multiple separate constituent systems, with separate working cultures, schedules, processes and working practices, as well as coping with technical challenges such as communications and data exchange. Mismatched assumptions and expectations are a real risk.



INCOSE Systems of Systems Primer

INCOSE-TP-2018-003-01.0

SoS Pain Points

What does a systems engineer need to know about SoS?

Many existing systems do play a role in an SoS, whether they are explicitly aware of this or not. Working in an SoS context brings a number of challenges, and it can help to be aware of these. Surveys conducted by the INCOSE SoS Working Group have identified "pain points" which are particularly associated with SoS by practising systems engineers (summarized by Judith Dahmann 2014).

[1] COMPASS project: <http://thecompassclub.org/>
 [2] DANSE project: <http://danse-ip.eu/home/>
 [3] INTO-CPS project: <http://projects.aunz.net/>

Autonomy, Interdependence & Emergence

How can system engineering address the complexities of SoS inter-dependencies and emergent behaviors? The unanticipated evolution of constituent systems can produce emergent effects at the SoS level, often not predictable until the SoS is simulated or tested. Complex dependencies are common between constituent systems at different stages of maturity, often not well understood or managed. The scale, diversity & independence in an SoS makes it difficult to produce models that can accurately predict SoS-level performance. Recent work has begun to address SoS and emergence, SoS uncertainty & complexity, and modelling & simulation – see, for example, [1, 2, 3].

INCOSE-TP-2018-003-01.0

CALIFORNIA HIGH-SPEED RAIL SYSTEM (CHSRS)

BRIEF INTRODUCTION



WHO WE ARE WHAT WE DO INSIGHTS CAREERS

Investors ▾ News ▾ Contact us ▾ 🔍 GLOBAL - ENGLISH ▾ FRANÇAIS

What We Do / Projects / CALIFORNIA HIGH SPEED RAIL



Source: <https://www.wsp.com/en-GL/projects/california-high-speed-rail>

CALIFORNIA HIGH SPEED RAIL

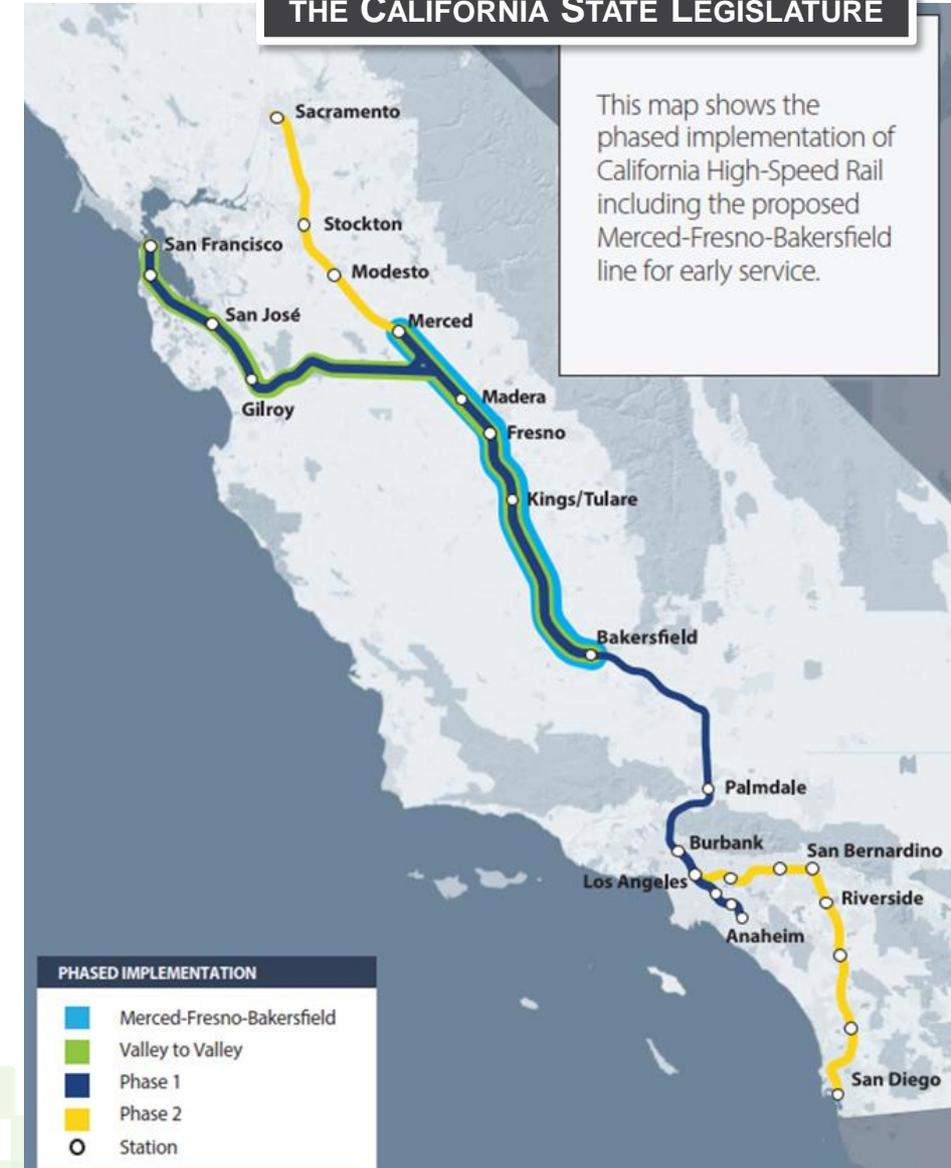
CALIFORNIA HIGH-SPEED RAIL SYSTEM (CHSRS)



KEY HIGHLIGHTS

- One of the largest and most ambitious public transportation programs in U.S. history
- Will allow passengers to travel from Los Angeles to San Francisco at speeds of up to 220 miles (354 kilometers) per hour
- Trip in just 2 hours and 40 minutes, compared to almost 6 hours by automobile
- Connects California's megaregions, contributes to economic development and a cleaner environment, creates jobs and preserves agricultural and protected lands
- Using federal and state funds, including Cap and Trade, Authority plans to begin high-speed operations to begin in the Central Valley by 2028
- Will eventually connect San Francisco to Los Angeles in under three hours at speeds of 350km/h (220mph) by 2033, extending to Sacramento and San Diego, totaling 800 miles with up to 24 stations
- Improves local and regional rail lines

2019 PROJECT UPDATE REPORT TO THE CALIFORNIA STATE LEGISLATURE



CALIFORNIA HIGH-SPEED RAIL SYSTEM (CHSRS)



PROCUREMENT STRATEGY / CONTRACT PACKAGING

EXHIBIT 2.2 PROCUREMENT STRATEGY

2018 BUSINESS PLAN & 2019 PROJECT
UPDATE REPORT TO THE CALIFORNIA
STATE LEGISLATURE

OPERATOR



ROLLING STOCK



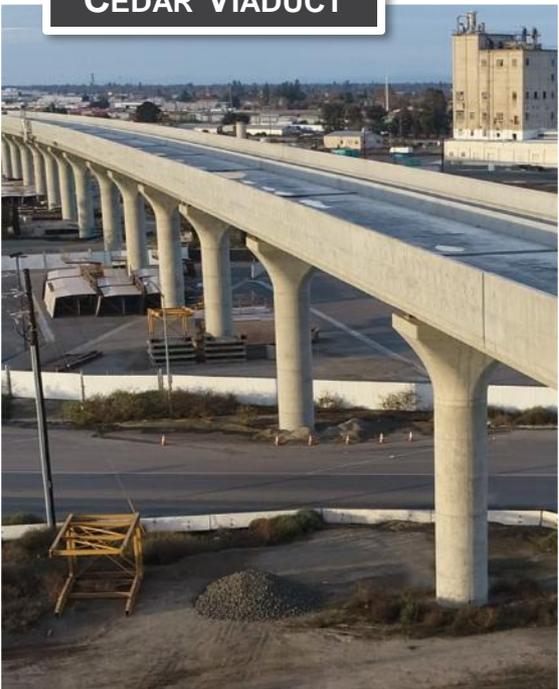
RAIL INFRASTRUCTURE



CIVIL WORKS



CEDAR VIADUCT



AVENUE 12



CHSRS AS A SYSTEM OF SYSTEMS

CHSRS AS A CONSTITUENT SYSTEM WITHIN A LARGER SoS



Interfacing Systems & Organization



Interfacing Systems & Organization



Adjacent Railroads



Power Utilities



River Crossing



Adjacent Roadways



Seismic Detection

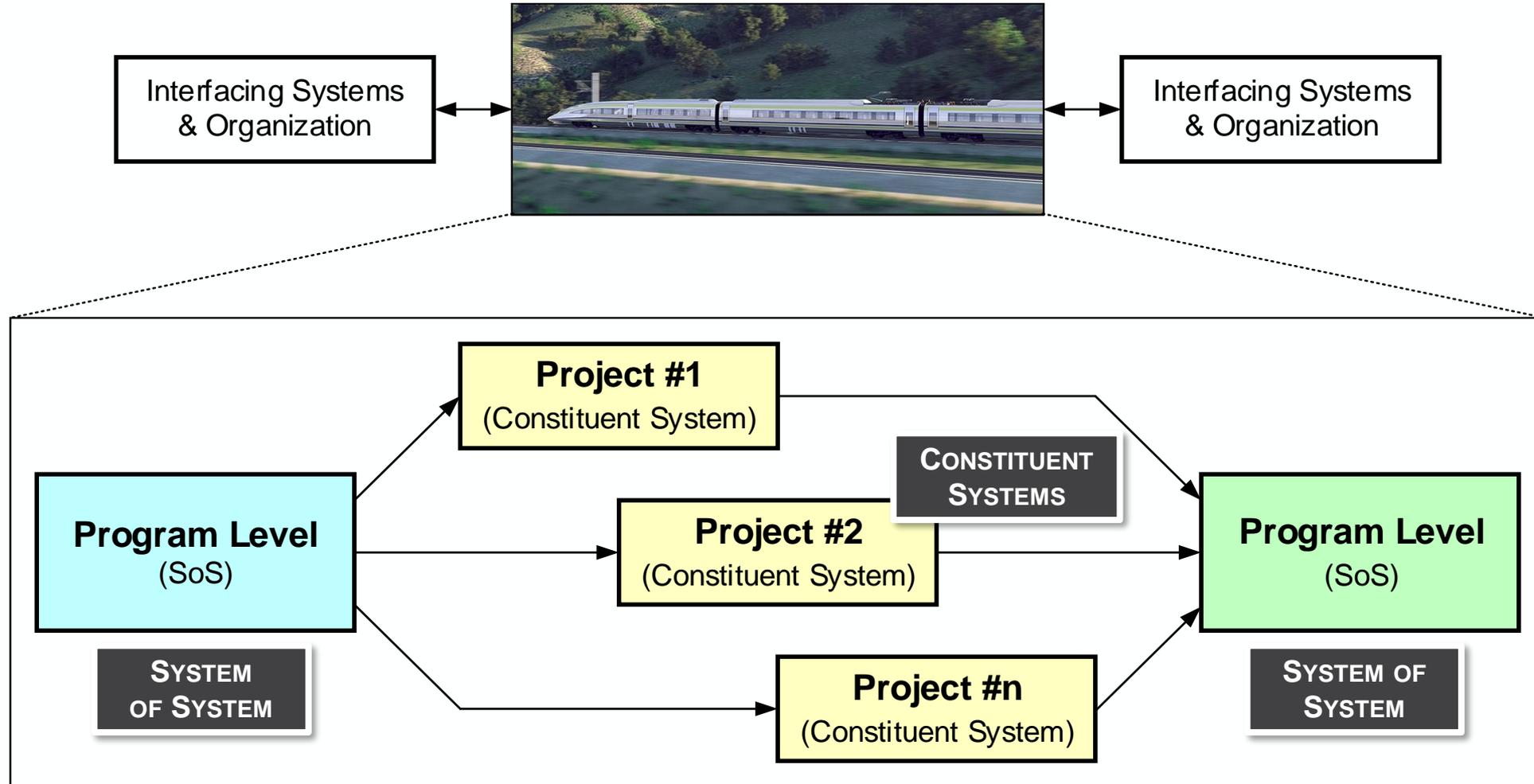


Shared Corridors

Source:
<https://www.youtube.com/watch?v=AKsjqu3l0xA>

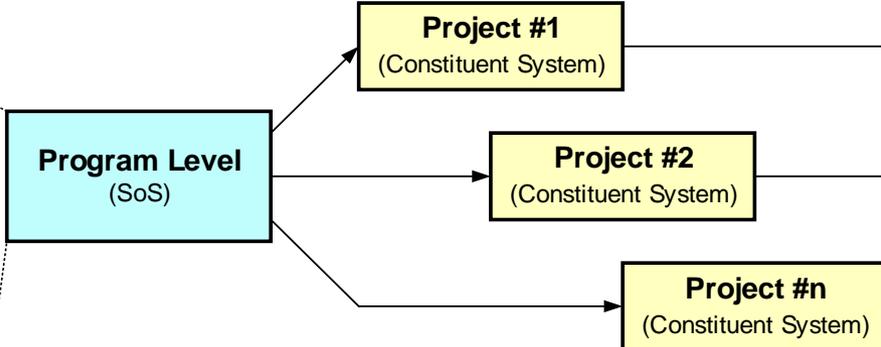
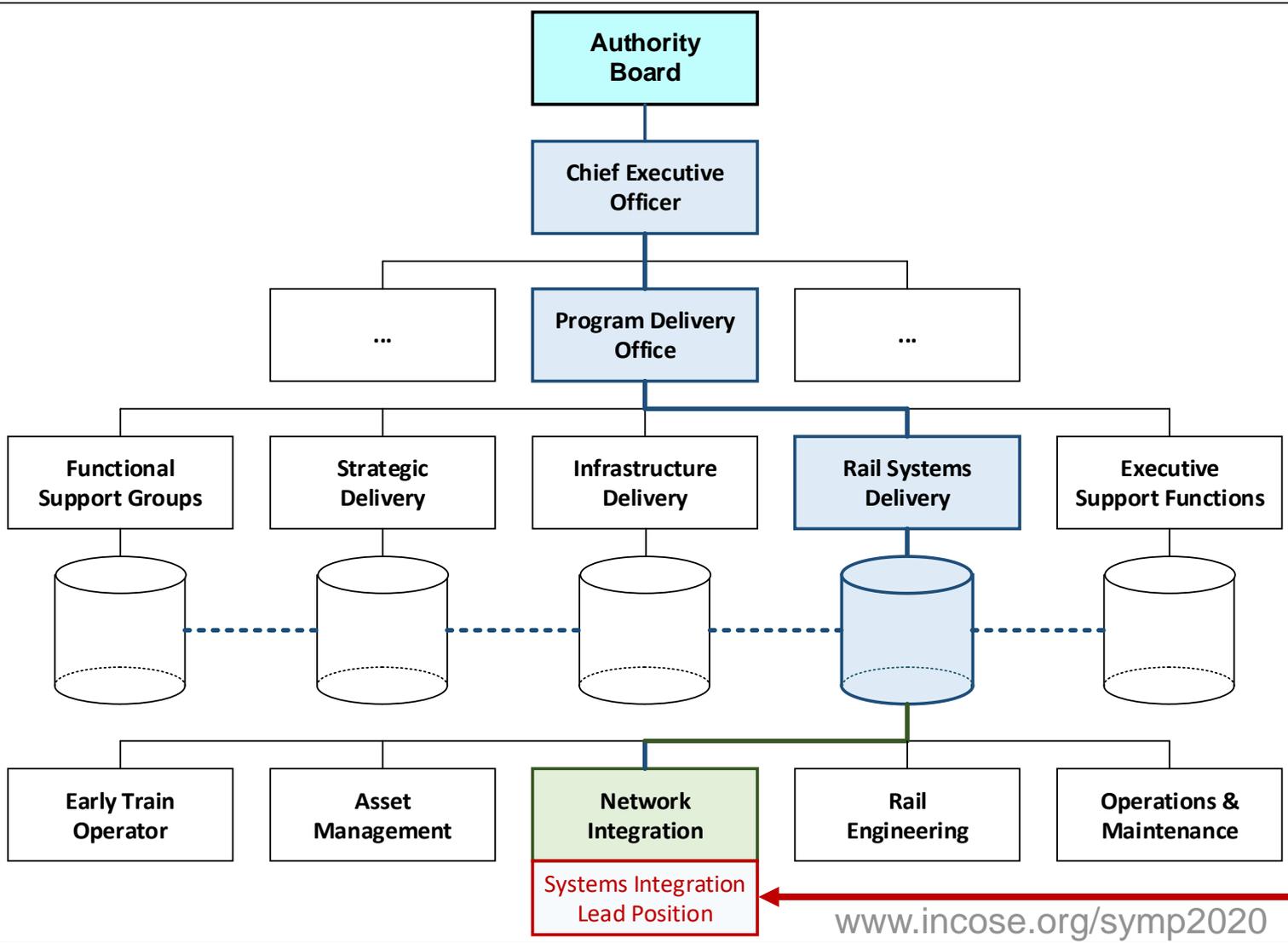
CHSRS AS A SYSTEM OF SYSTEMS

CHSRS AS A PROGRAM (SoS) OF PROJECTS (CONSTITUENT SYSTEMS)

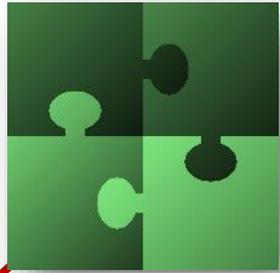


CHSRS AS A SYSTEM OF SYSTEMS

CHSR PROGRAM ORGANIZATION AS AN ORGANIZATIONAL SoS



SYSTEM INTEGRATION AS A "CONSTITUENT SYSTEM" OF THE ORGANIZATIONAL SoS





❖ Introduction

- System of Systems (SoS)
- California High-Speed Rail System (CHSRS) Program
- CHSRS as a System of Systems

❖ SoSE Challenges Faced

- Traditional Industry Approach to Systems Integration
- SoS Engineering Challenges

❖ SoSE Activities Performed

- International Best Practice Analysis of HSR System Integration
- SoS Integration Strategy
- Step by Step Process Description

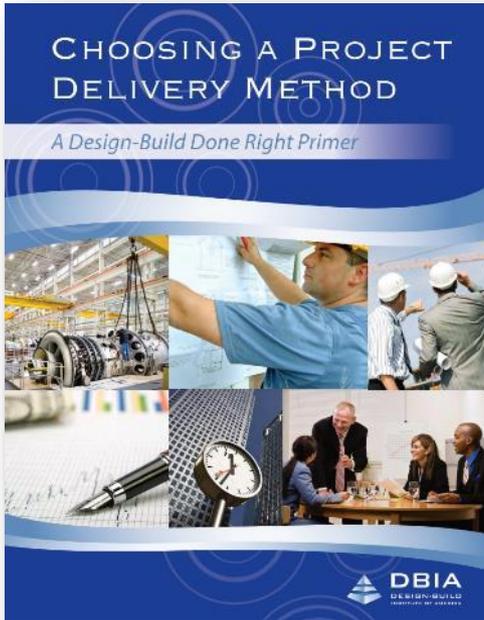
❖ Summary, Achieved Outcomes & Conclusion

TRADITIONAL INDUSTRY APPROACH TO SYSTEMS INTEGRATION

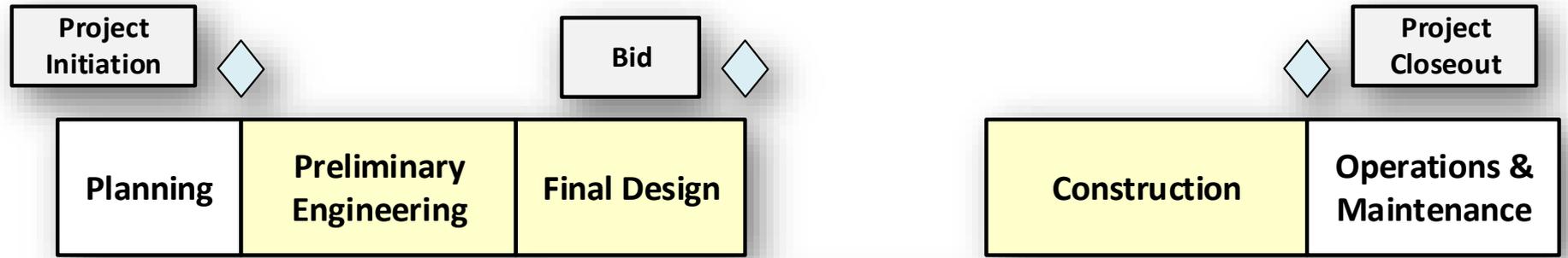


PROJECT DELIVERY METHODS

**TRADITIONAL METHOD
(DESIGN / BID / BUILD)**



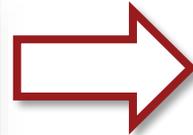
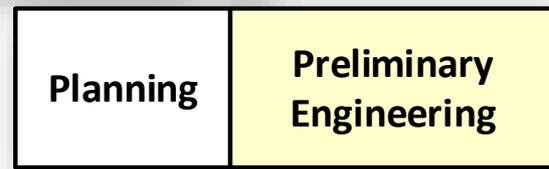
**TODAY'S PREFERRED METHOD
(DESIGN / BUILD)**



**OWNER ORGANIZATION
(FUNCTIONAL STRUCTURE)**



CONSTRUCTION FIRM



**(INTEGRATION) RISK TRANSFER
TO DESIGN & CONSTRUCTION FIRM**

TRADITIONAL INDUSTRY APPROACH TO SYSTEMS INTEGRATION

CONSEQUENCES OF DESIGN / BUILD (DB)



❖ Reluctance to be Specific:

- Interference with design / construction firm's business, possibility of "re-owning" the risk
- Detailed directions may result in additional work order claims

❖ Unknown System Integration Scope:

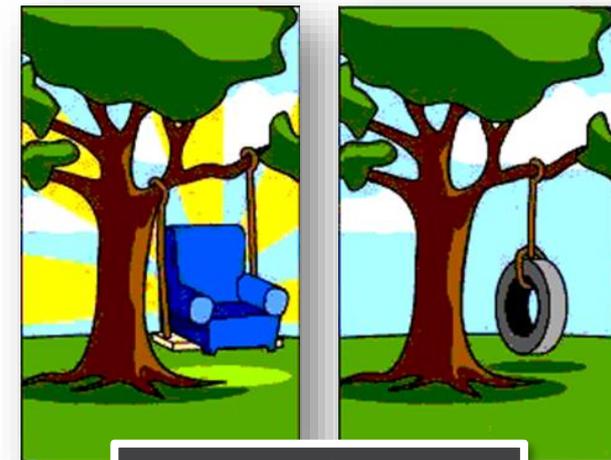
- Design / construction firm responsible for final design & construction
- Limited knowledge of final solution at time of bid (i.e. system architecture & interfaces)
- Resulting in hesitance to provide detailed interfaces lists & descriptions (see above)
- Risk of omitted interfaces may be subject to additional work order claims

❖ Innovative Design & Construction:

- Saving time and money by encouraging collaboration and innovation
- May result in (emerging) unanticipated and/or unintended design solutions

❖ Design / Build Impact to Systems Integration:

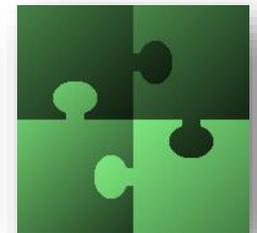
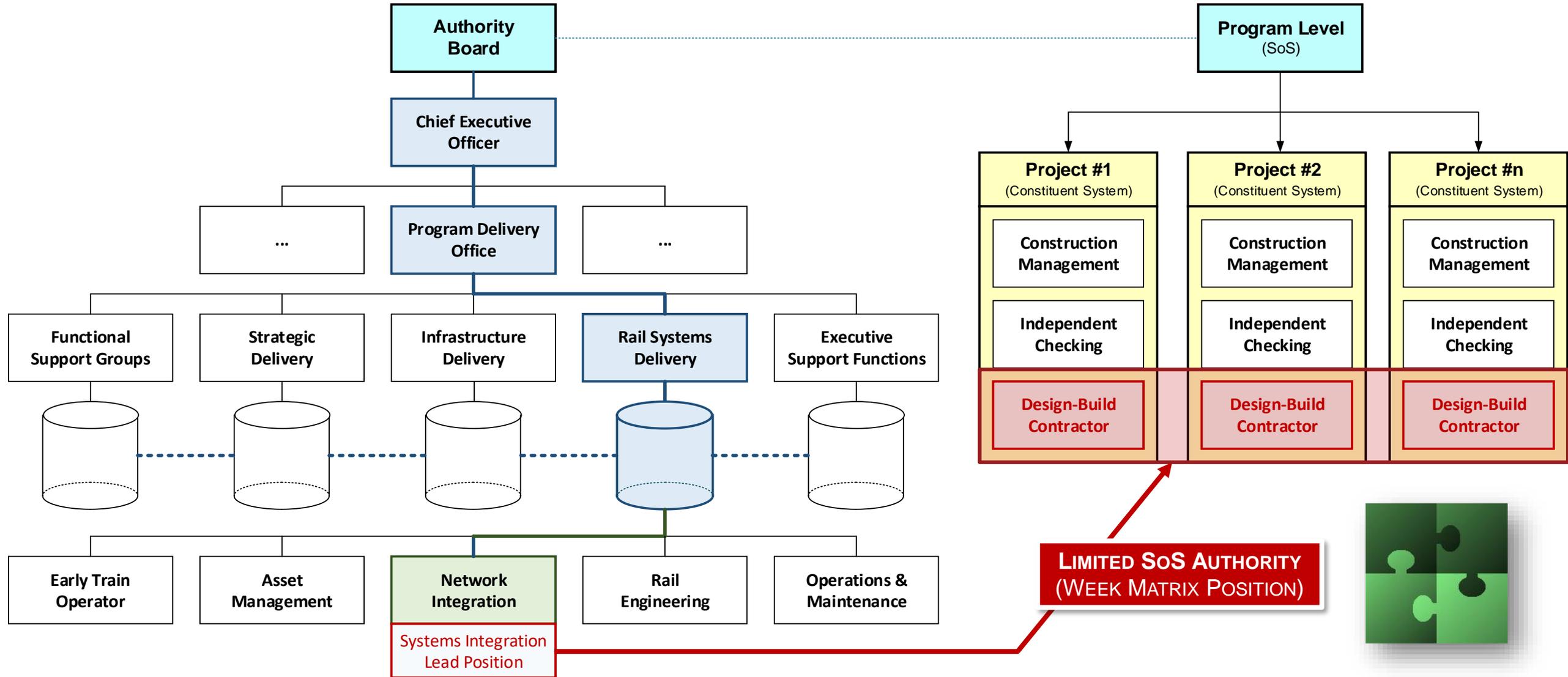
- Systems integration becomes "coordination" responsibility (scope)
- Risk avoidance approach (hands-off, "leave it to the contractor")
- Often reactive, late interface identification during final design & construction



EMERGING SOLUTIONS

SoSE CHALLENGES FACED

SoS AUTHORITY



SoSE CHALLENGES FACED

SoS ARCHITECTURE (CONTRACT PACKAGING) & LEADERSHIP



Design-Build Construction Packages

The high-speed rail system is being built through a series of design-build contracts. Work within a design-build contract continues until a project section has been environmentally cleared. Currently, the Authority has identified four design-build contracts in the Central Valley. Construction updates and road closure alerts are posted on BuildHSR.com.

CIVIL WORKS



Contracts Out for Bid

Design-Build Construction Packages

Track & Systems

Construction Package 1 (HSR 13-06)

STARTED IN 2013

Construction Package 1 (CP 1) is the first significant construction contract executed on the Initial Operating Section of the high-speed rail program. The CP1 construction area is a 32-mile stretch between Avenue 19 in Madera County to East American Avenue in Fresno County. It includes 12 grade separations, 2 viaducts, 1 tunnel and a major river crossing over the San Joaquin River.

Construction Package 2-3 (HSR 13-57)

Construction Package 2-3 (CP 2-3) is the second significant construction contract executed on the Initial Operating Section of the high-speed rail program. The CP 2-3 construction area extends approximately 60 miles from the terminus of Construction Package 1 at East American Avenue in Fresno to one mile north of the Tulare-Kern County line. CP 2-3 will include approximately 36 grade separations in the counties of Fresno, Tulare and Kings, including viaducts, underpasses and overpasses.

Construction Package 4 (HSR 14-32)

Construction Package 4 (CP 4) is the third significant construction contract executed on the Initial Operating Section of the high-speed rail program. The CP 4 construction area is a 22-mile stretch bounded by a point approximately one mile north of the Tulare/Kern County Line at the terminus of Construction Package 2-3 and Poplar Avenue to the south. CP 4 will include construction of at-grade, retained fill and aerial sections of the high-speed rail alignment and the relocation of four miles of existing Burlington Northern Santa Fe (BNSF) tracks.



RESOURCES

- Cal eProcure

SoSE CHALLENGES FACED

SoS ARCHITECTURE & LEADERSHIP (CONT'D)



Track & Systems

The Track and Systems procurement is proposed to be a design-build-maintain contract with a scope of work that includes design and construction of trackwork, railway systems, and electrification, as well as testing and commissioning. The Track and Systems contract, as proposed, will also include a 30-year term of maintenance for both the underlying civil works and the Track and Systems work would be issued through multiple Notices to Proceed (NTP) for the Central Valley.

TRACK & SYSTEMS

Contracts Out for Bid

Design-Build Construction Packages

Track & Systems

The anticipated schedule for this procurement is as follows:

- RFQ Release: July 17, 2019
- SOQ Due Date: November 4, 2019
- RFP Release: December 19, 2019
- **Proposal Due Date: September 15, 2020**

TO BE STARTED

RFP for Track and Systems

The Authority released the Request for Proposals (RFP HSR19-13) to [three shortlisted teams](#) on December 19, 2019. California High-Speed Rail Constructors notified the Authority on February 27, 2020 that their team has withdrawn from the Track and Systems RFP procurement process.

Please find below the small-business and non-small business contact information:



Source: https://hsr.ca.gov/business/contractors/contracts_out.aspx

SoSE CHALLENGES FACED

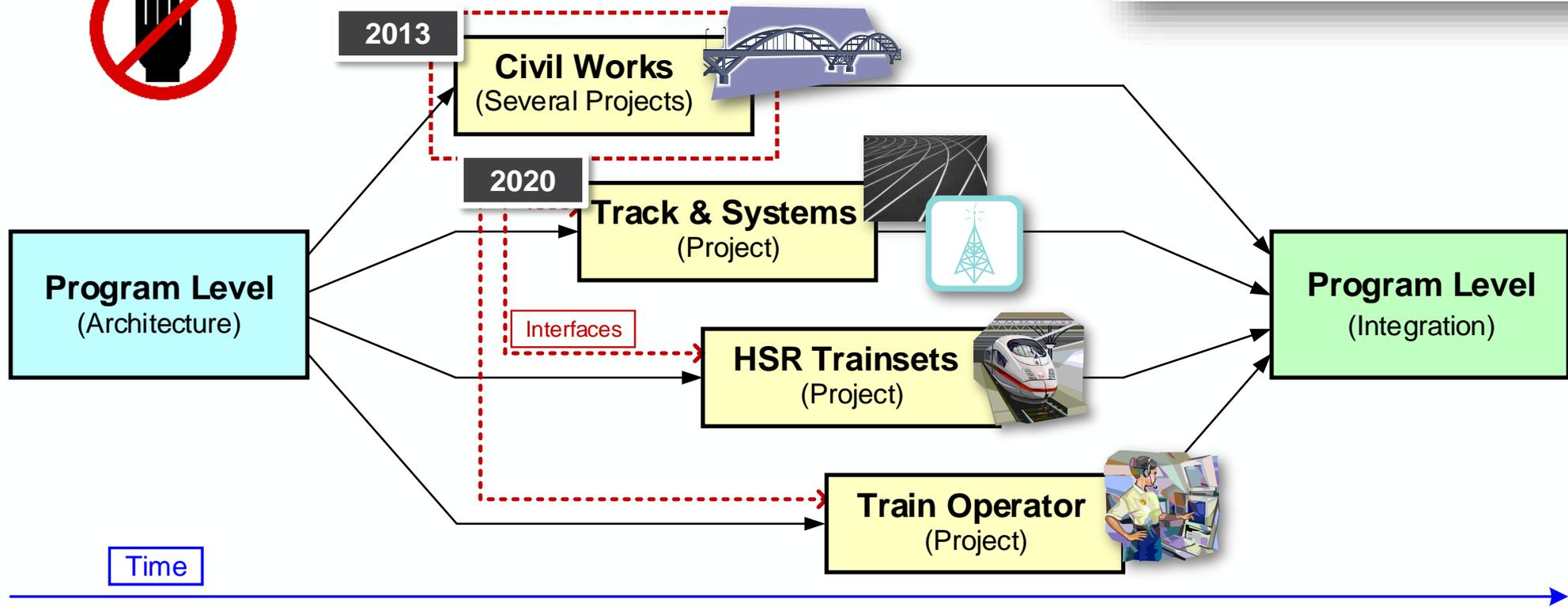
SoS ARCHITECTURE & LEADERSHIP (CONT'D)



- TRAIN OPERATOR
- HSR TRAINSETS
- TRACK & SYSTEMS
- CIVIL WORKS

SoS LEADERSHIP
("LEAVE IT TO THE CONTRACTOR")

SoS ARCHITECTURE
(CONTRACTS & INTERFACES)



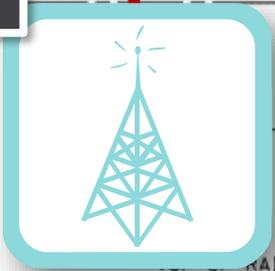
SoS COLLABORATION & INTEGRATION (EARLY INTERFACE NEEDS)



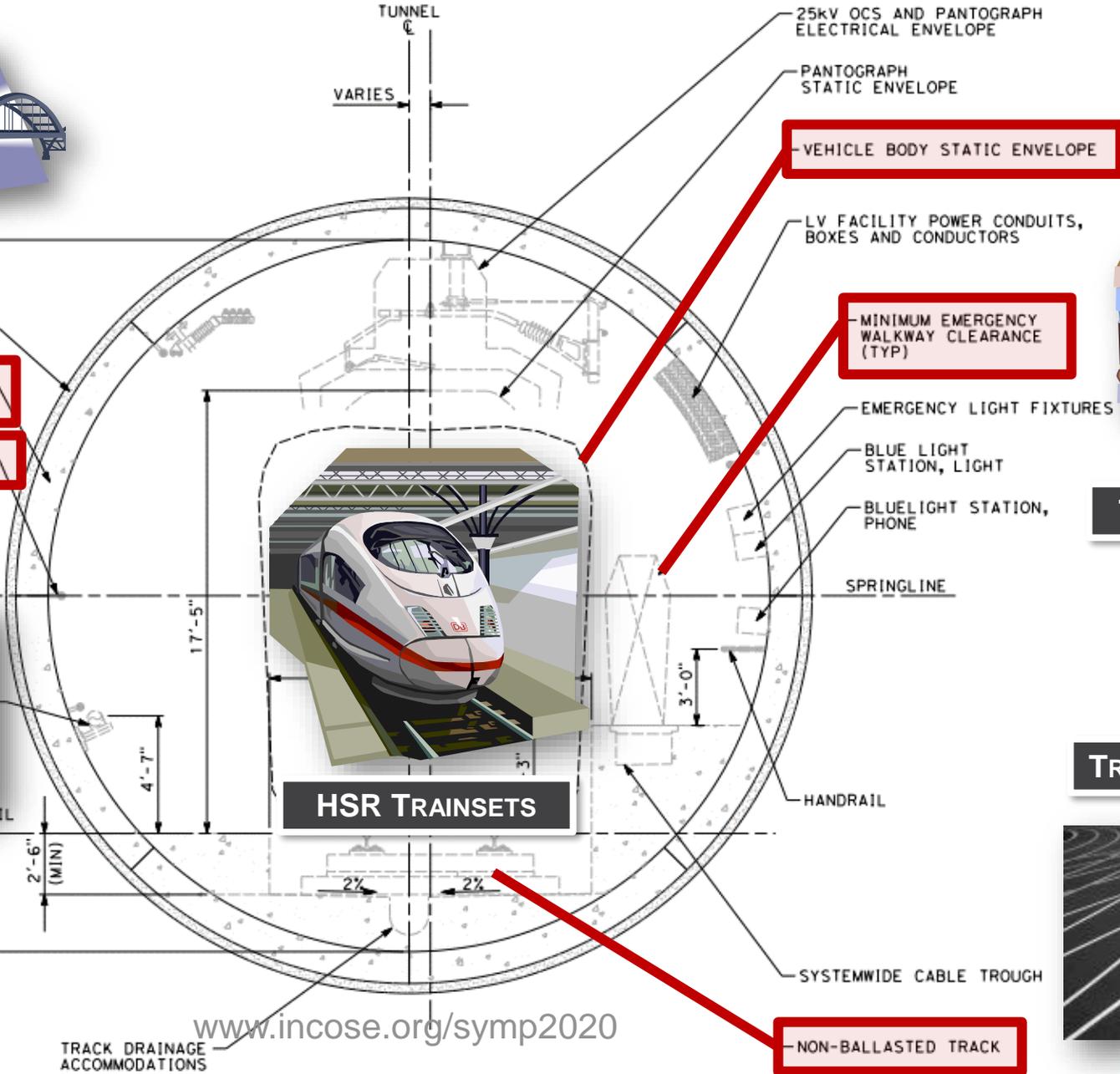
CIVIL WORKS



TRACK & SYSTEMS



INTERFACE REQUIREMENTS NEEDED FROM CONTRACTS NOT ISSUED YET



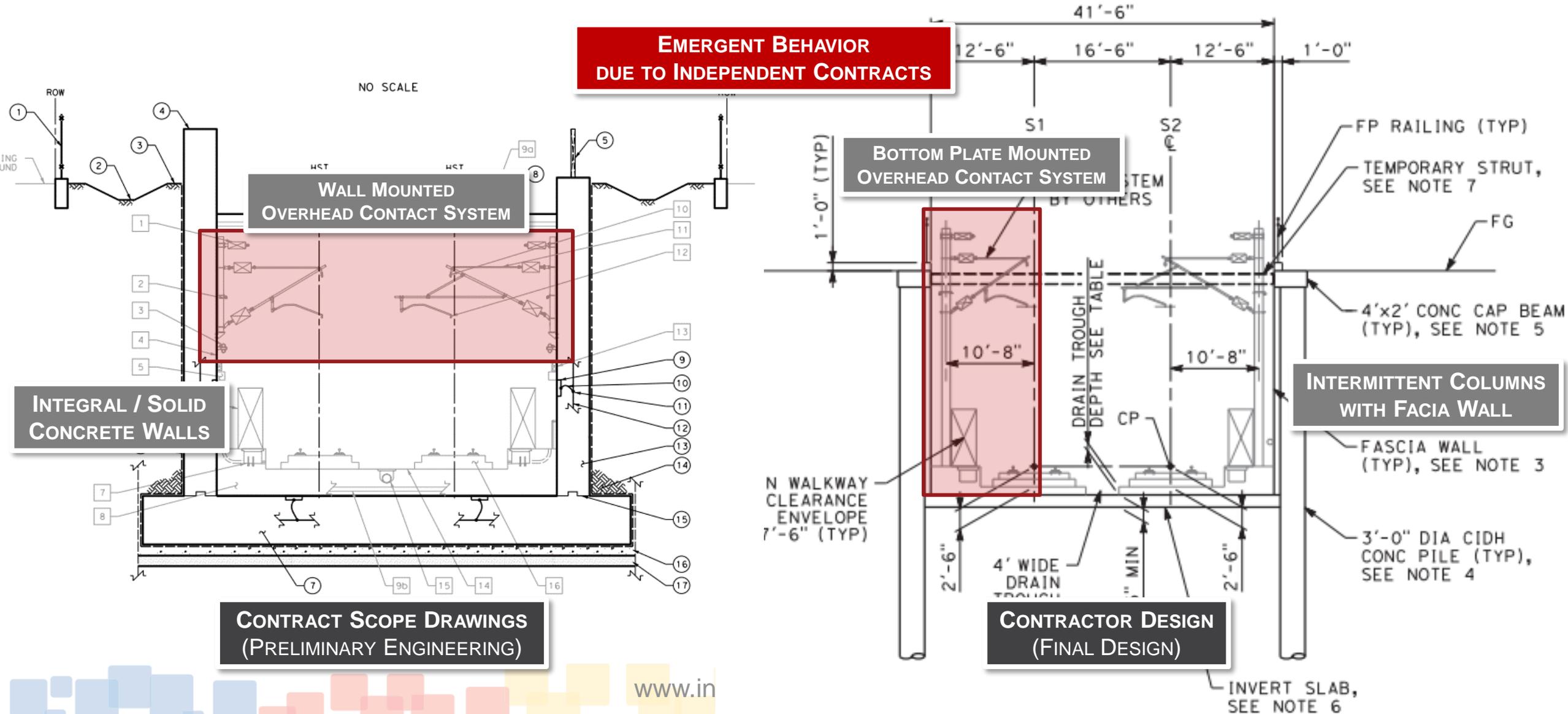
TRAIN OPERATOR

TRACK & SYSTEMS



SoSE CHALLENGES FACED

SoS AUTONOMOUS CONSTITUENT SYSTEMS & EMERGENCE





❖ Introduction

- System of Systems (SoS)
- California High-Speed Rail System (CHSRS) Program
- CHSRS as a System of Systems

❖ SoSE Challenges Faced

- Traditional Industry Approach to Systems Integration
- SoS Engineering Challenges

❖ SoSE Activities Performed

- International Best Practice Analysis of HSR System Integration
- SoS Integration Strategy
- Step by Step Process Description

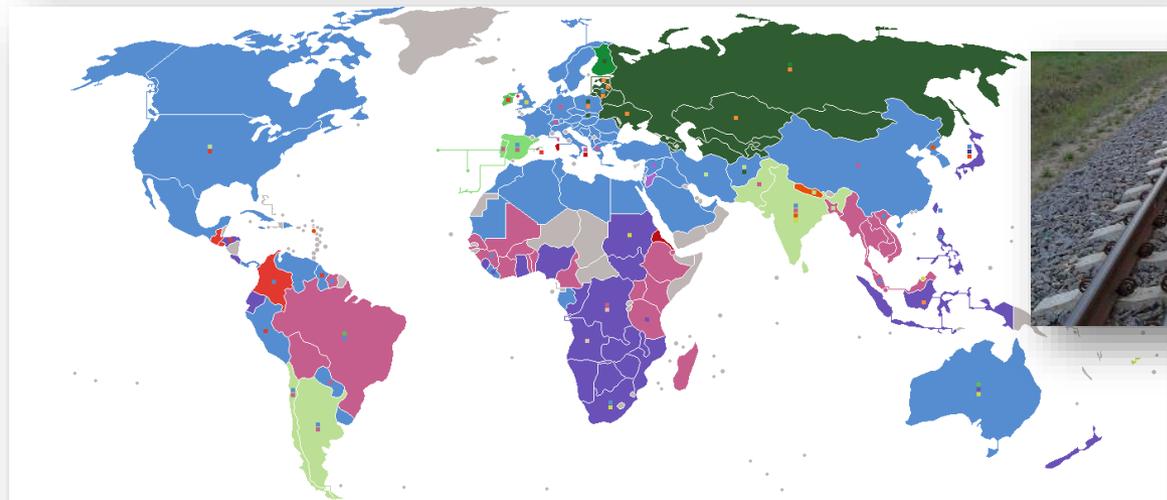
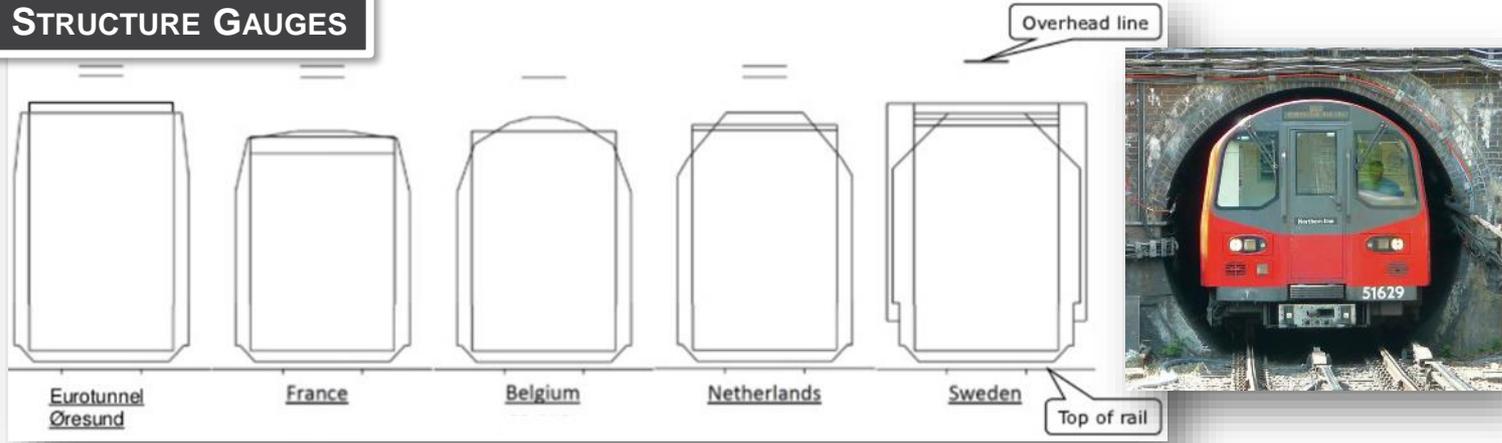
❖ Summary, Achieved Outcomes & Conclusion

INTERNATIONAL BEST PRACTICE ANALYSIS

TRANS EUROPEAN HIGH-SPEED RAIL SYSTEM – INTEGRATION CHALLENGES

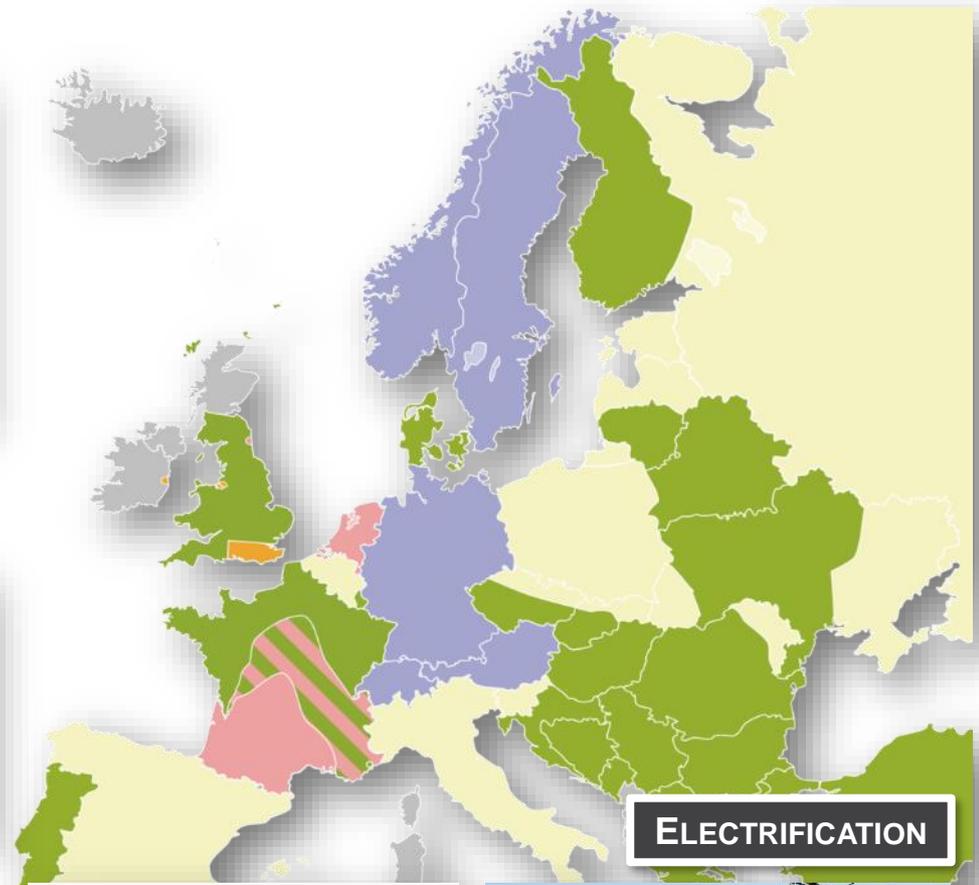


STRUCTURE GAUGES



| | | | | | | | | | | | | | | | | |
|----|-------|---------|-------|-------|----------|---------|-------|-------|---------|---------|---------|-----|-------|---------|-----|----------|
| mm | 1676 | 1668 | 1600 | 1524 | 1520 | 1435 | 1372 | 1067 | 1050 | 1000 | 950 | 914 | 762 | 750 | 610 | 600 |
| | 5' 6" | 5' 5.5" | 5' 3" | 5' 0" | 4' 11.8" | 4' 8.5" | 4' 6" | 3' 6" | 3' 5.3" | 3' 3.4" | 3' 1.4" | 3' | 2' 6" | 2' 5.5" | 2' | 1' 11.6" |

TRACK GAUGES



ELECTRIFICATION

- Electrification systems:
- 750 V DC
 - 1,5 kV DC
 - 3 kV DC
 - 15 kV, 16.7 Hz AC
 - 25 kV, 50 Hz AC
 - Non-electrified



INTERNATIONAL BEST PRACTICE ANALYSIS

TECHNICAL SPECIFICATIONS FOR INTEROPERABILITY (TSI)



- Legend :**
- 310 - 320 km/h 190 - 200 mph
 - 270 - 300 km/h 165 - 185 mph
 - 240 - 260 km/h 150 - 160 mph
 - 200 - 230 km/h 125 - 145 mph
 - < 200 km/h < 125 mph
 - - - Under construction/ upgrading



INTERNATIONAL BEST PRACTICE ANALYSIS



TSIs – SUBSYSTEMS & INTERFACES



8 Subsystems, incl. 4 Structural Subsystems:

1. Infrastructure
2. Energy
3. Control-Command & Signalling
4. Rolling Stock

4.3 Functional and technical specification of the interfaces

From the standpoint of technical compatibility, the interfaces of the infrastructure domain with the other subsystems are the following:

4.3.1 Interfaces with the rolling stock subsystem

INTERFACES BETWEEN INFRASTRUCTURE & ROLLING STOCK

| Interface | Reference High-Speed Infrastructure TSI | Reference High-speed Rolling Stock TSI |
|---|--|---|
| <p>Structure gauge Infrastructure gauge</p> <p>SPECIFIC INTERFACES</p> | 4.2.3 minimum infrastructure gauge | 4.2.3.1 kinematic gauge 4.2.3.3. Rolling stock parameters, which influence ground based train monitoring systems |
| gradients | 4.2.5 maximum rising and falling gradients | 4.2.3.6 maximum gradients 4.2.4.7 Brake force on st |
| Minimum radius | 4.2.8 minimum radius 4.2.9 equivalent conicity | 4.2.3.7 Minimum radius |
| Equivalent conicity | 4.2.9 equivalent conicity 4.2.11 rail inclination 5.3.1.1 railhead profile | 4.2.3.4 Rolling stock dynamic behaviour; 4.2.3.4.7 design values for wheel profiles |

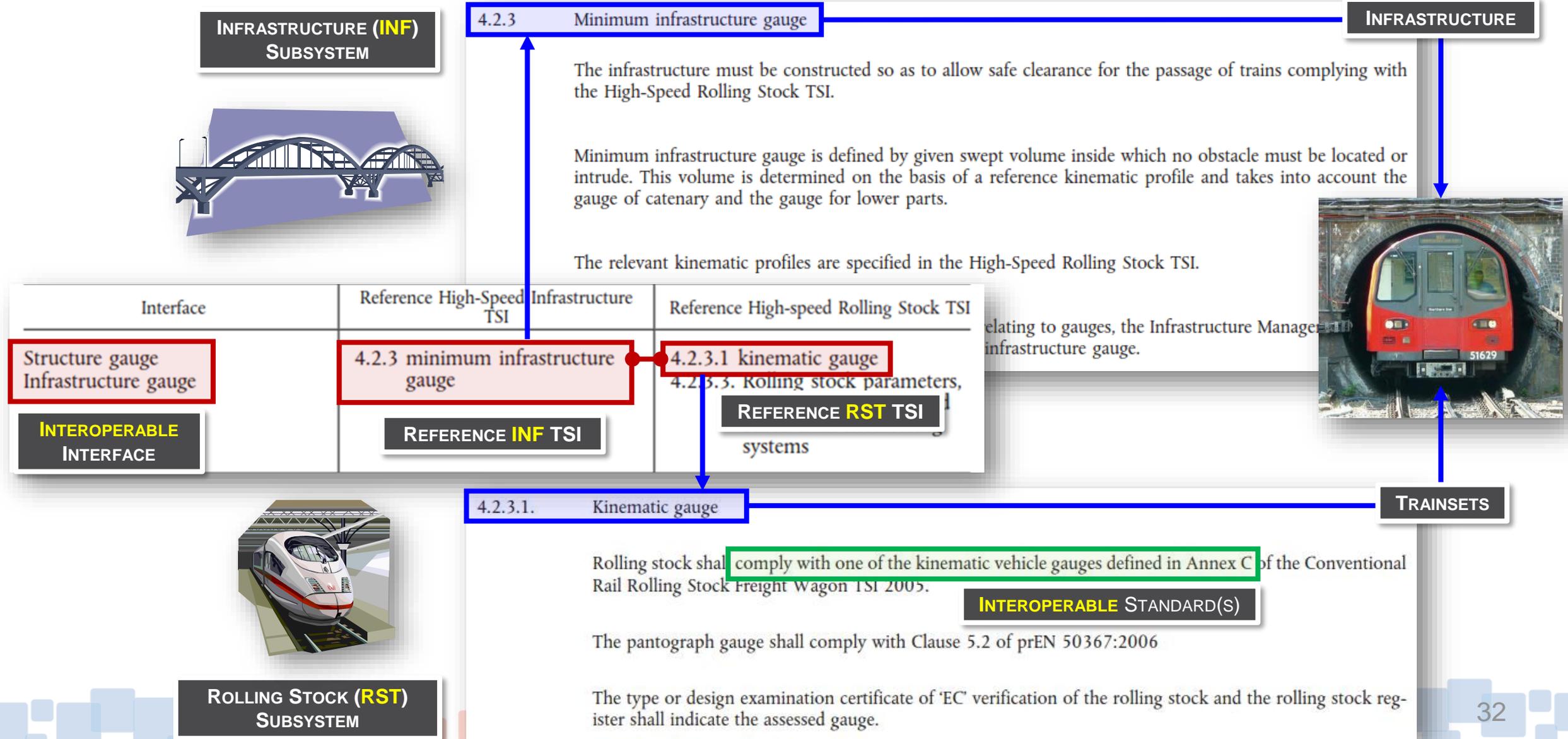
INFRASTRUCTURE SUBSYSTEM TSI



INTERNATIONAL BEST PRACTICE ANALYSIS



TSIs – INTEROPERABLE INTERFACE SPECIFICATION



SoS INTEGRATION STRATEGY



ADDRESSING THE SoSE CHALLENGES: INTEROPERABILITY APPROACH

❖ SoS Leadership & Authority

- Leadership: CHSRS system integration team
- Authority: Integration team authorized to identify & manage technical Interfaces

❖ SoS Architecture

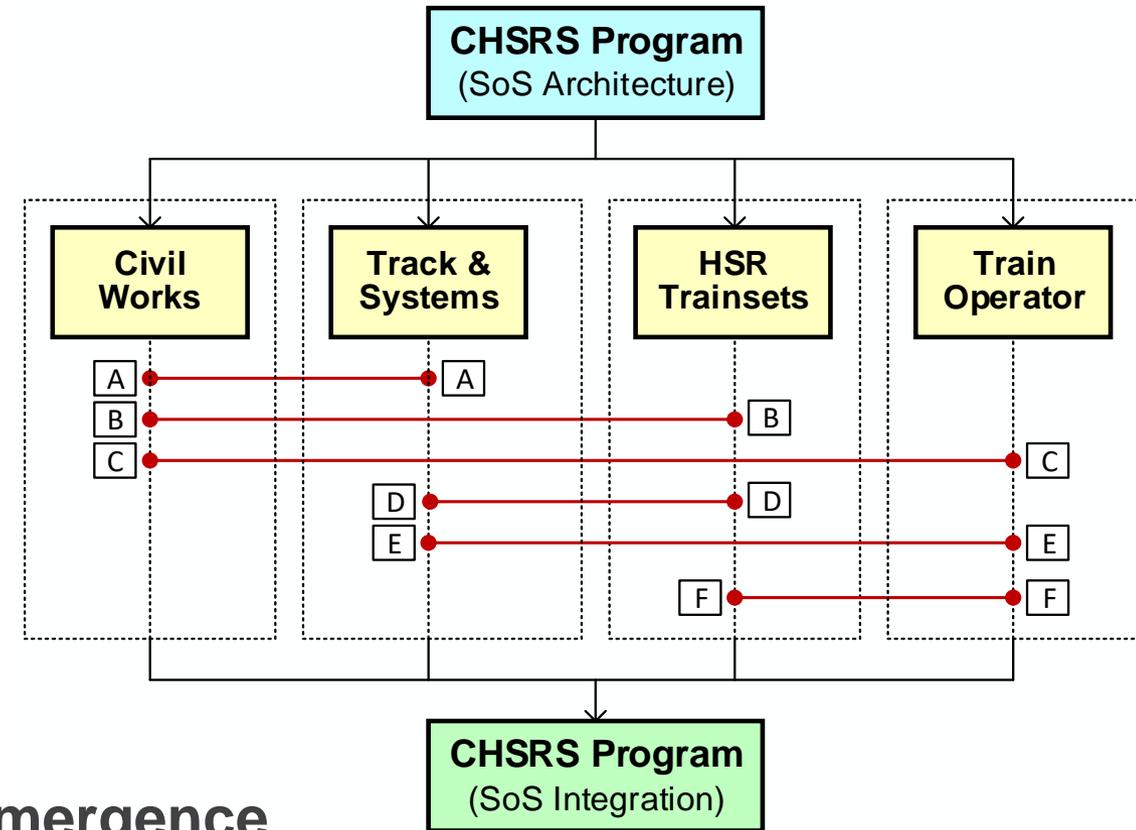
- SoS: CHSRS program
- Constituent systems: CHSRS projects

❖ SoS Collaboration & Integration

- SoS: Interface identification & specification
- Constituent systems: Interface implementation

❖ SoS Autonomous Constituent Systems & Emergence

- SoS: Defines interoperable interface standards
- Constituent systems: Allowed innovate, emergent solutions ...
- ... as long as they meet interoperable interfaces standards

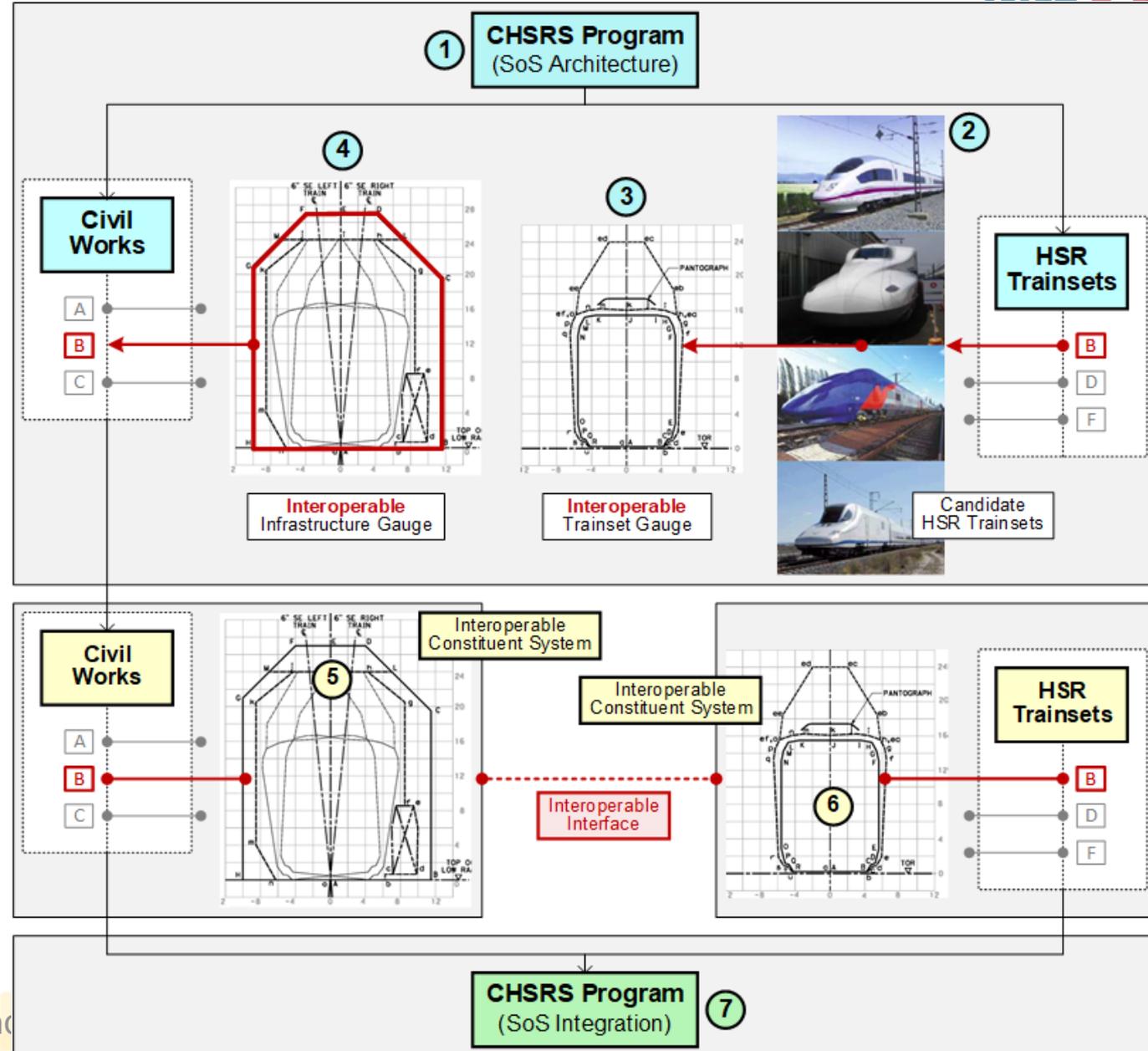


SoS INTEGRATION STRATEGY



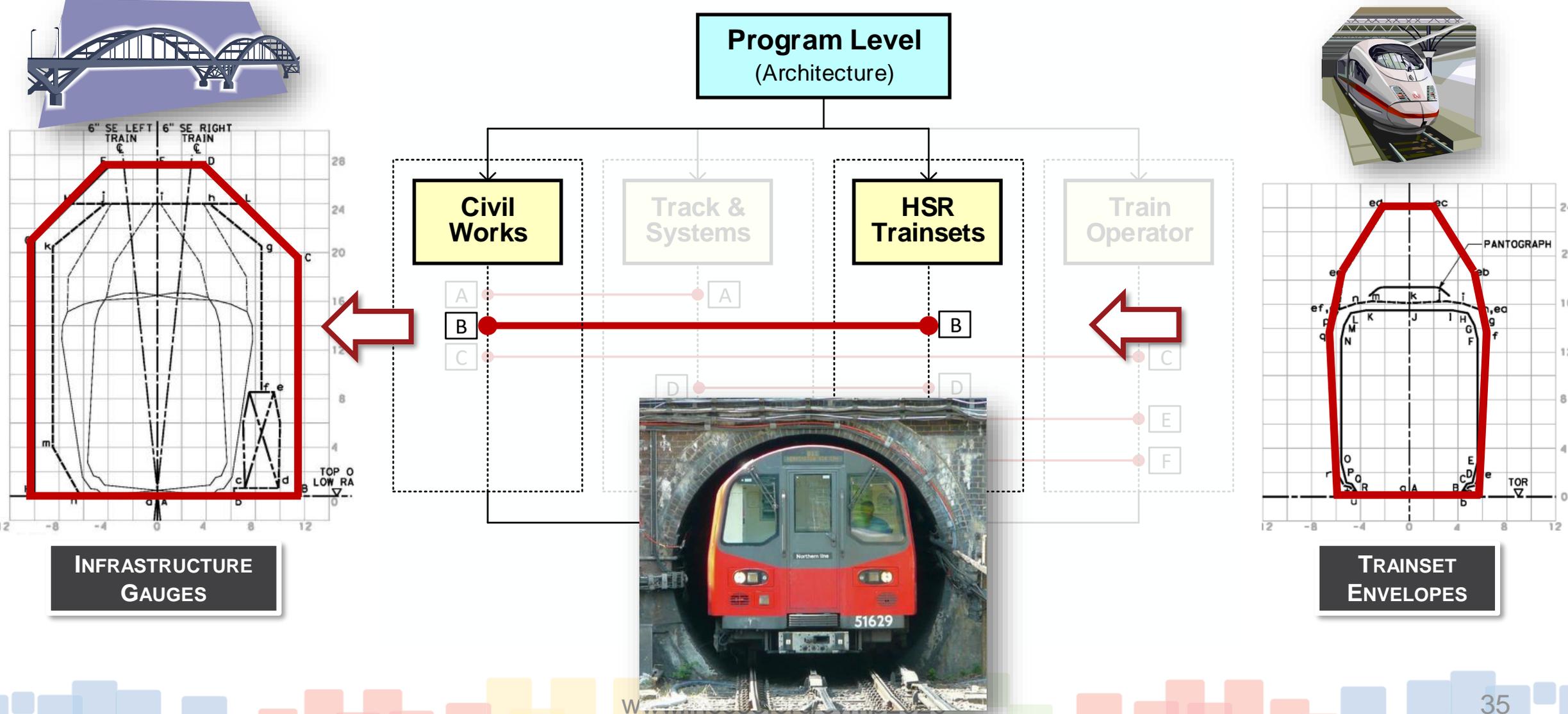
SEVEN (7) STEP PROCESS

- Step 1:** SoS architect (systems integration team) identifies key interfaces
- Step 2:** HSR trainset subject matter expert (SME) identifies candidate HSR trainsets
- Step 3:** HSR trainset SME determines interoperable interface requirements
- Step 4:** Civil works SME develops corresponding interoperable interface design
- Step 5:** Civil works contractor implements interoperable civil works contract
- Step 6:** HSR trainset contractor implements interoperable HSR trainset contract
- Step 7:** SoS system integrator (track & systems contractor) integrates, tests, and commissions (taking into service) the interoperable contracts



STEP 1: IDENTIFICATION OF KEY INTERFACES

EXAMPLE: INTERFACE BETWEEN TRAINSET ENVELOPE & INFRASTRUCTURE GAUGE



INFRASTRUCTURE GAUGES

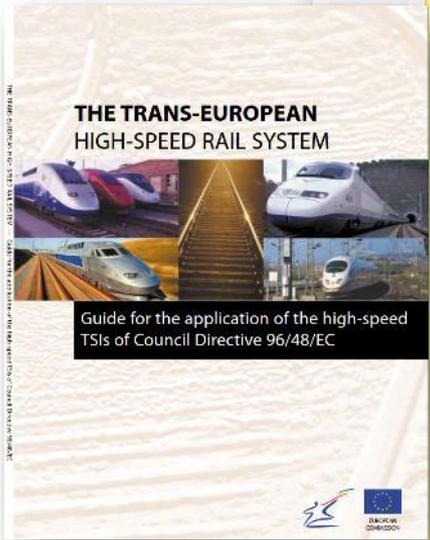
TRAINSET ENVELOPES

STEP 1: IDENTIFICATION OF KEY INTERFACES

TSI INTERFACE ANALYSIS, APPLICATION & TAILORING TO CHSRS



| _TSI-TYPE | | INTERFACES BETWEEN INFRASTRUCTURE & ROLLING STOCK | Traced To: IF-REG (LM) |
|--------------|---|--|---|
| --- | 1 TSI Interface Register | | |
| --- | 1.1 TSI Infrastructure | | |
| --- | 1.1.1 Interfaces with the Rolling Stock Subsystem | | |
| --- | 1.1.1.1 Structure Gauge and Infrastructure Gauge | | |
| INF_A RST | 1.1.1.1.1 Interface between INF Minimum Infrastructure Gauge and RST Kinematic Gauge | <p>[10 TSI-INF_A] ID: 30 4.2.3 Minimum infrastructure gauge (INF-3-03: Minimum Infrastructure Clearances)</p> <p>[10 TSI-INF_A] ID: 168 4.3.1 Interfaces with the rolling stock subsystem</p> <p>[30 TSI-RST] ID: 77 4.2.3.1 Kinematic gauge (RST-5-03.1: Kinematic gauge)</p> <p>[30 TSI-RST] ID: 398 4.3.2.3 Kinematic gauge</p> | <p>[IF-REG] ID: 481 Interface between RST HST Trainset Dynamic Envelope Requirements and GWY Infrastructure</p> <p>[IF-REG] ID: 490 Interface between RST HST Trainset Static Gauge Requirements and GWY Infrastructure</p> |
| | <p>SPECIFIC INTERFACES</p> <p>TSI INF_A: Interface: Structure gauge</p> <ul style="list-style-type: none"> • TSI INF: 4.2.3 Minimum • TSI RST: 4.2.3.1 Kinematic gauge <p>TSI RST: Clause 4.2.3.1 of this TSI specifies that the rolling stock shall comply with one of the kinematic vehicle gauges that are specified in Annex C of the Conventional Rail Rolling Stock TSI 2005. The corresponding infrastructure gauges are specified in clause 4.2.3 of the Infrastructure TSI 2006, and the infrastructure register states for each line the kinematic gauge that shall be met by the rolling stock operating on this line.</p> | | |
| | <p>1.1.1.1.2 Interface between INF Minimum Infrastructure Gauge and RST Rolling Stock Parameters which influence Ground Based Train Monitoring Systems</p> <p>TSI INF_A: Interface: Structure gauge, Infrastructure gauge</p> <ul style="list-style-type: none"> • TSI INF: 4.2.3 Minimum infrastructure gauge • TSI RST: 4.2.3.3. Rolling stock parameters, which influence monitoring systems <p>TSI RST: Clause 4.2.3.3.2 of this TSI details the specifications concerning the rolling stock related to axle bearing health monitoring by trackside hot axle boxes detectors. The minimum infrastructure gauge requirements concerning the infrastructure subsystem are set out in clause 4.2.3 of the Infrastructure TSI 2006.</p> <p>Clause 4.2.3.3.2.3 of this TSI details the specifications concerning the rolling stock related to parameters, which influence ground based train monitoring systems, and particularly electrical resistance of the wheelsets and axle bearing health monitoring. The corresponding specifications concerning the control-command and signalling subsystem are set out in clauses 4.2.10 and 4.2.11 of the Control-Command and Signalling TSI 2006 and in its Annex A Appendix 1 clauses 1 to 4.</p> | <p>[10 TSI-INF_A] ID: 30 4.2.3 Minimum infrastructure gauge (INF-3-03: Minimum Infrastructure Clearances)</p> <p>[30 TSI-RST] ID: 85 4.2.3.3.2.1 Class 1 trains (RST-5-03.3: Rolling stock parameters which influence ground based train monitoring systems)</p> <p>[30 TSI-RST] ID: 87 4.2.3.3.2.2 Class 2 trains (RST-5-03.3: Rolling stock parameters which influence ground based train monitoring systems)</p> <p>[30 TSI-RST] ID: 90 4.2.3.3.2.3.1 General (RST-5-03.3: Rolling stock parameters which</p> | <p>[IF-REG] ID: 600 Interface between SYS COM Wayside/Field Equipment Spatial Requirements and GWY Infrastructure</p> <p>[IF-REG] ID: 6341 Interface between SYS TCS Wayside/Field requirements and GWY</p> |
| | | <p>TAILORING: 49 TSI INFRASTRUCTURE INTERFACES RESULTED IN OVER 100 CHSRS GUIDEWAY (GWY) INFRASTRUCTURE INTERFACES</p> | |



TECHNICAL SPECIFICATIONS FOR INTEROPERABILITY (TSI)

STEP 1: IDENTIFICATION OF KEY INTERFACES

INTERFACE REGISTER USING N² CHART APPROACH



| ID | _TSI-TYPE | | Traced To: IF-REG (LM) |
|-----|--------------|---|---|
| 1 | --- | 1 TSI Interface Register | |
| 5 | --- | 1.1 TSI Infrastructure | |
| 2 | --- | 1.1.1 Interfaces with the Rolling Stock Subsystem | |
| 3 | --- | 1.1.1.1 Structure Gauge and Infrastructure Gauge | |
| 4 | INF_A RST | <p>1.1.1.1.1 Interface between INF Minimum Infrastructure Gauge and RST Kinematic Gauge</p> <p><u>TSI INF_A:</u> Interface: Structure gauge, Infrastructure gauge</p> <ul style="list-style-type: none"> • TSI INF: 4.2.3 Minimum infrastructure gauge • TSI RST: 4.2.3.1 Kinematic gauge <p><u>TSI RST:</u> Clause 4.2.3.1 of this TSI specifies that the rolling stock shall comply with one of the kinematic vehicle gauges that are specified in Annex C of the Conventional Rail Rolling Stock TSI 2005. The corresponding infrastructure gauges are specified in clause 4.2.3 of the Infrastructure TSI 2006, and the infrastructure register states for each line the kinematic gauge that shall be met by the rolling stock operating on this line.</p> | <p>[IF-REG] ID: 481 Interface between RST HST Trainset Dynamic Envelope Requirements and GWY Infrastructure</p> <p>[IF-REG] ID: 490 Interface between RST HST Trainset Static Gauge Requirements and GWY Infrastructure</p> |
| 13 | --- | 1.5 TSI Energy | |
| 108 | --- | 1.5.1 Interfaces with the Rolling Stock Subsystem | |
| 113 | --- | 1.5.1.1 Voltage and Frequency | |
| 130 | RST EGY | <p>1.5.1.1.1 Interface between EGY Voltage and Frequency and RST Energy Supply</p> <p><u>TSI EGY:</u> Interface: Voltage and frequency & Energy Supply</p> <ul style="list-style-type: none"> • TSI EGY: 4.2.2 • TSI RST: 4.2.8.3.1.1 <p><u>TSI RST:</u> Clause 4.2.8.3 of this TSI details the specifications concerning the rolling stock related to power supply. The corresponding specifications concerning the energy subsystem are specified in clauses 4.2.2, ... of the Energy TSI 2006. The specifications concerning the energy subsystem, related to the position of ...</p> | <p>[IF-REG] ID: 6408 Interface between TRK TP Voltage and Frequency and RST HST Trainset</p> |
| 14 | --- | 1.6 TSI Operations and Traffic Management | |
| 244 | --- | 1.6.3 Interfaces with the Rolling Stock TSI | |
| 248 | --- | 1.6.3.1 Braking | |
| 272 | RST OPE | <p>1.6.3.1.1 Interface between OPE Brake Performance and RST Brake System Requirements</p> <p><u>TSI OPE:</u> Interfaces exists between Subsection 4.2.2.5.1, 4.2.2.6.1 and 4.2.2.6.2 of this OPE TSI, and subsection 4.2.4.1 and 4.2.4.3 of the HS RST TSI.</p> <p><u>TSI RST:</u></p> | <p>[IF-REG] ID: 6672 Interface between O&M OPS Brake Performance Requirements and RST HST Trainset Brake System Performance</p> |

**INTERFACES BETWEEN
INFRASTRUCTURE & ROLLING STOCK**

**INTERFACES BETWEEN
ENERGY & ROLLING STOCK**

**INTERFACES BETWEEN
OPERATIONS & ROLLING STOCK**

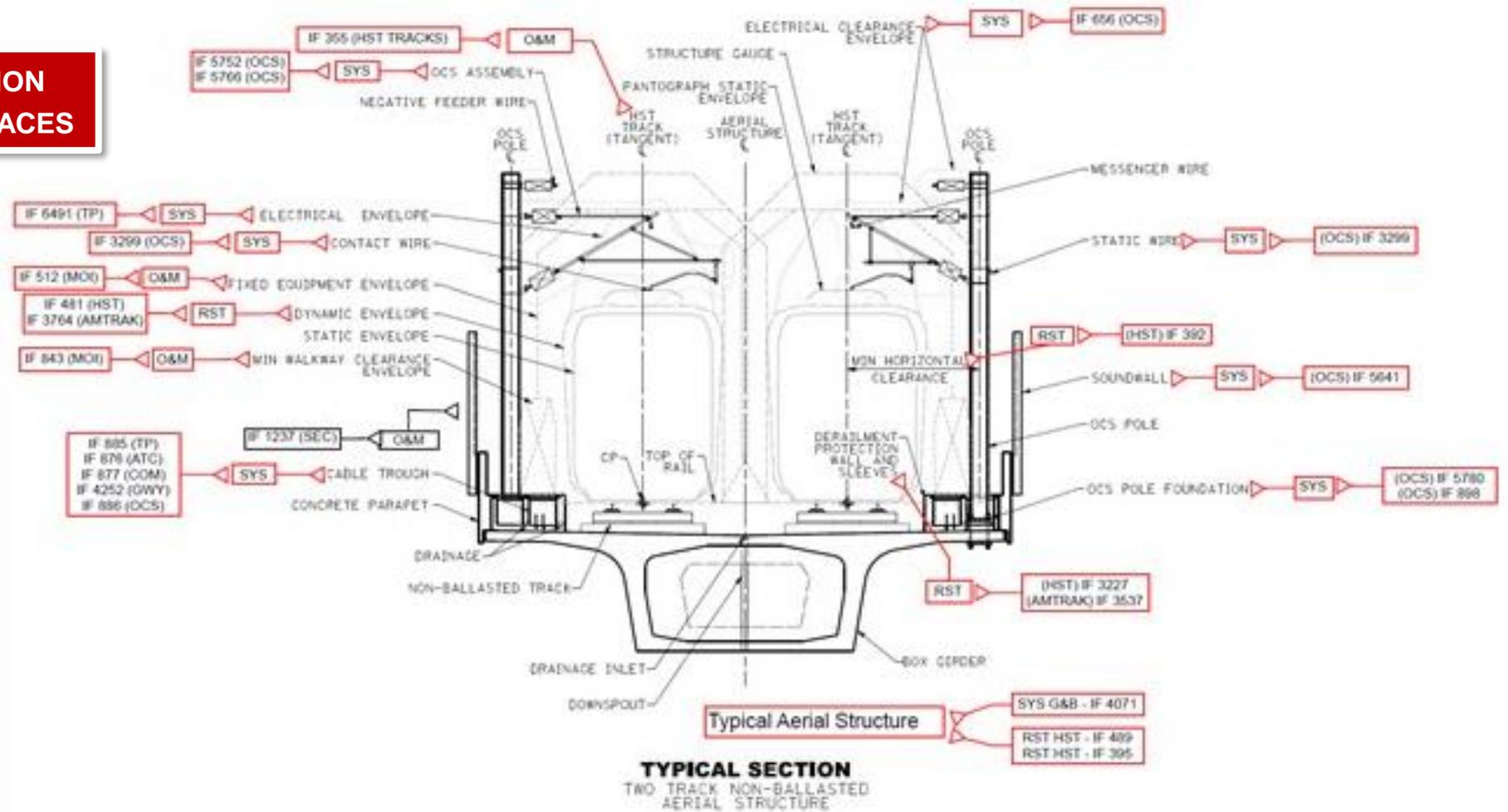
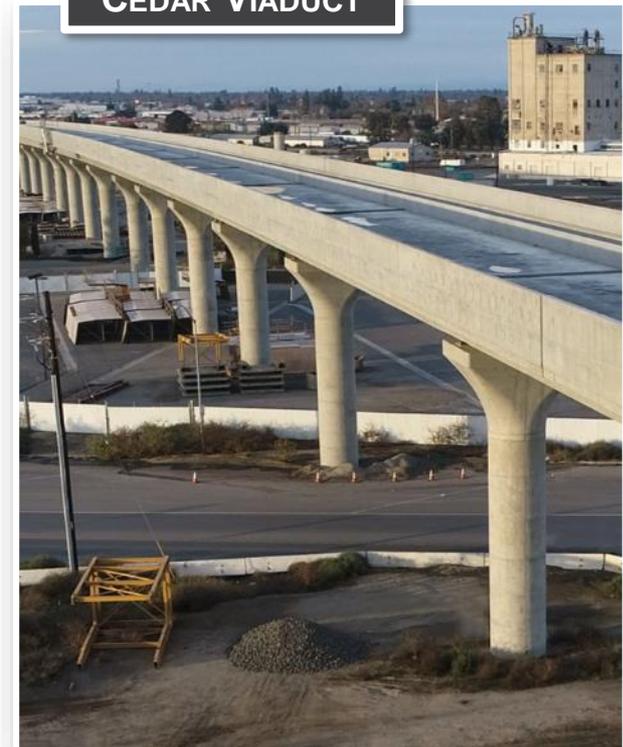
STEP 1: IDENTIFICATION OF KEY INTERFACES

INTEGRATED CROSS SECTIONS: EXAMPLE AERIAL STRUCTURE



IMPROVE VISIBILITY, RECOGNITION AND COMMUNICATION OF INTERFACES

CEDAR VIADUCT



AERIAL STRUCTURE INTEGRATED CROSS SECTION

STEP 2: IDENTIFY CANDIDATE HSR SOLUTIONS



| Model | Builder | Year Built | AW0 [UST] | Produced | Consist | Seats | Country | Length (m) | Width [m] | Train Length [m] | Height [m] | Maximum Operating Speed [kph] | Weight [tonnes] |
|--|--------------------------------|------------|---------------------|----------------------|-------------------------|---------|---------|---------------------|-----------|------------------|------------|-------------------------------|-----------------|
|  | Siemens | 2004 | 467 | 26 Trainsets | MCC-TC-MC-2TC-MC-TC-MCC | 404 | Spain | 25.67 CC 24.77 C | 2.95 | 200 | 3.89 | 350 | 425/T |
|  | Hitachi/Kawasaki/Nippon Sharyo | 2005~ | 769 | 97 Trainsets by 2011 | TCC-14MC-TCC | 1323 | Japan | 25 C 27.35 CC | 3.36 | 430.6 | 3.6 or 3.5 | 300 | 40/C |
|  | Alstom | 2008 | 270 to 510 | 1 Prototype | 7C~14C | 250~650 | France | 17.1 CC 17.3 C | 2.9 | 130~250 | / | 360 | 270~510 |
|  | Bombardier | 2004 | 92 Max. (Loco Only) | 46 | 1L-12C-1L | 318 | Spain | 20.87 L | 2.96 | 366 | 4 | 330 | Max 17t/Axle |

REVIEW OF OVER 30 COMMERCIALY AVAILABLE HSR TRAINSETS OPERATED IN CHINA, FRANCE, GERMANY, ITALY, KOREA, JAPAN, RUSSIA, SPAIN, TAIWAN, AND THE U.S.

California High-Speed Train Project



TECHNICAL MEMORANDUM
Selected Train Technologies
TM 6.1

Prepared by: *Joseph Sillen* 30 May 08
Date: Joseph Sillen

Checked by: *Frank Banko* 30 May 08
Date: Frank Banko

Approved by: *Ken Jong* 30 May 08
Date: Ken Jong, PE Engineering Manager

Released by: *Anthony Daniels* 30 May 08
Date: Anthony Daniels, Program Director

| Revision | Date | Description |
|----------|-----------|-----------------|
| 0 | 30 May 08 | Initial Release |
| | | |
| | | |

Prepared by **PB** for the California High-Speed Rail Authority

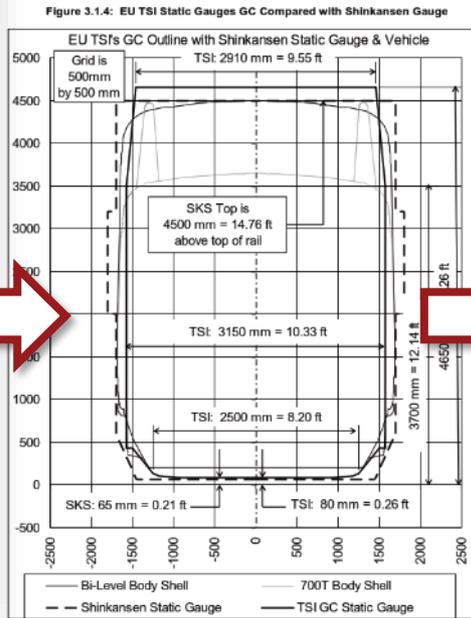
SELECTED TRAIN TECHNOLOGIES

AVE S-102 Power Car (S-350 Trainset)

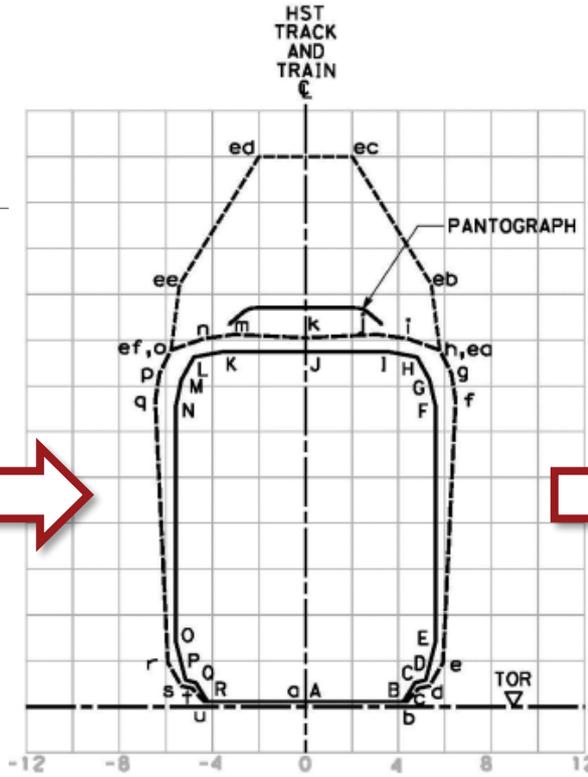
STEP 3/4: DEVELOP INTEROPERABLE INTERFACE STANDARD



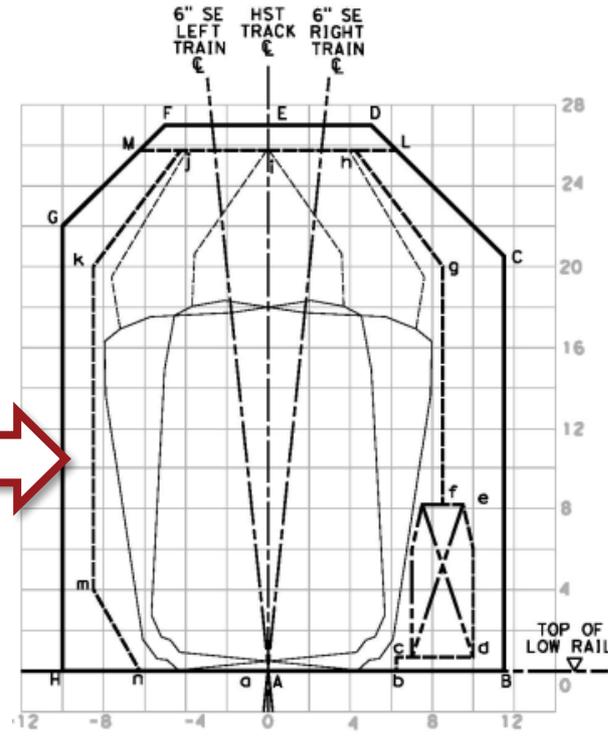
CANDIDATE HSR TRAINSETS



OVERLAID TRAINSET ENVELOPES



INTEROPERABLE TRAINSET ENVELOPES



INTEROPERABLE STRUCTURE GAUGES

Appendix 3.G: All Passenger Equipment, Structure Gauge and Fixed Equipment Envelope, Open Sections

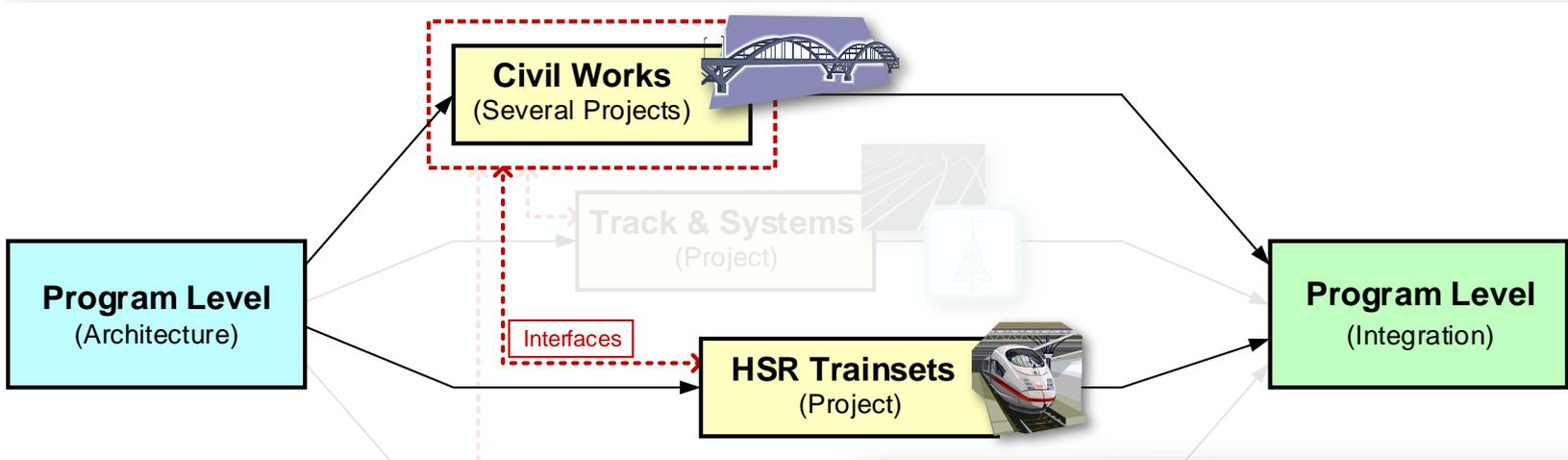
| Open Sections | | |
|---|-------------------------------------|-----------------------------------|
| Point ID | Horizontal Distance from TCL (feet) | Vertical Distance from TOR (feet) |
| Structure Gauge | | |
| Walkway Side (See Note 3 & 4) | | |
| A | 0.00 | 0.00 |
| B | 11.50 | 0.00 |
| C | 11.50 | 20.50 |
| D | 5.00 | 27.00 |
| E | 0.00 | 27.00 |
| Non-Walkway Side | | |
| A | 0.00 | 0.00 |
| H | -10.00 | 0.00 |
| G | -10.00 | 20.50 |
| F | -5.00 | 27.00 |
| E | 0.00 | 27.00 |
| Under Existing Low Overhead Structures | | |
| L | 6.25 | 25.75 |
| M | -6.25 | 25.75 |
| Fixed Equipment Envelope | | |
| Walkway Side (See Notes 1, 3, & 4) | | |
| a | 0.00 | 0.00 |
| b | 6.25 | 0.00 |
| c | 6.25 | 0.67 |
| d | 10.00 | 0.67 |
| e | 10.00 | 8.17 |
| f | 8.50 | 8.17 |
| g | 8.50 | 20.00 |
| h | 4.25 | 25.75 |
| i | 0.00 | 25.75 |
| Non-Walkway Side | | |
| a | 0.00 | 0.00 |
| n | -6.25 | 0.00 |
| m | -8.50 | 4.00 |
| k | -8.50 | 20.00 |
| j | -4.25 | 25.75 |

CIVIL WORKS DESIGN CRITERIA

STEP 5: CIVIL WORKS IMPLEMENTATION



COMMUNICATION OF INTERFACES & INTERFACE STANDARDS TO CONTRACTORS



IMPOSED CHSRS INTERFACES USING N² CHART APPROACH

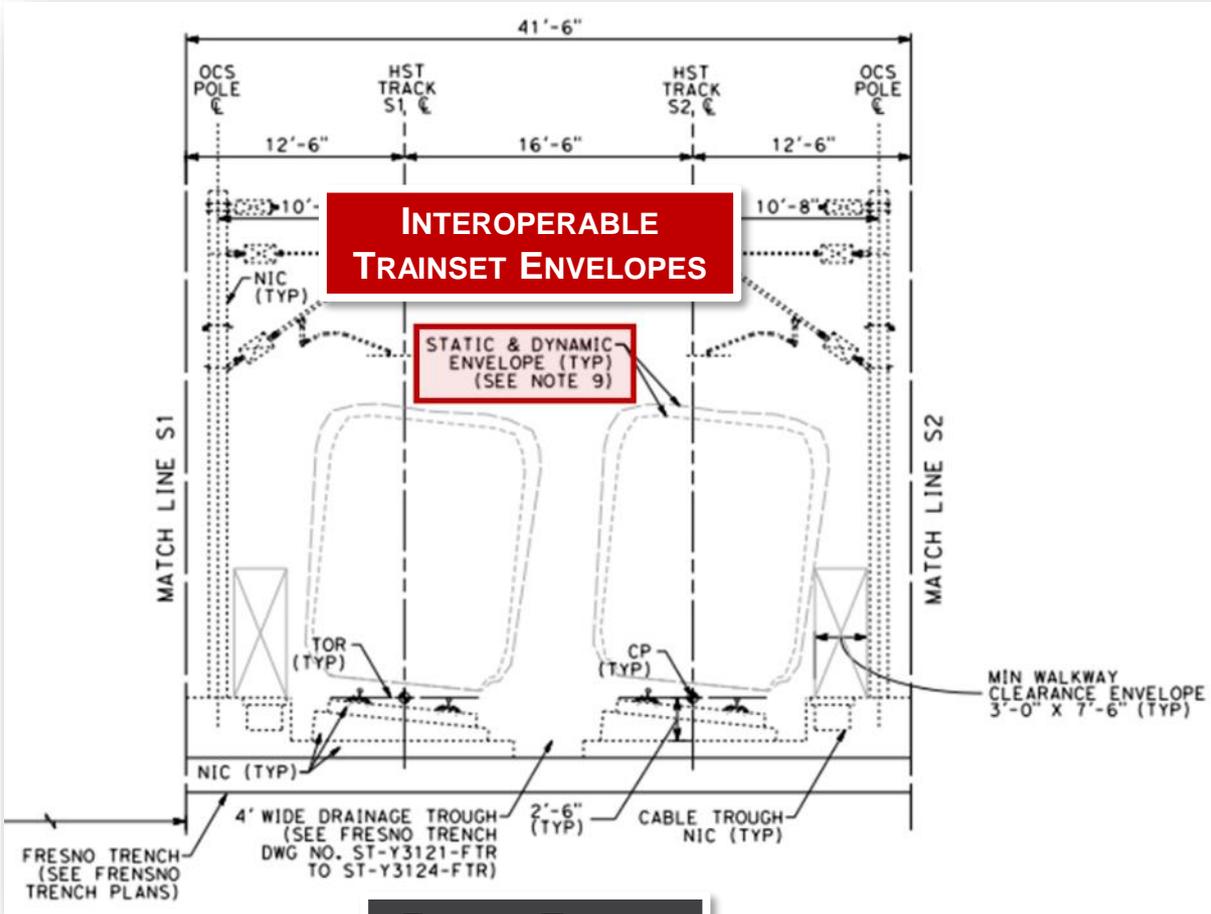
4 ROLLING STOCK
4.1 HST Trainsets
4.1.1 Interfaces with Guideway (excl. Trackwork)

- 4.1.1.1 Track Alignment.....
 - 4.1.1.1.1 Interface between RST HST Trainset Minimum Radii Requirements and GWY Infrastructure
 - 4.1.1.1.2 Interface between RST HST Trainset Actual Superelevation Requirements (incl. Tilting) and GWY Infrastructure ..
 - 4.1.1.1.3 Interface between RST HST Trainset Unbalanced Superelevation Requirements and GWY Infrastructure.....
 - 4.1.1.1.4 Interface between RST HST Trainset Maximum Grade Requirements and GWY Infrastructure.....
- 4.1.1.2 Vehicle Static Gauge & Dynamic Envelope.....
 - 4.1.1.2.1 Interface between RST HST Trainset Static Gauge Requirements and GWY Infrastructure.....
 - 4.1.1.2.2 Interface between RST HST Trainset Dynamic Envelope Requirements and GWY Infrastructure ..
- 4.1.1.3 Aerodynamic Effects.....
 - 4.1.1.3.1 Interface between RST HST Trainset Aerodynamic Effects and GWY Infrastructure
- 4.1.1.4 Loads & Forces
- 4.1.1.4.1 Interface between RST HST Trainset Axle Loads and GWY Infrastructure
- 4.1.1.4.2 Interface between RST HST Trainset Dynamic Train-Structure Interaction Analysis and GWY Infrastructure.....
- 4.1.1.4.3 Interface between RST HST Trainset Traction & Braking Forces and GWY Infrastructure
- 4.1.1.4.4 Interface between RST HST Trainset Nosing & Hunting Effects and GWY Infrastructure
- 4.1.1.4.5 Interface between RST HST Trainset Dynamic Train-Structure Interaction Analysis and GWY Infrastructure.....

LIST OF INTERFACES PROVIDED TO CIVIL WORKS INCLUDING REFERENCES TO DESIGN CRITERIA

STEP 5: CIVIL WORKS IMPLEMENTATION

CONTRACTOR FINAL DESIGN & CONSTRUCTION



**FRESNO TRENCH
FINAL DESIGN**



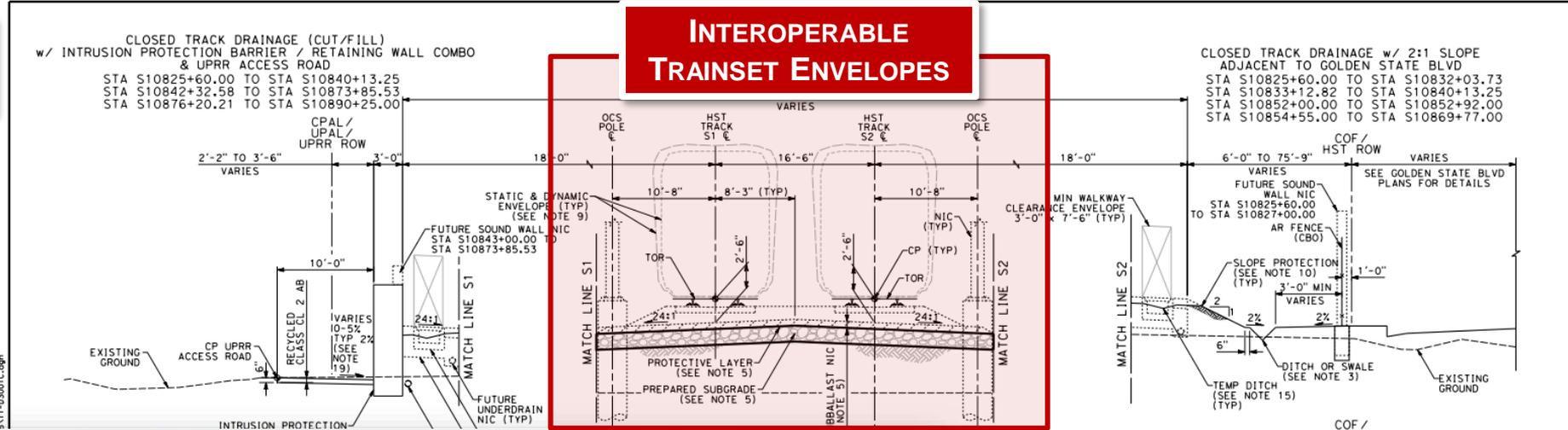
**FRESNO TRENCH
CONSTRUCTION**

STEP 5: CIVIL WORKS IMPLEMENTATION

TRUST BUT VERIFY (CHSRS VERIFICATION & VALIDATION PROCESS)



**CONTRACTOR
DESIGN SUBMITTAL**

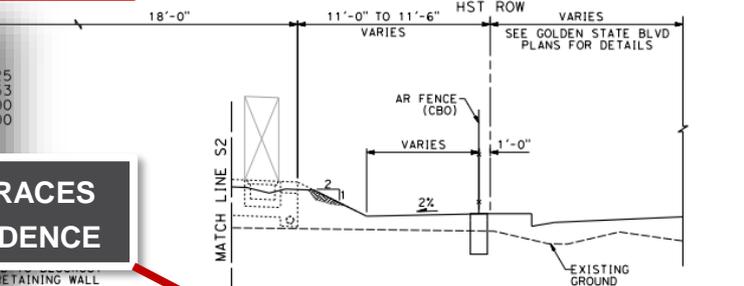


**INTERFACE TRACEABILITY
(CERTIFIABLE ITEMS LIST)**

| ID | DOC ID | CIL-Safety | Document Section | Requirements Text | Reference |
|----|------------------|-----------------------|--|---|-----------|
| 71 | Interoperability | CHSRIR329 (IF 481) | 4 Rolling Stock 4.1 HST Trainset 4.1.1 Interfaces with Guideway (excl. work) 4.1.2 Vehicle Static Gauge & Dynamic Envelope 4.1.1.2.2 Interface between RST HST Trainset Dynamic Envelope Requirements and GWY Infrastructure | <u>Purpose/Scope:</u> Ensures that the RST HST trainset dynamic envelope requirements have been addressed by the INF team. | TT-D3001C |

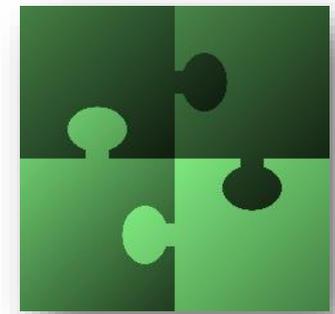
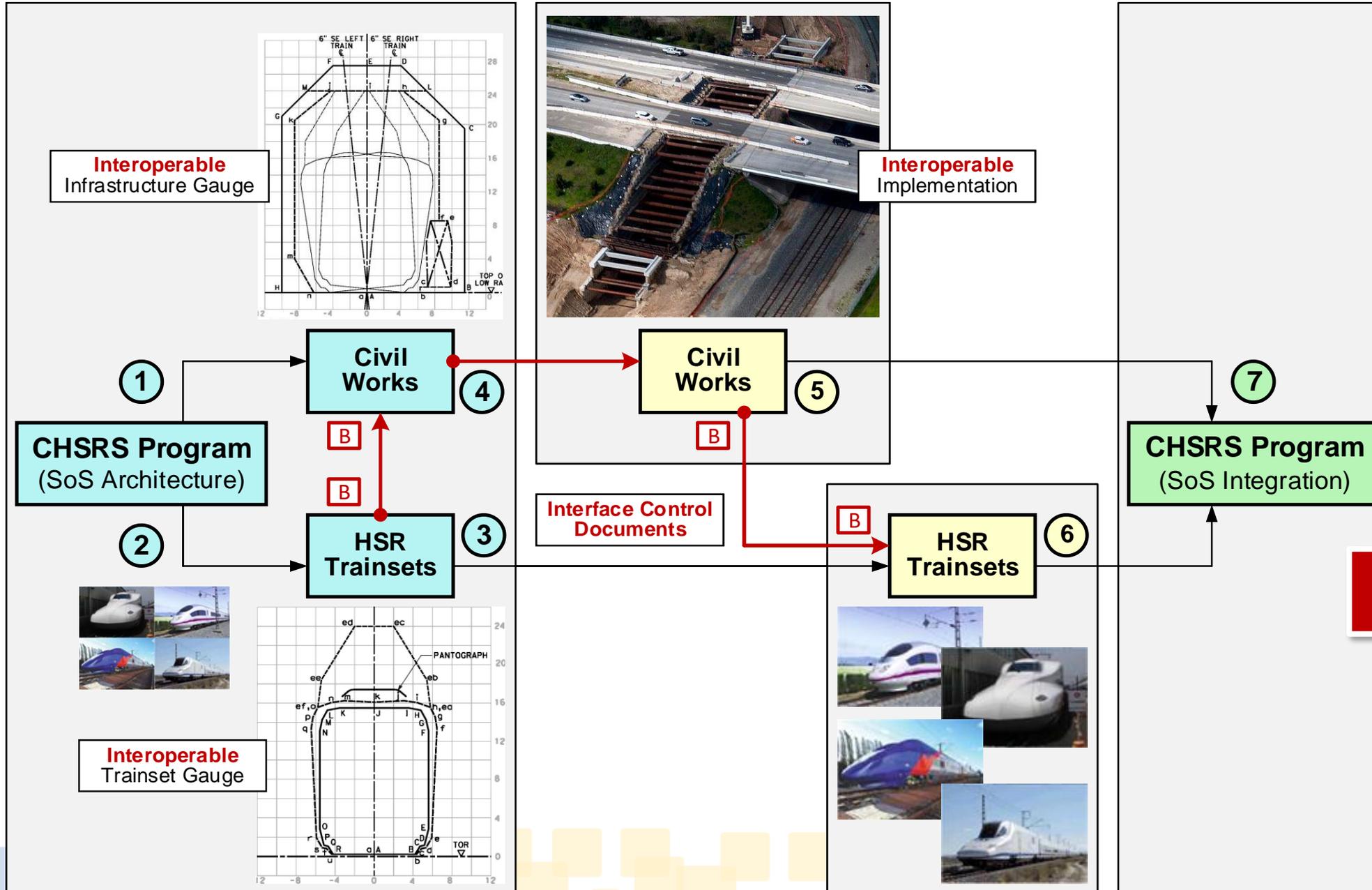
**INTEROPERABLE
CHSRS INTERFACE**

**REFERENCES & TRACES
TO OBJECTIVE EVIDENCE**



TT-D3001C

STEP 6/7: FOLLOW-UP CONTRACTS, FINAL INTEGRATION





❖ Introduction

- System of Systems (SoS)
- California High-Speed Rail System (CHSRS) Program
- CHSRS as a System of Systems

❖ SoSE Challenges Faced

- Traditional Industry Approach to Systems Integration
- SoS Engineering Challenges

❖ SoSE Activities Performed

- International Best Practice Analysis of HSR System Integration
- SoS Integration Strategy
- Step by Step Process Description

❖ Summary, Achieved Outcomes & Conclusion

SUMMARY



INTRODUCTION: SYSTEM OF SYSTEMS INCOSE SoS PRIMER

SoS Pain Points

- SoS Authority:** Who has the authority to make decisions about the system of systems?
- SoS Principles:** What are the guiding principles for the system of systems?
- Leadership:** Who is responsible for the system of systems?
- Constituent Systems:** What are the constituent systems of the system of systems?
- Autonomy, Interdependence & Emergence:** How do the constituent systems interact and emerge as a system of systems?

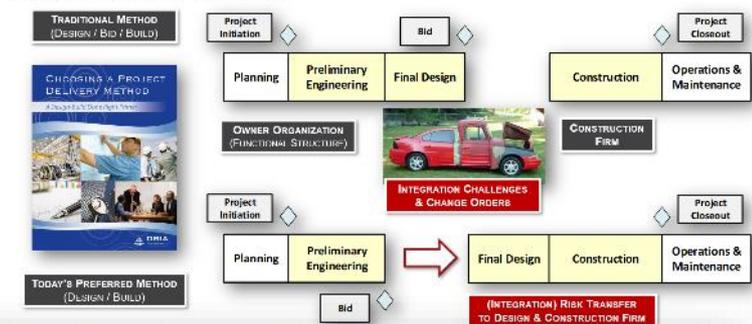
CALIFORNIA HIGH-SPEED RAIL SYSTEM (CHSRs) BRIEF INTRODUCTION

Source: <https://www.wsp.com/en-GL/projects/california-high-speed-rail>

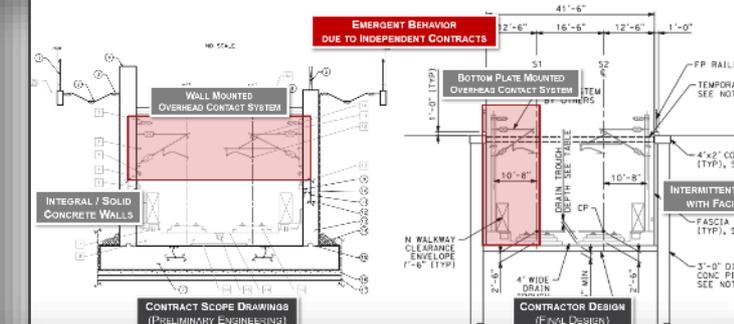
CHSRs AS A SYSTEM OF SYSTEMS CHSRs AS A CONSTITUENT SYSTEM WITHIN A LARGER SoS



TRADITIONAL INDUSTRY APPROACH TO SYSTEMS INTEGRATION PROJECT DELIVERY METHODS



CHSRs CHALLENGES FACED SoS AUTONOMY & EMERGENCE, CONSTITUENT SYSTEMS

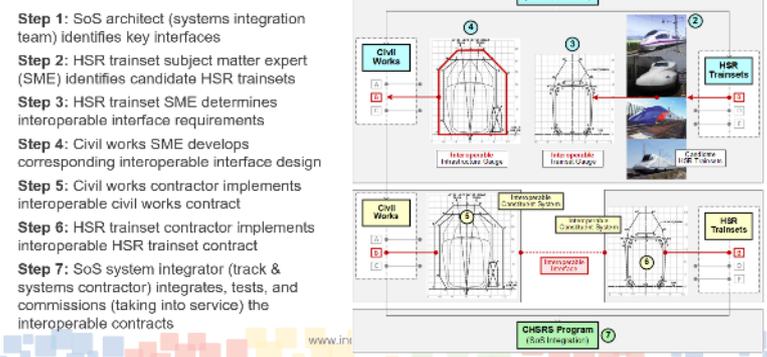


INTERNATIONAL BEST PRACTICE ANALYSIS TECHNICAL SPECIFICATIONS FOR INTEROPERABILITY (TSI)

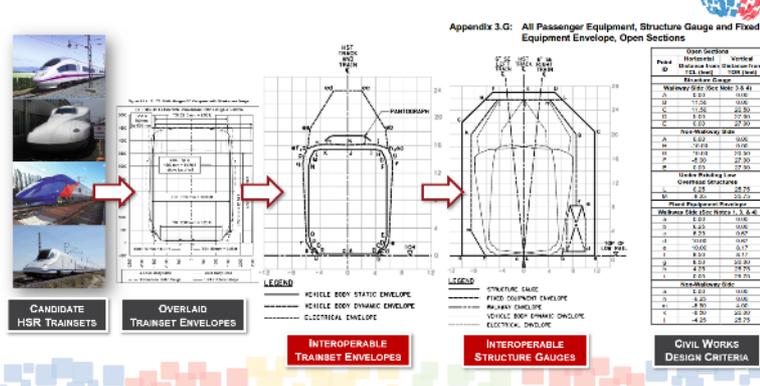
THE TRANS-EUROPEAN HIGH-SPEED RAIL SYSTEM

TECHNICAL SPECIFICATIONS FOR INTEROPERABILITY (TSI)

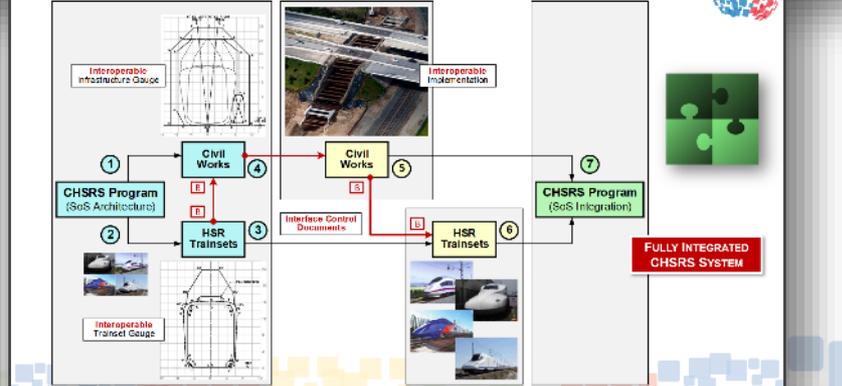
SoS INTEGRATION STRATEGY SEVEN (7) STEP PROCESS



STEP 3/4: DEVELOP INTEROPERABLE INTERFACE STANDARD



STEP 6/7: FOLLOW-UP CONTRACTS, FINAL INTEGRATION



ACHIEVED OUTCOMES & CONCLUSION



❖ SoS Authority & Leadership

- Maximized limited SoS authority by focusing on technical systems integration
- Demonstrated SoS leadership by developing tailored SoS integration strategy based on proven internal best practices

❖ SoS Architecture

- Developed SoS architecture based on procurement strategy with program as SoS and procurement contracts (projects) serving as constituent systems
- Created easily understandable SoS architecture with key stakeholder buy-in

❖ SoS Collaboration & Integration

- Worked closely with subject matter experts to communicate, specify and document key interfaces between the procurement contracts

❖ SoS Autonomous Constituent Systems & Emergence

- Enabled individual Design / Build contract innovation and SoS emergence, without negatively affecting overall SoS integration

- ❖ **Conclusion:** The tailored CHSRS systems integration approach created modular and interoperable constituent systems that can be efficiently integrated into a SoS, successfully **achieving system integration through interoperability**



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