SoSECIE Webinar

Welcome to the
2019 System of Systems Engineering Collaborators Information Exchange (SoSECIE)

We will start at 11AM Eastern Time

Skype Meeting +1 (703) 983-2020, 46013573#

You can download today's presentation from the OUSD(R&E) Website:

https://www.acq.osd.mil/se/outreach/sosecollab.html

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NDIA System of Systems SE Committee

- **Mission**
  - To provide a forum where government, industry, and academia can share lessons learned, promote best practices, address issues, and advocate systems engineering for Systems of Systems (SoS)
  - To identify successful strategies for applying systems engineering principles to systems engineering of SoS
- **Operating Practices**
  - Face to face and virtual SoS Committee meetings are held in conjunction with NDIA SE Division meetings that occur in February, April, June, and August
  - SoS Track at NDIA 22nd Annual Systems Engineering Conference, Grand Hilton Tampa Downtown, Tampa, FL, October 21-24, 2019
    - Conference Info: http://www.ndia.org/events/2019/10/21/22nd-annual-systems-and-mission-engineering-conference

NDIA SE Division SoS Committee Industry Chairs:
Mr. Rick Poel, Boeing
Ms. Jennie Horne, Raytheon
OSD Liaison:
Dr. Judith Dahmann, MITRE

Simple Rules of Engagement

- I have muted all participant lines for this introduction and the briefing.
- If you need to contact me during the briefing, send me an e-mail at knharrington@mitre.org.
- Download the presentation so you can follow along on your own
- We will hold all questions until the end:
  - I will start with questions submitted online via the CHAT window in Skype.
  - I will then take questions via telephone; State your name, organization, and question clearly.
- If a question requires more discussion, the speaker(s) contact info is in the brief.

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2019 System of Systems Engineering Collaborators Information Exchange Webinars
Sponsored by OUSD(R&E) and NDIA SE Division

January 22, 2019
Systems of Systems Model Building and Acausal Simulation Environment
Peter Menegay, SynaptiCAD

February 5, 2019
Development of New Standards for Systems of Systems Engineering
Dr. Mike Yokell, Lockheed Martin Fellow and Deputy Director, Systems Engineering

February 19, 2019
Systems of Systems Engineering Managerial and Operational Affinity
Dr. Mike Yokell, Lockheed Martin Fellow and Deputy Director, Systems Engineering

March 12, 2019
Mission Engineering Competency Model
Dr. Nicole A. Hutchison, Stevens Institute of Technology

March 26, 2019
Practical Modeling Concepts for Engineering Emergence in Systems of Systems
Dr. Judith Dahmann, The MITRE Corporation
Ms. Philomena Zimmerman, OUSD(R&E)

2019 System of Systems Engineering Collaborators Information Exchange Webinars

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April 16, 2019
Mission Analysis and Operational Architectures
Mr. Zane Scott, Vitech Corporation

April 30, 2019
Digital Engineering Transformation
Mr. Thomas McDermott, Georgie Tech Research Institute, SERC

May 14, 2019
Toward Scaling Model-based Engineering for Systems of Systems
Dr. Ryan B. Jacobs, The MITRE Corporation

May 28, 2019
Modular Online Open SoS Education (MOOSE)
Mr. Kyle Hastings, The MITRE Corporation

June 11, 2019
Mission Engineering and Prototype Warfare
Mr. Matthew Horning, US ARMY FUTURES COMMAND

June 25, 2019
A Tool for Architecting Socio-Technical Problems: SoS Explorer
Dr. Cihan Dagli

System of Systems Model Building and Acausal Simulation Environment

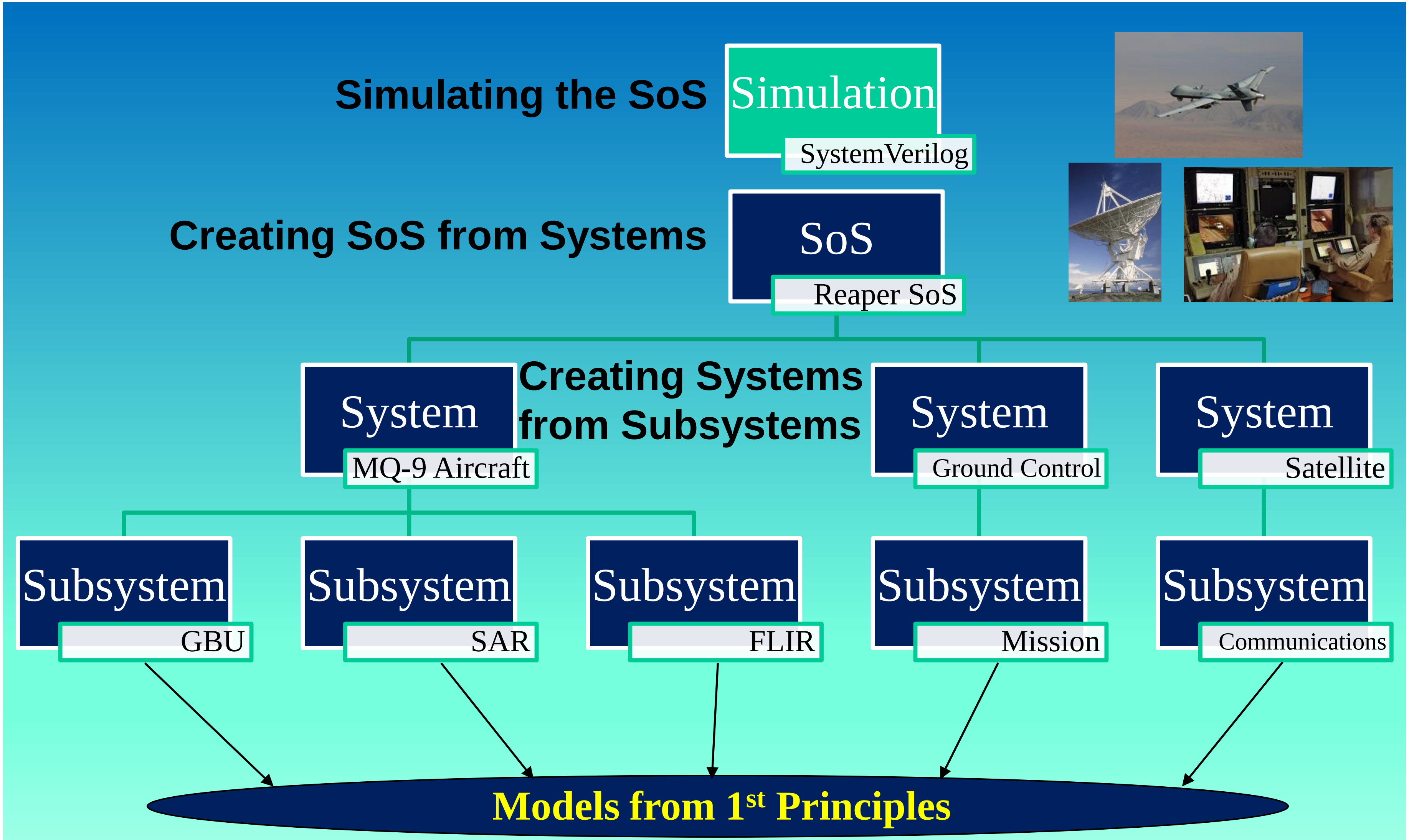
Peter Menegay – Director, Funded R&D, SynaptiCAD
pete@syncad.com, 540-953-3390
Dale Burnham – Lead Systems Engineer, AFRL
dale.burnham@us.af.mil

SoSECIE Webinar
Jan. 22, 2019

Technology Motivation

- DoD systems are increasingly complex and challenge human cognitive and organizational abilities. We are now combining those systems into System of Systems.
  - Engineering model flexibility & robustness.
  - Reuse of models.
  - SoS requirements expression and flowdown.
  - Discovering unforeseen behavior through trade studies.
  - Understanding complex results.
  - Accurate simulations, well before we commit.
  - Handling highly scaled simulation problems – “digital twin”.

The Basics



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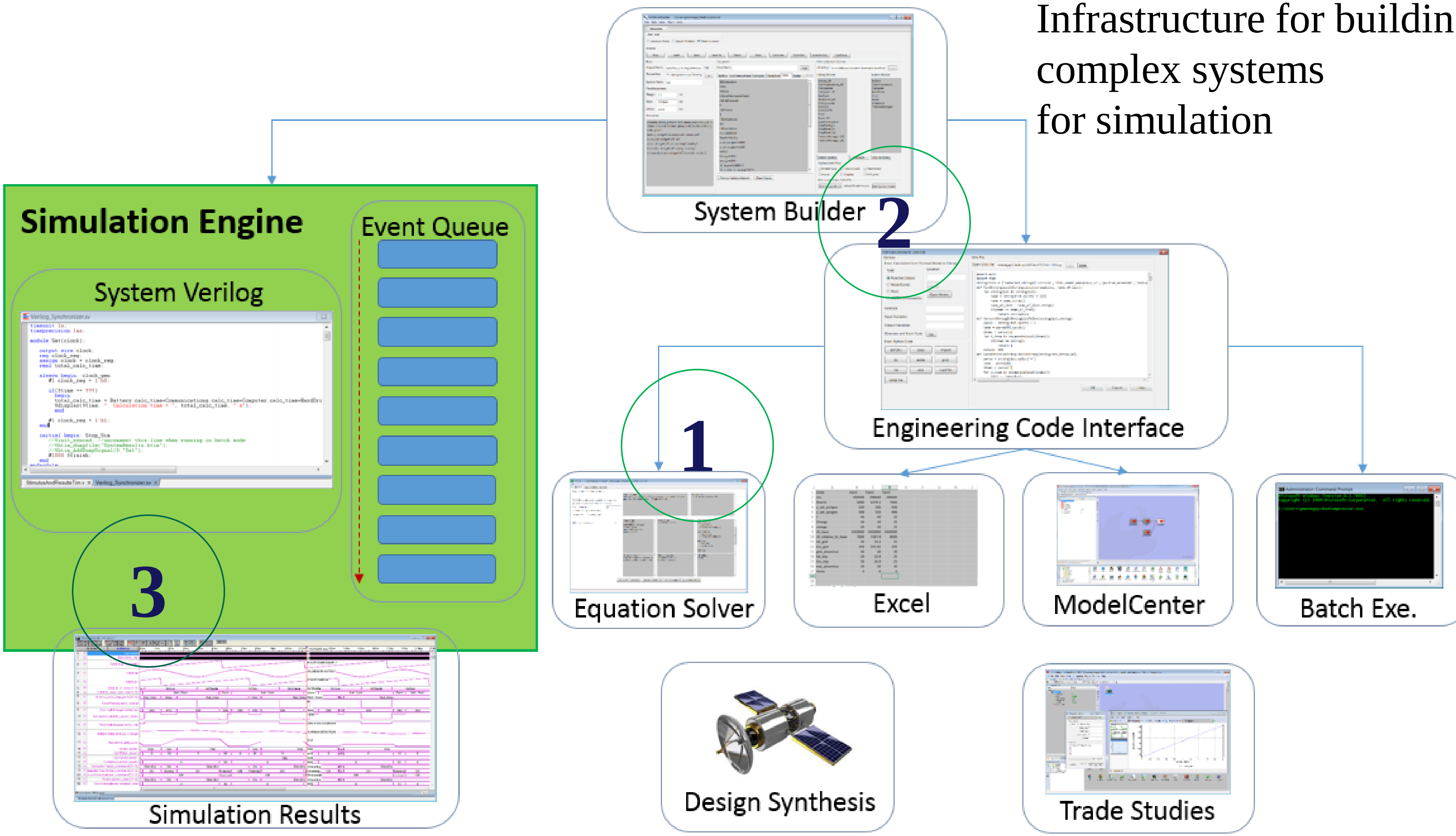
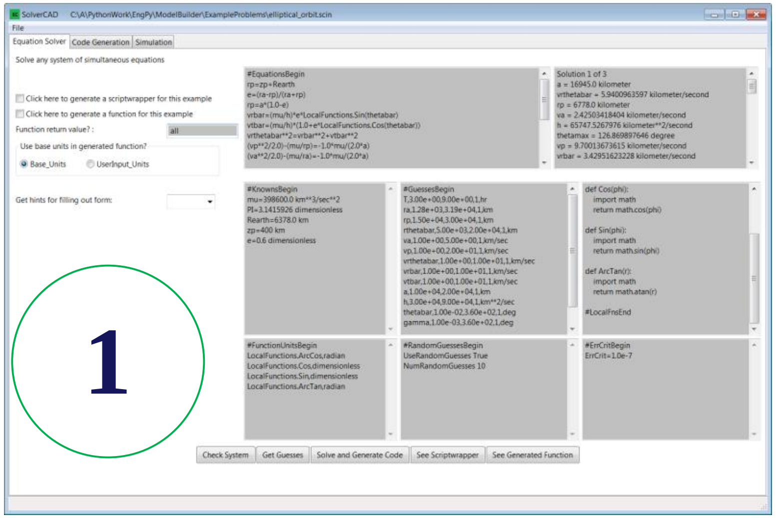
System Computation Platform

Infrastructure for building complex systems for simulation

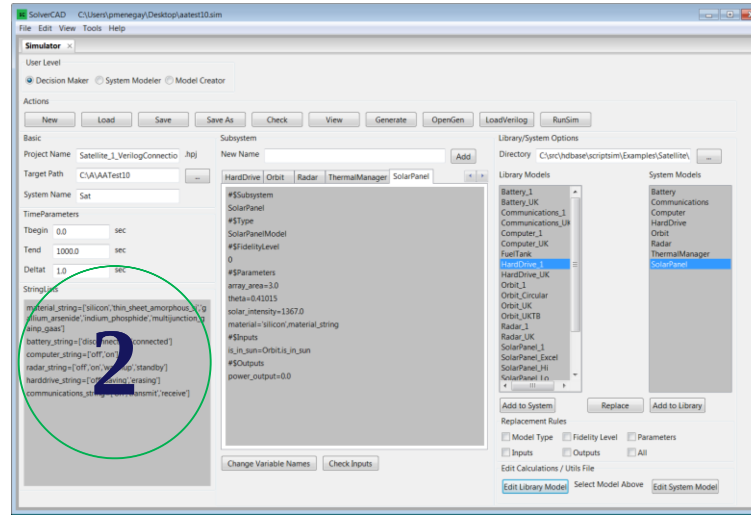


Our approach is to fix weaknesses in the 3 key areas

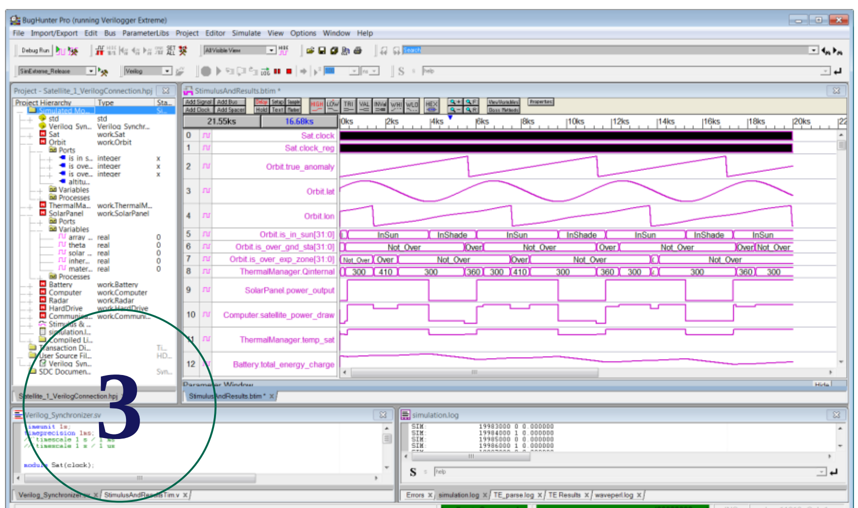
3 Core Elements & Workflow



Eqn. Based Model Creator -- Simultaneous equation solver for creating new engineering models for subsystems.



System Builder -- User interface for creating new system models.



System Simulator -- SystemVerilog simulation engine for system model execution and results.

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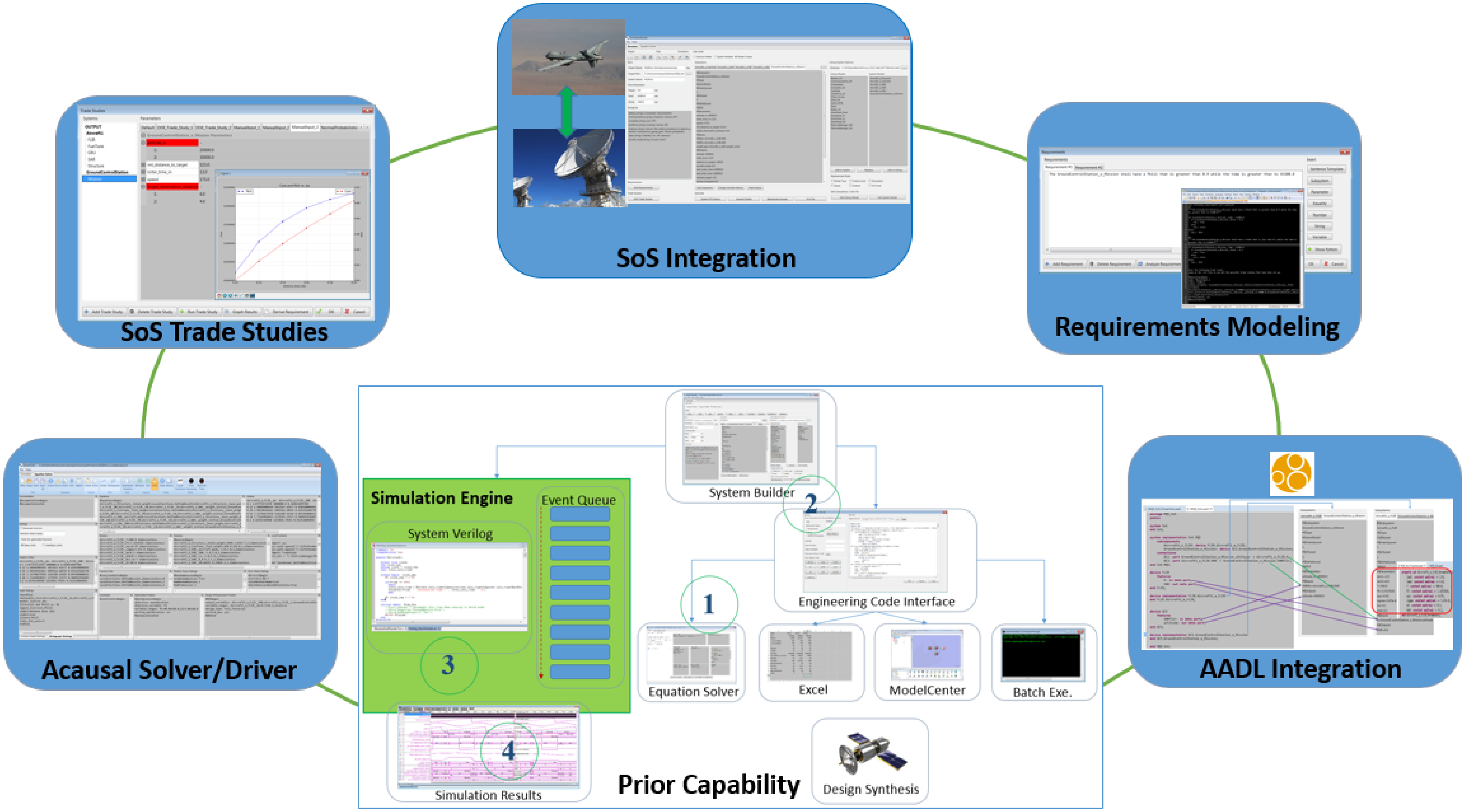
New Capability



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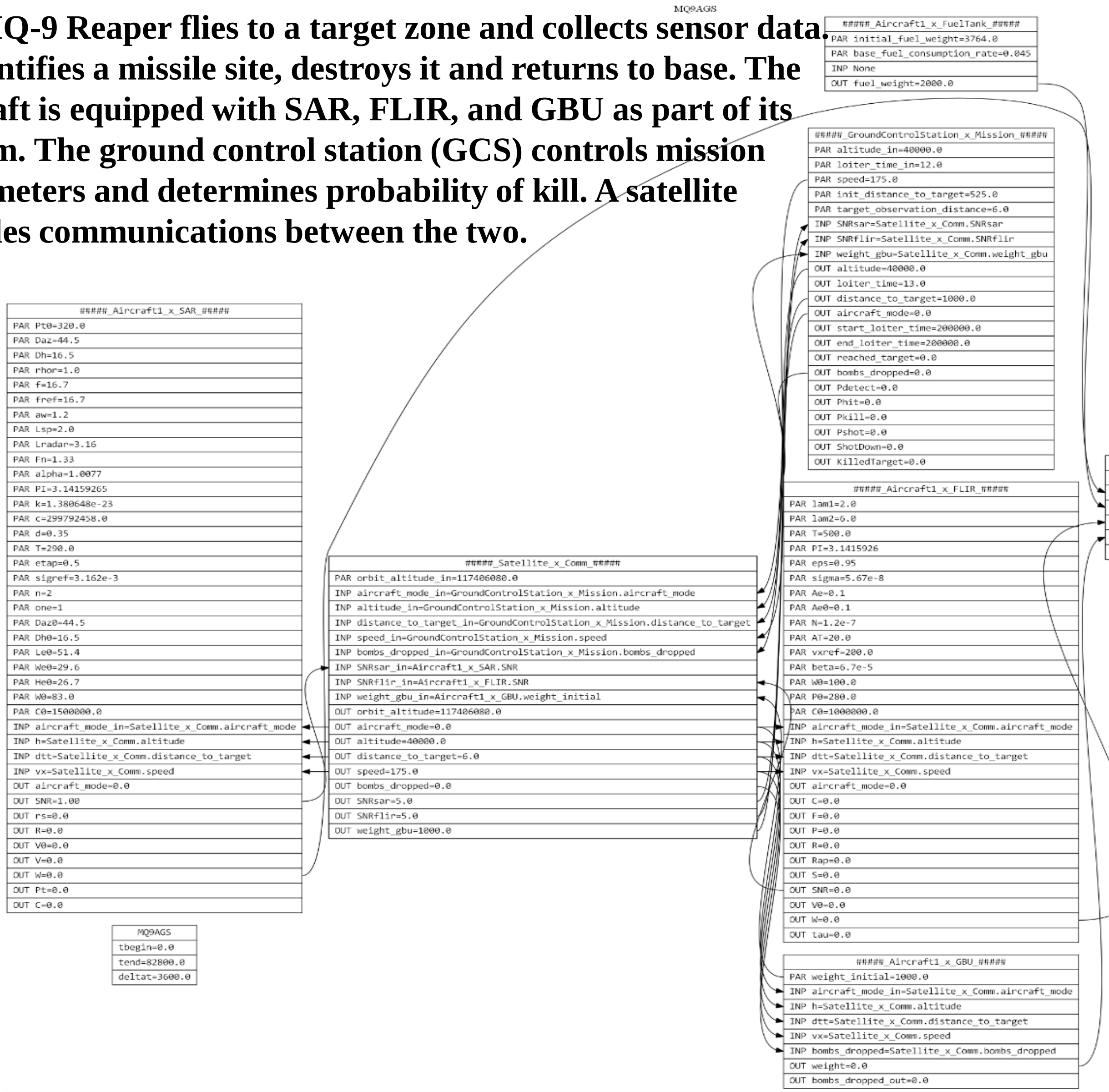
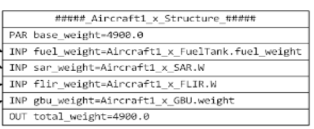
Example Problem

An MQ-9 Reaper flies to a target zone and collects sensor data. It identifies a missile site, destroys it and returns to base. The aircraft is equipped with SAR, FLIR, and GBU as part of its system. The ground control station (GCS) controls mission parameters and determines probability of kill. A satellite handles communications between the two.





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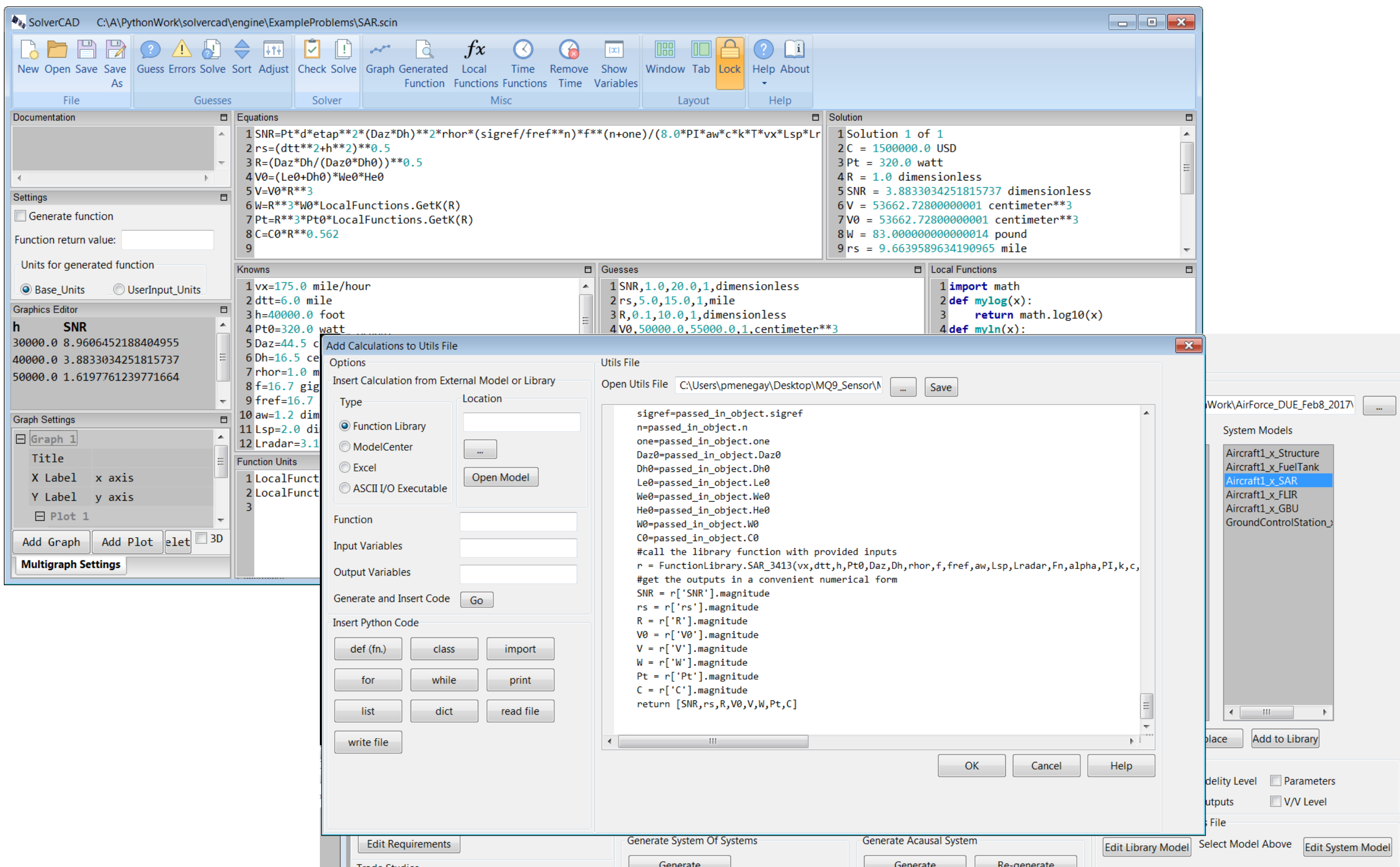
SoS Integration - 1

- First build independent systems: aircraft, ground control station, and satellite. Aircraft is composed of multiple subsystems (e.g. SAR) which can be modeled in equation solver and connected to overall system:



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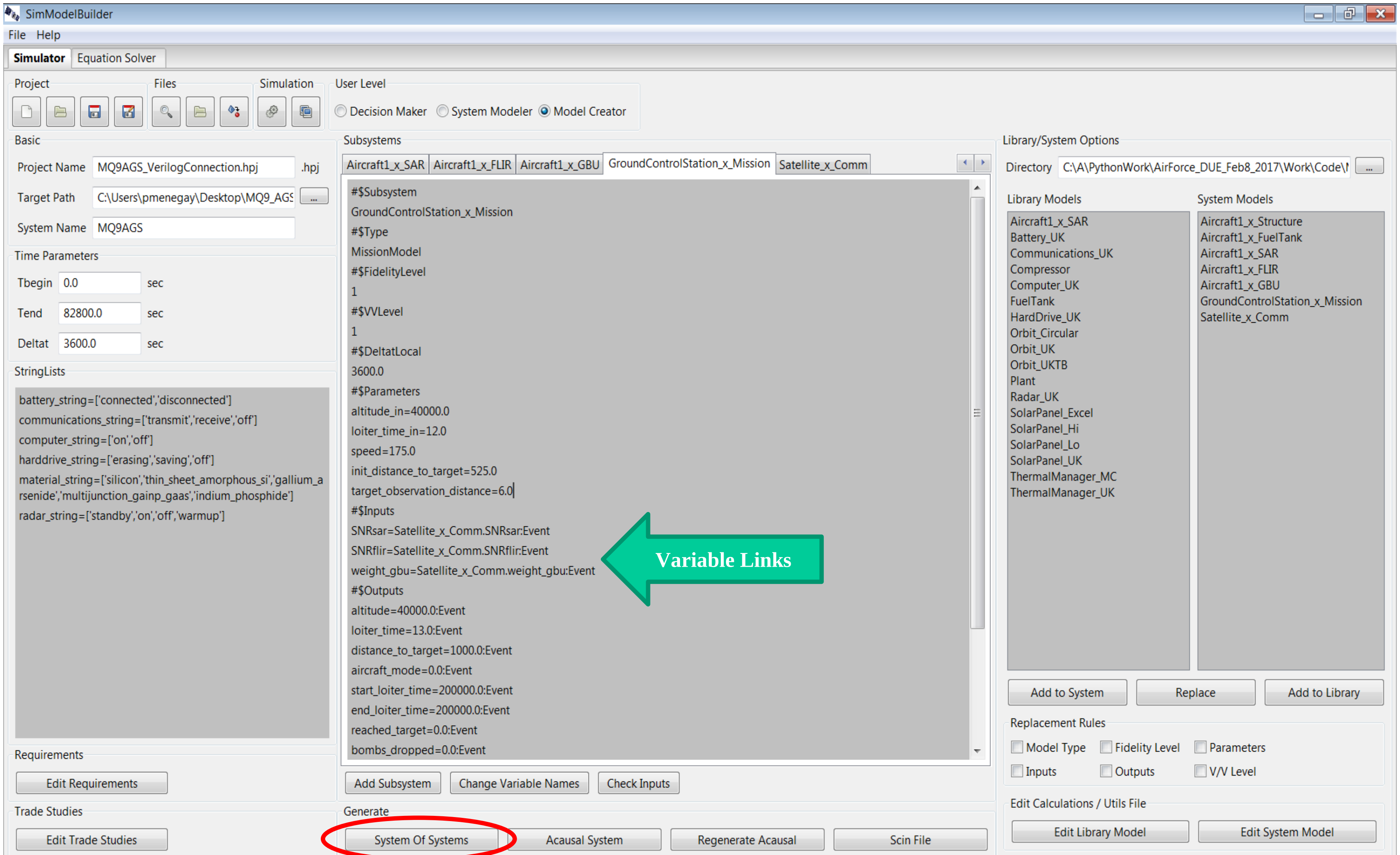
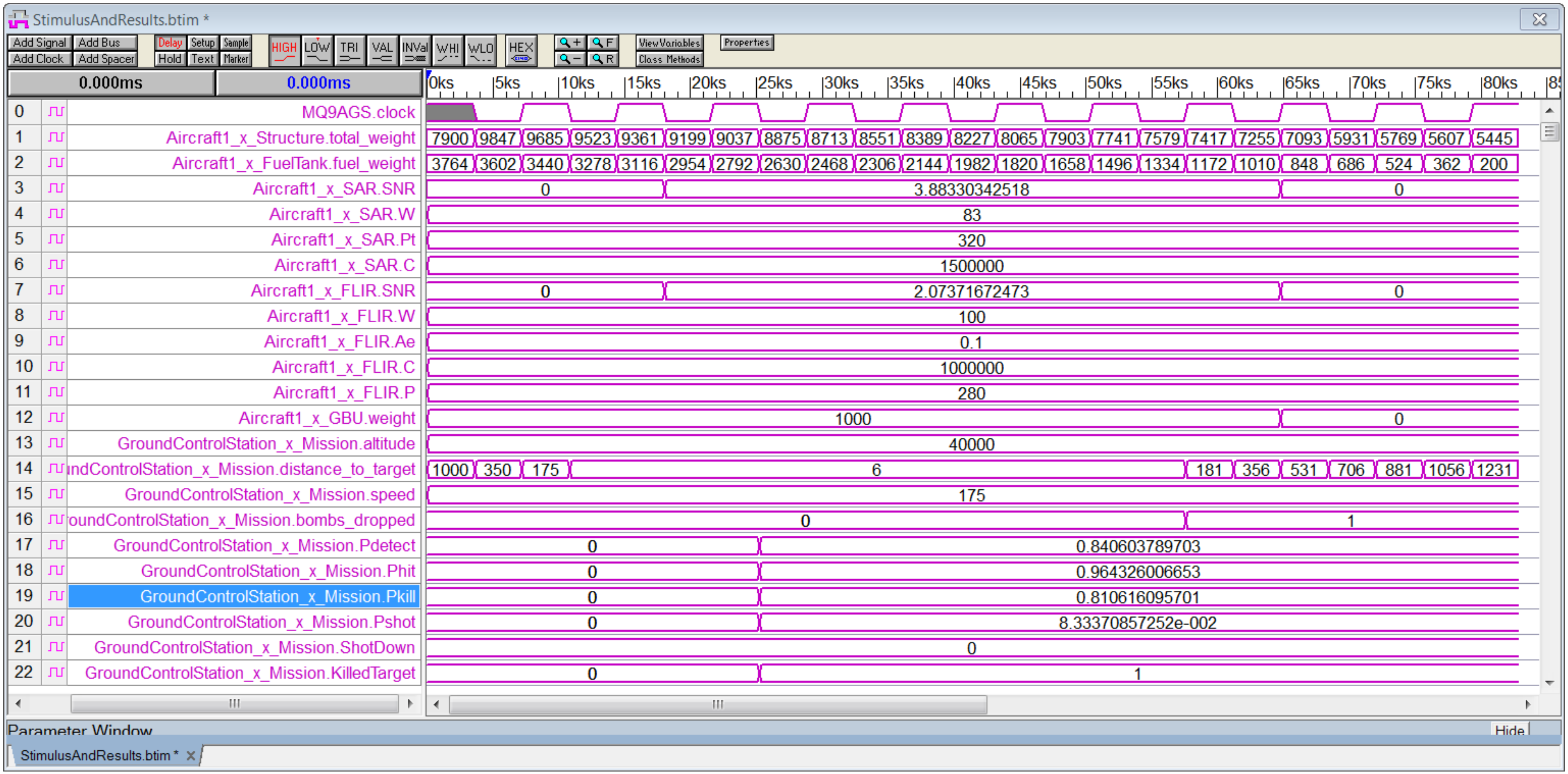
SoS Integration - 2

- Next, SoS is built by specifying which systems to unite. A flat hierarchy of all contained subsystems results. Variable links must be created.



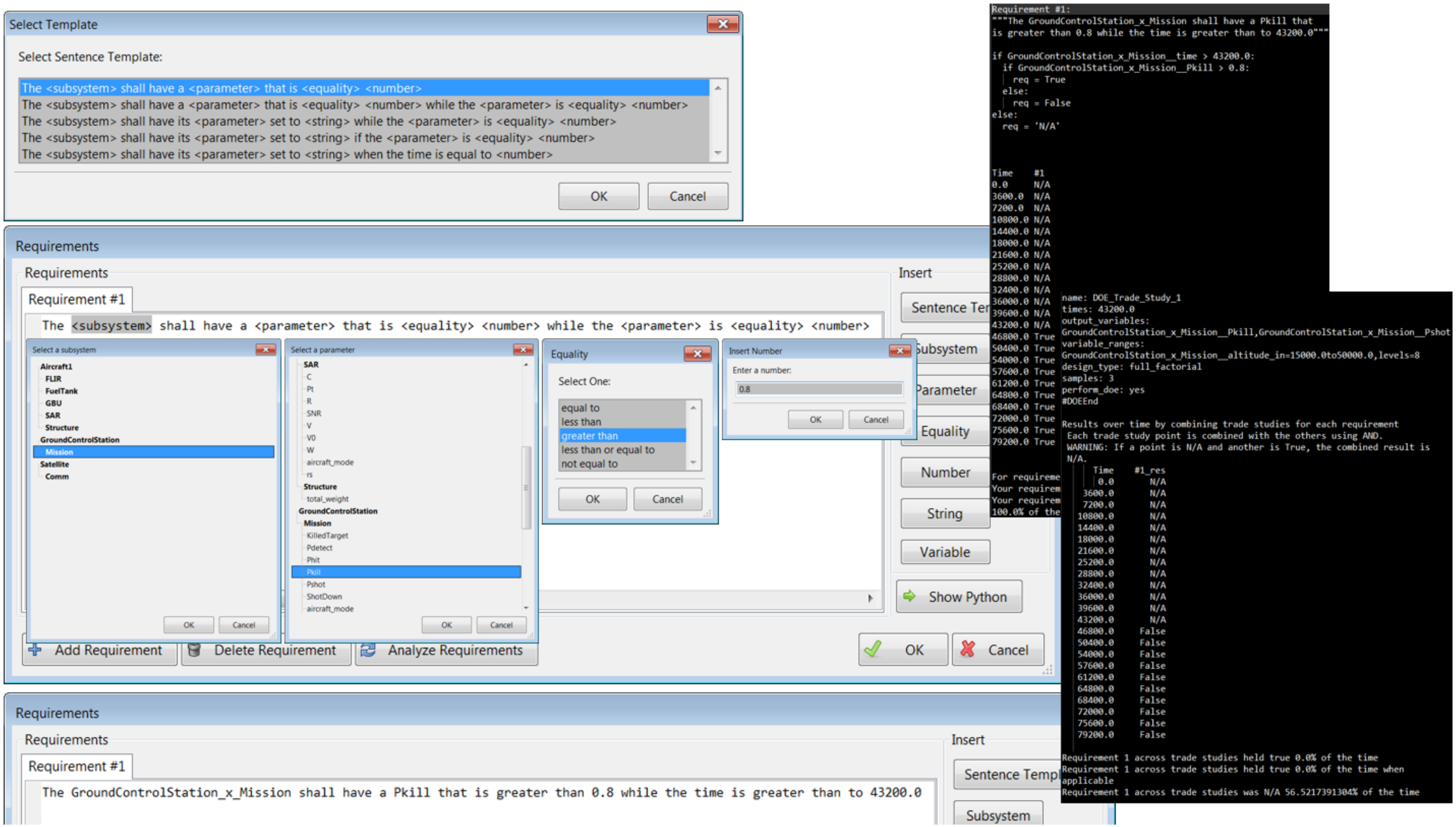
Simulation Results

- The SoS is simulated using the System Verilog engine and results are shown in a timing diagram:



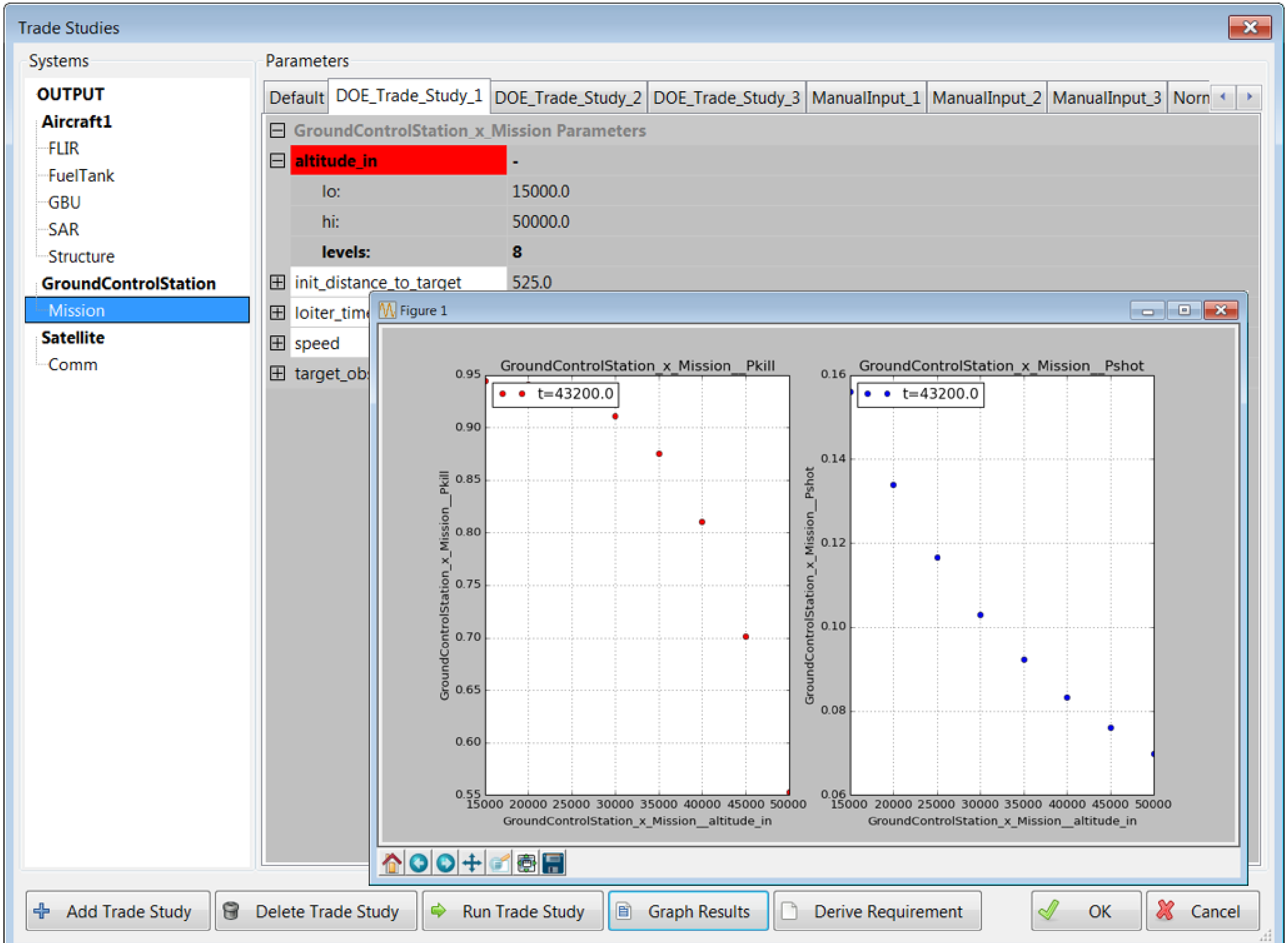
Requirements Modeling

- A template is used to create requirements sentences in English which are translated to Python for analysis. Requirements can also be written directly in Python.



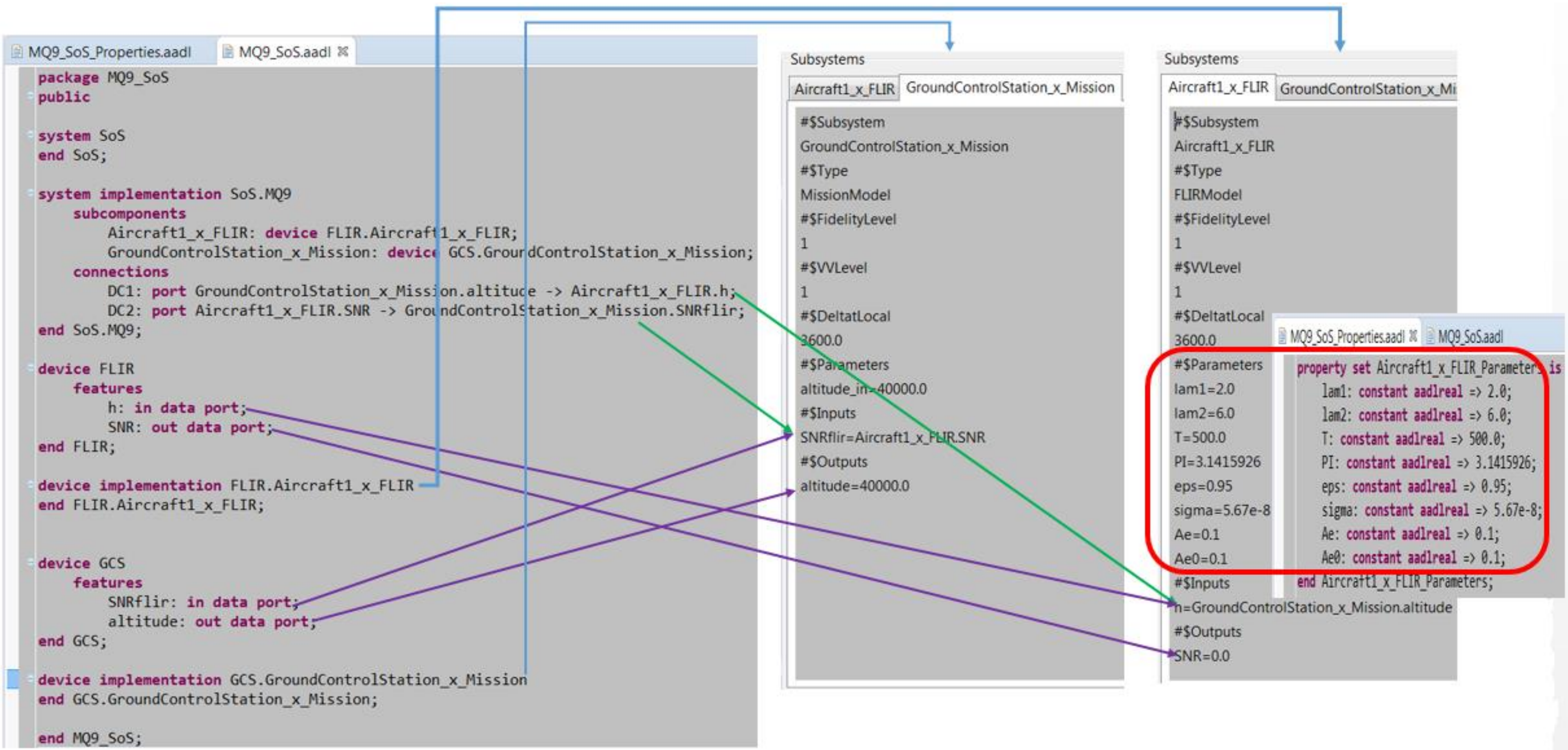
SoS Trade Studies

- Operate over the entire SoS and perform full simulations for each point. DOE, Monte-Carlo, and single variable optimization is available.



AADL Integration

- Simulation models are architecturally analogous to AADL language.



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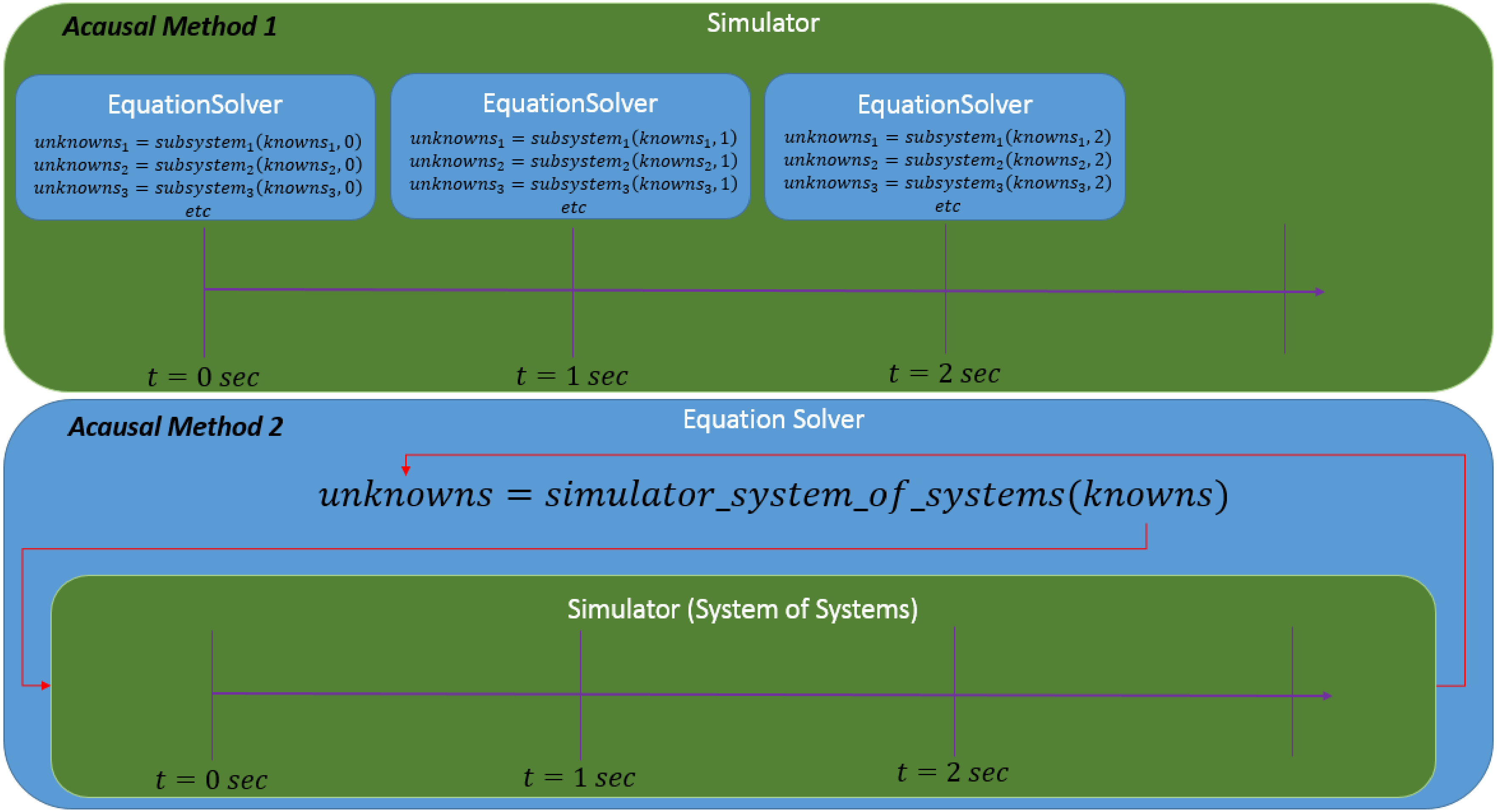
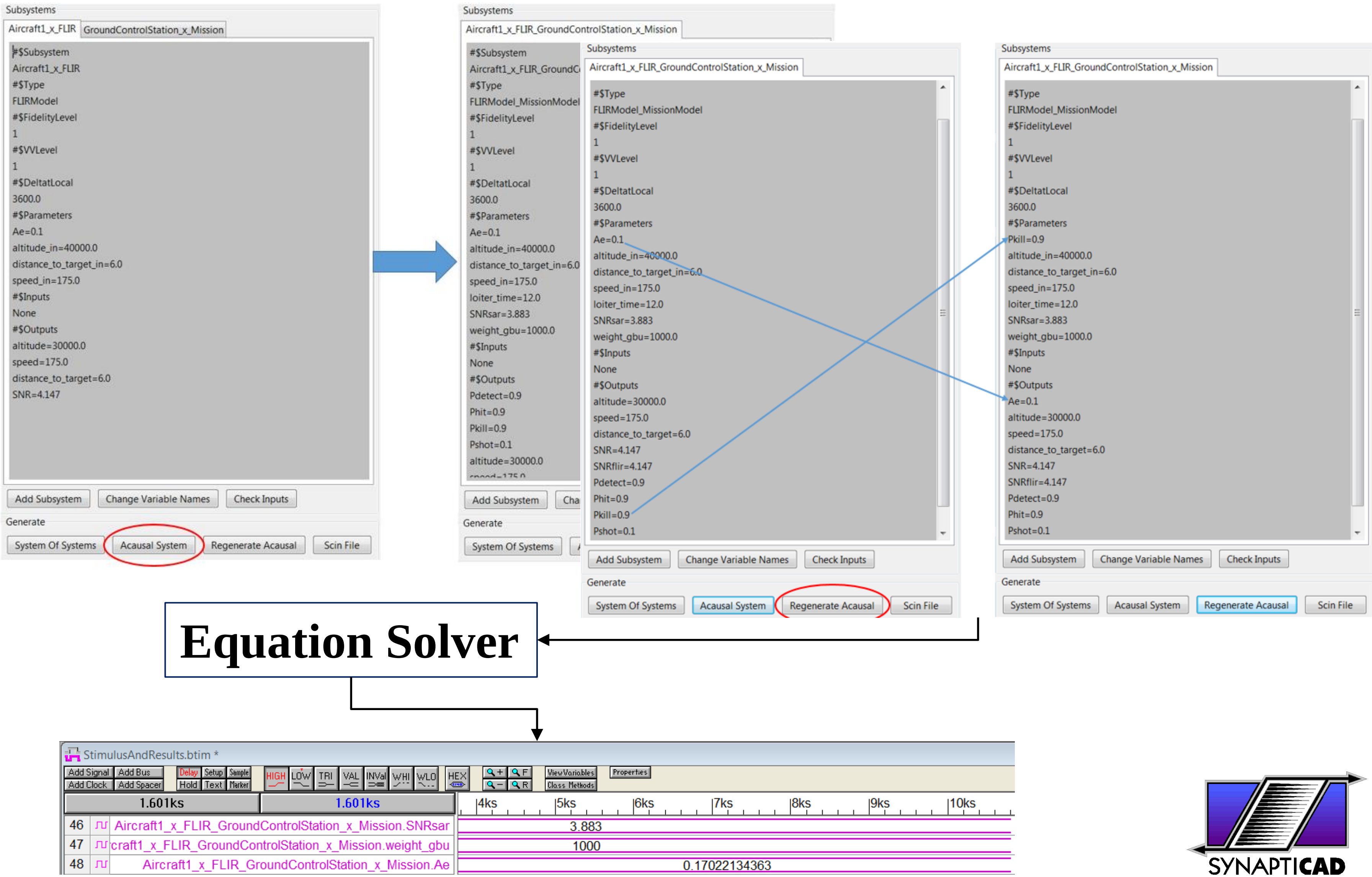
Acausal Solver/Driver

- Acausal simulation means that what we consider an input or output is not fixed. All models are solved as a system of equations using two methods:



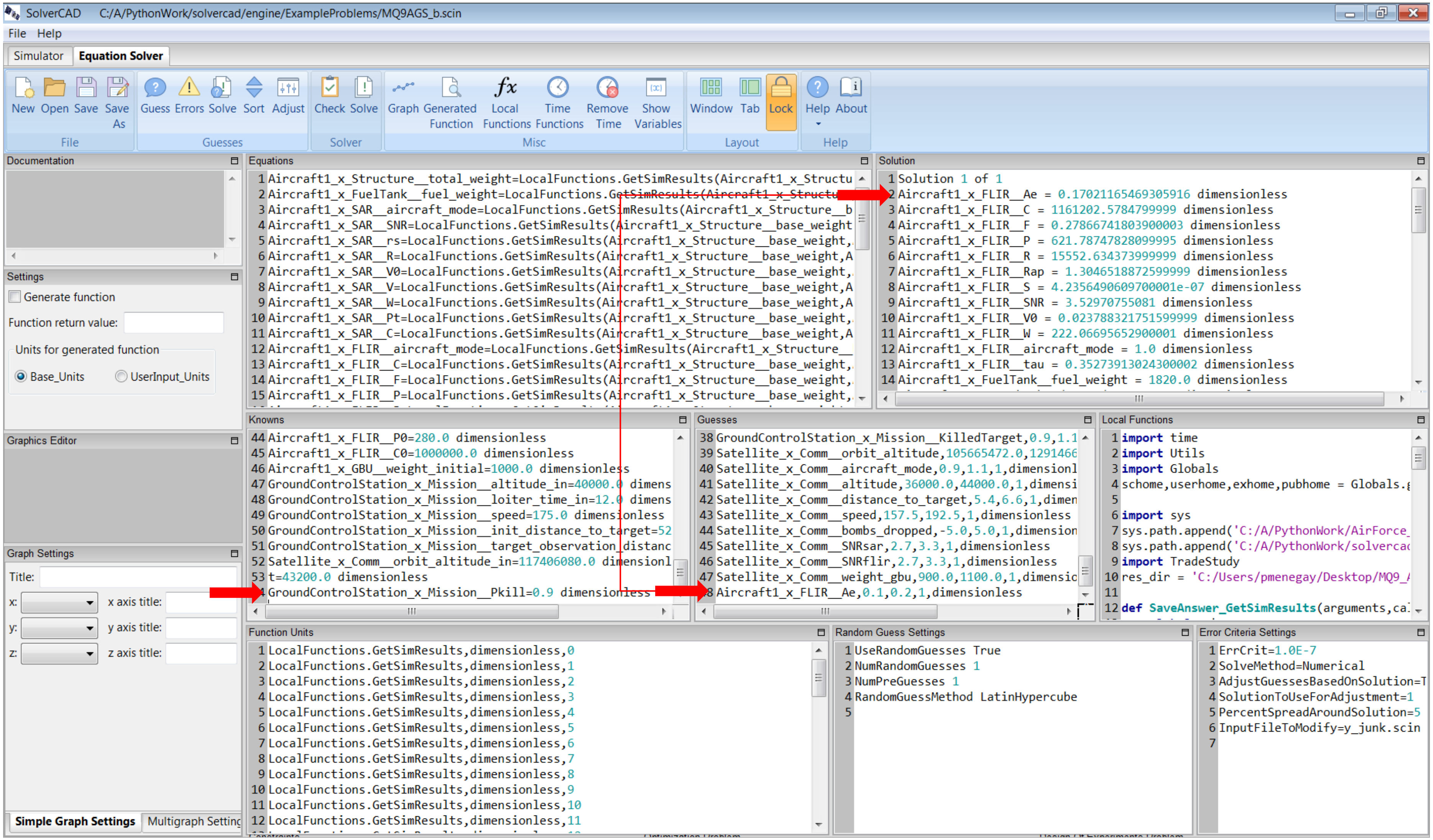
Acausal Method 1

- Each system is rendered as an equation to be solved at every timestep. The simulator is the driver and the equation solver runs behind the scenes:



Acausal Method 2

- The entire SoS is viewed as an equation to be solved over the entire span of time of the simulation. The equation solver is the driver and the simulator runs behind the scenes.



Some Observations

- Scale up.
  - Human scalability: our ability to see, understand, and manipulate large SoS models.
  - Computational scalability: Multiple nested engineering models, solved iteratively by equation solver, are possible. Trade studies make this worse.
- "Explosion" of data caused by trade studies.
- English requirements are backed up by requirements expression through a computer language (i.e. Python).
- Requirements modeling can be enforced through equation solver.
- The acausal capability allows for many scenarios without having to rebuild the model. Inputs/outputs can be switched.
- This tool is designed to be linked from 3rd party systems engineering tools such as AADL or SysML.

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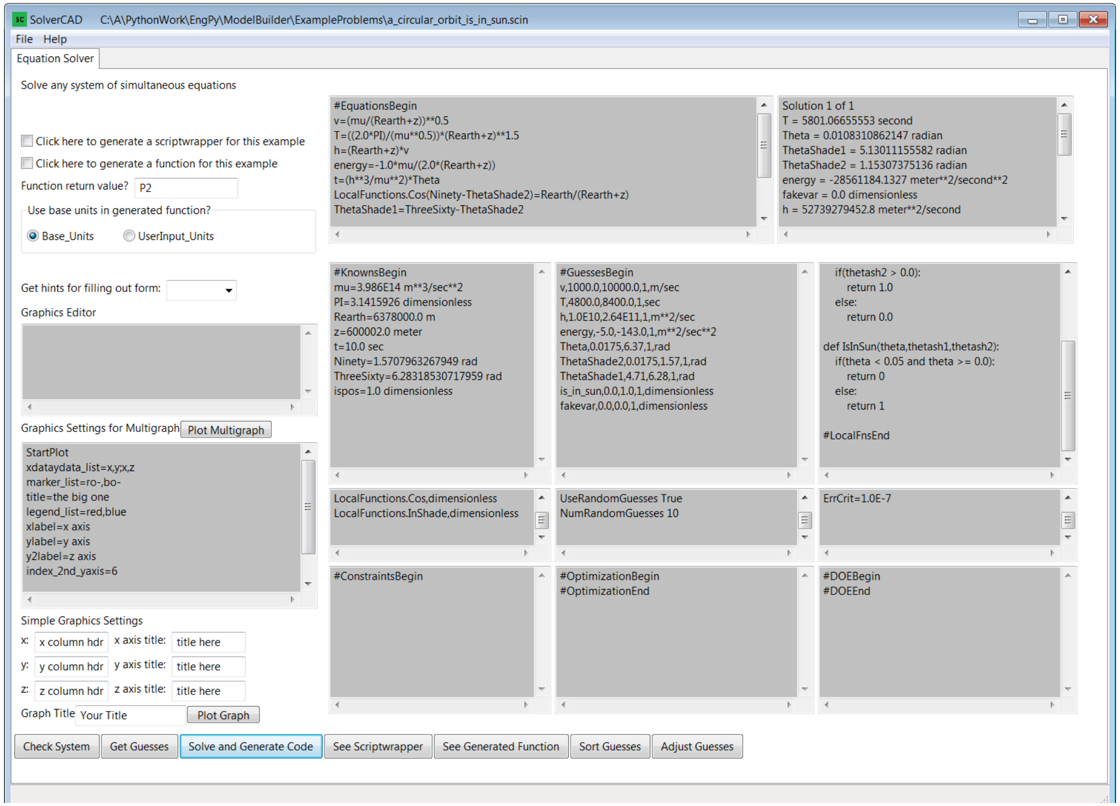
Backup Slides

1. Eqn. Based Model Creator

A general purpose model-creation environment for engineering analysis. Under development.

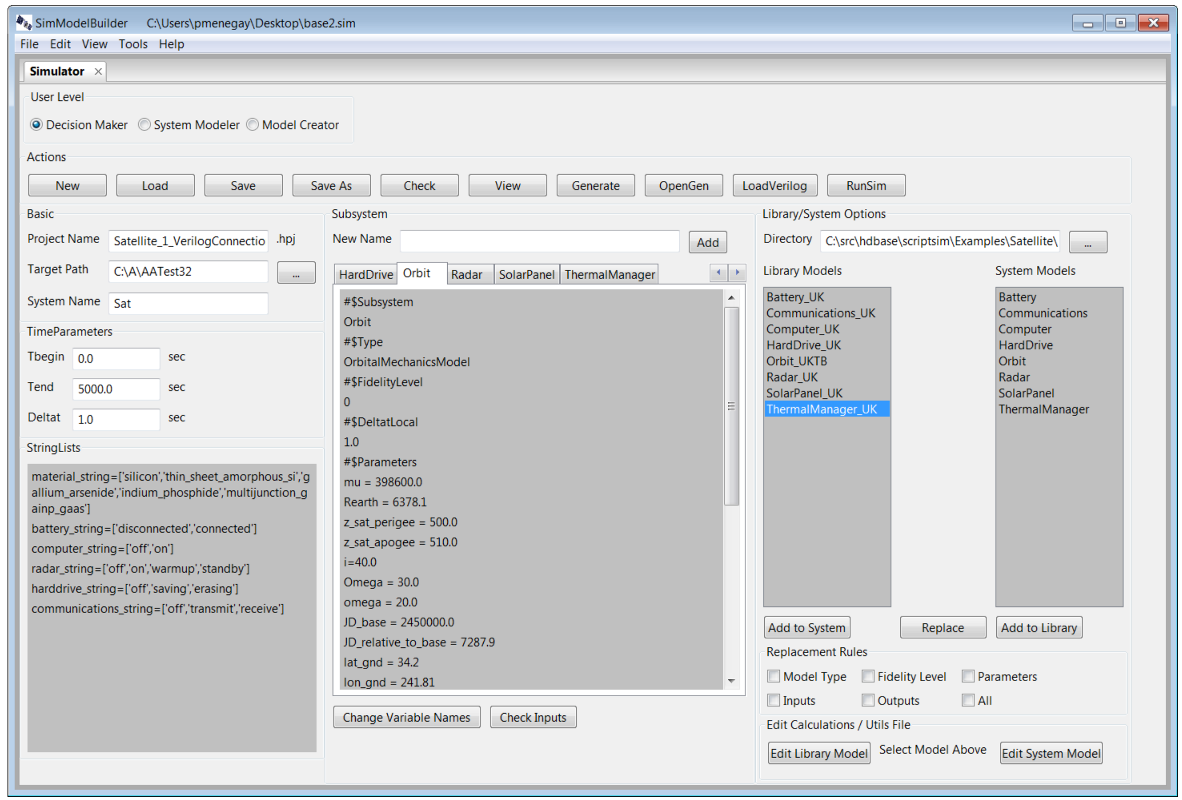
- Solves any system of nonlinear simultaneous equations.
- Manages the core numerical library to achieve robustness.
- Generates Python functions to use in simulation code.
- Uses a library concept for storing functions for later use.



2. System Builder

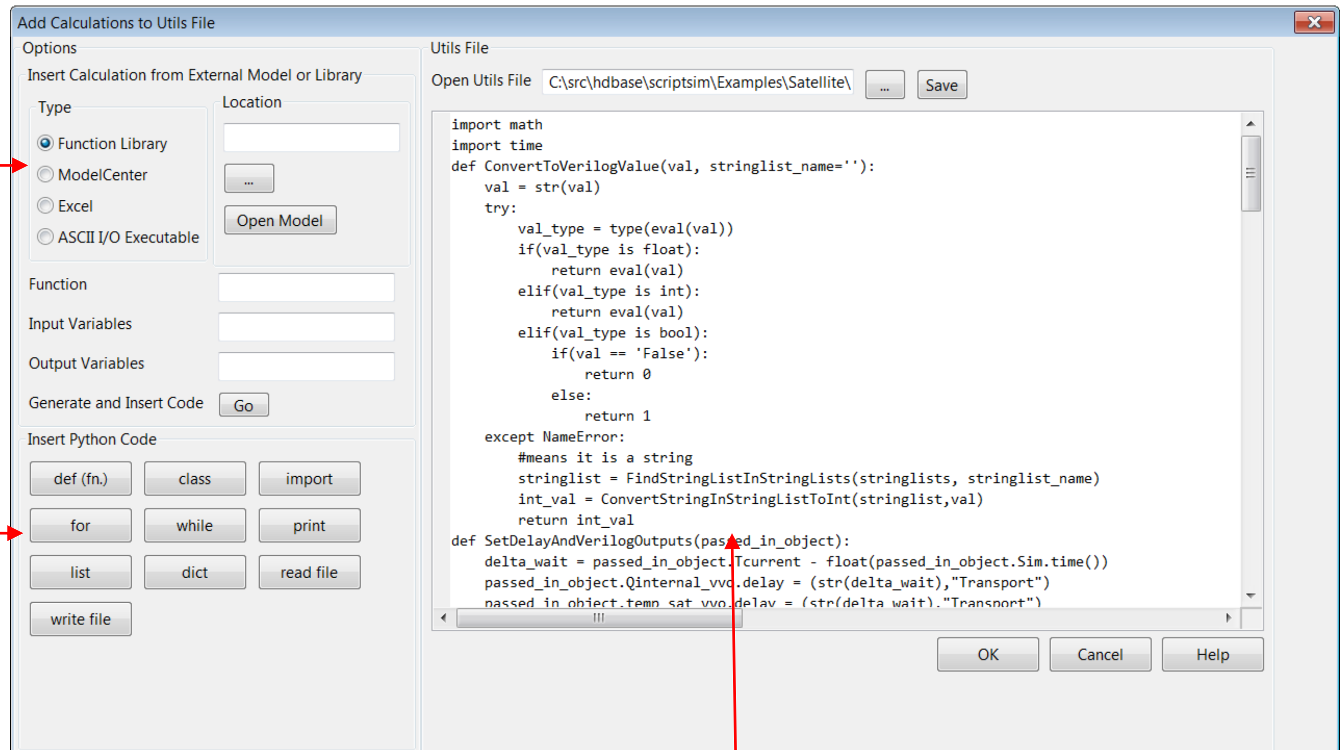
A GUI that helps you build, connect, and modify sub-system models for simulation.

- Create system models from a library of pre-built subsystems.
- Create subsystem models from equation solver and external tools.
- Publish subsystems to library.
- Easily replace subsystems with higher/lower fidelity ones.



2. System Builder, cont.

Includes a feature to help you edit calculations or link to them from external tools.



Link to pre-built models in SolverCAD, ModelCenter, Excel, or your own program.

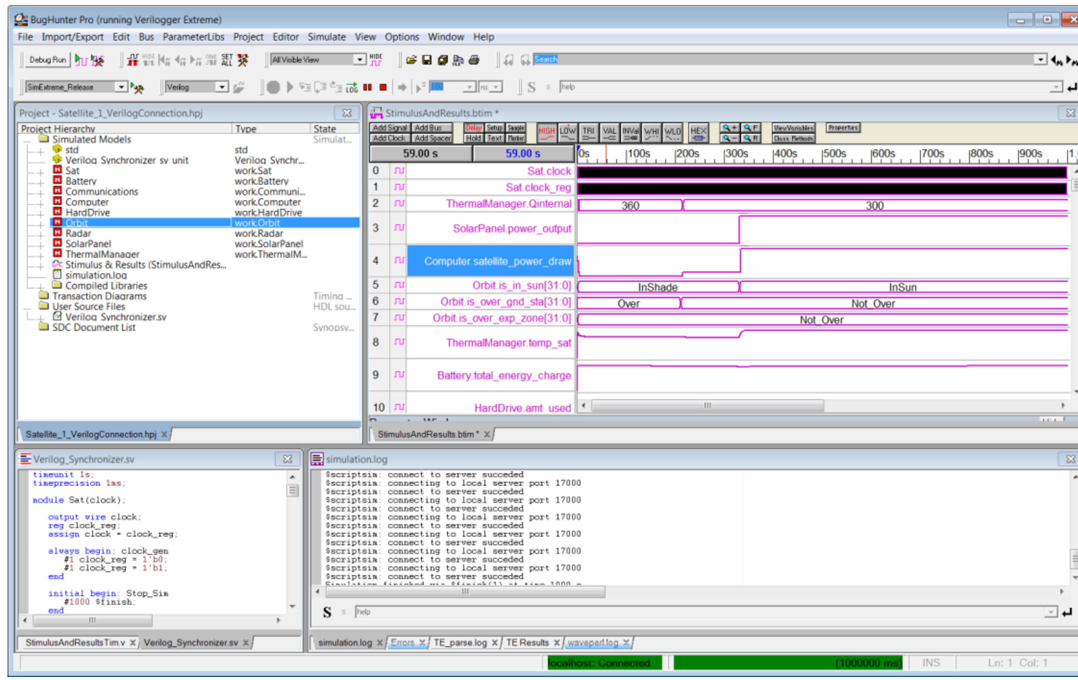
Buttons for quickly creating common Python constructs.

Edit the calculation file for any subsystem in Python.

3. System Simulator

The system simulator combines a high-performance compiled-code SystemVerilog simulator with a Python interpreter to enable engineering level modeling of real world systems.

- Timing diagram with simulation results
- Generated SystemVerilog code.
- Hierarchical view of subsystems and components.
- Full IDE including single step debugging, breakpoints, etc.
- Design browsing & navigation.
- Various output formats



VeriLogger Extreme

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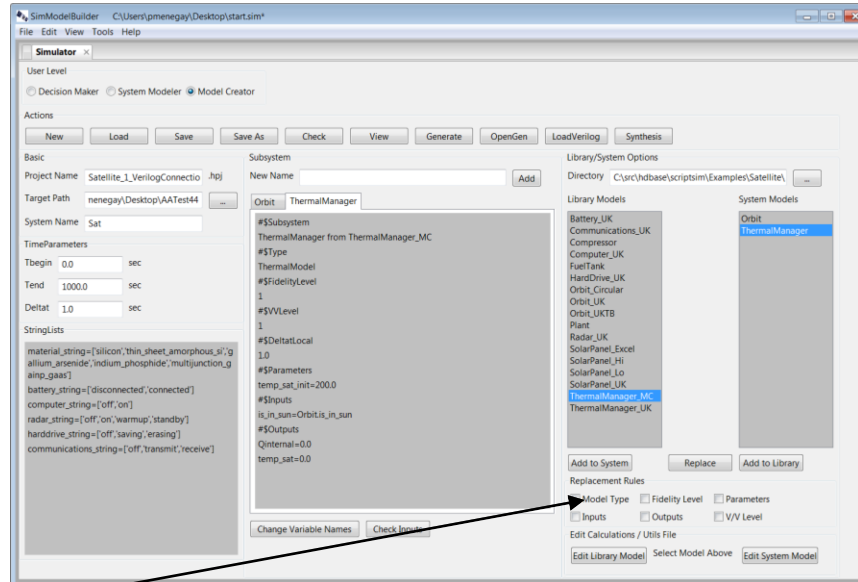
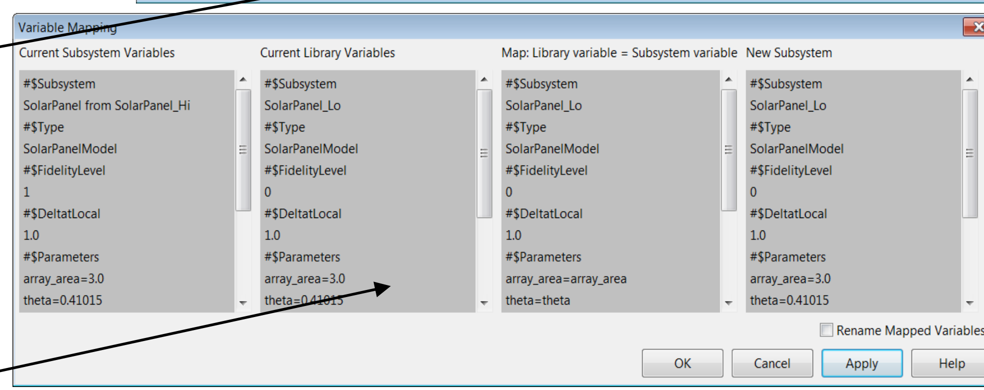
Multifidelity Modeling

- Models of different fidelity can be switched on the fly.
- As the project advances, the simulation environment remains in place, and maintains connectiveity with previous models.



Replacement rules for switching model fidelity



Variable mapping to ensure continuity between models

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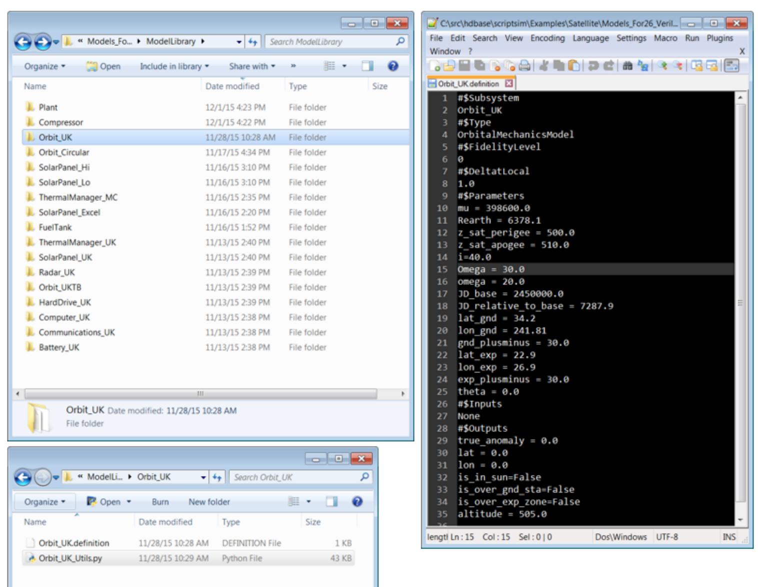
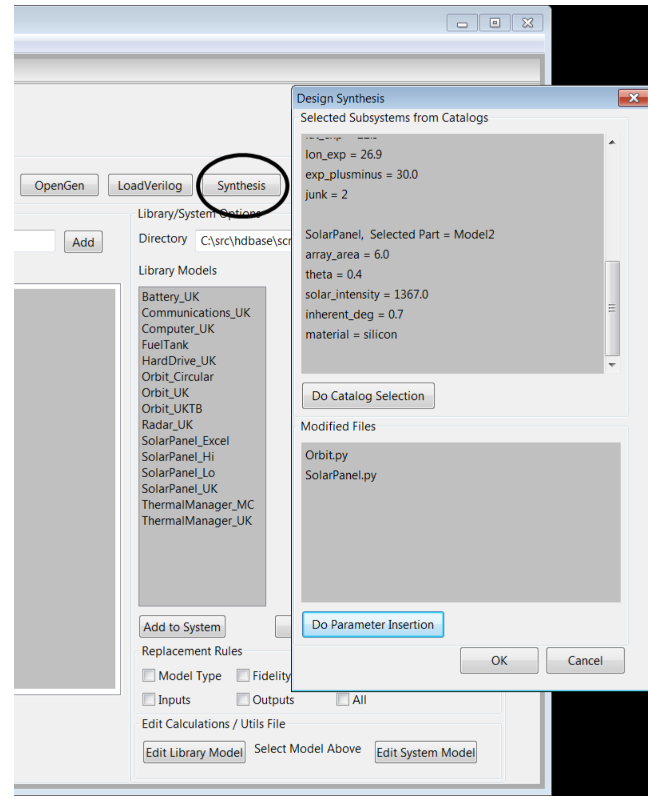
Model Libraries

- Subsystem model library.
  - Orbit calculations, solar panel, battery, etc. are publishable and retrievable from library.
- Function library for equation solver.
  - Generated functions can be accessed by System Builder.



Synthesis

- Compares simulation subsystems with a catalog of parts.
  - User has presumably optimized the subsystem and now wants to select hardware.
  - Software will choose the closest part from catalog and resimulate.



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Satellite Model

Satellite circles the earth in a standard elliptical orbit. It's mission is to collect earth data over an experimental zone and download it to a ground station at another location. It charges a battery in the sun and depletes the battery in the shade. The simulation objective is to understand if the subsystems are sized properly.

Orbit
PAR mu=398600.0
PAR Rearth=6378.1
PAR z_sat_perigee=500.0
PAR z_sat_apogee=510.0
PAR i=40.0
PAR Omega=30.0
PAR omega=20.0
PAR JD_base=2450000.0
PAR JD_relative_to_base=7287.9
PAR lat_gnd=34.2
PAR lon_gnd=241.81
PAR gnd_plusminus=30.0
PAR lat_exp=22.9
PAR lon_exp=26.9
PAR exp_plusminus=30.0
PAR theta=0.0
INP None
OUT true_anomaly=0.0
OUT lat=0.0
OUT lon=0.0
OUT is_in_sun=False
OUT is_over_gnd_sta=False
OUT is_over_exp_zone=False
OUT altitude=505.0

Sat
tbegin=0.0
tend=1000.0
deltat=100.0

SolarPanel
PAR array_area=3.0
PAR theta=0.41015
PAR solar_intensity=1367.0
PAR inherent_deg=0.77
PAR material='silicon',material_string
INP is_in_sun=Orbit.is_in_sun
OUT power_output=0.0

Computer
PAR power_rating=100.0
PAR on_state_init='on',computer_string
INP solar_panel_power_output=SolarPanel.power_output
INP radar_power=Radar.power
INP harddrive_power=HardDrive.power
INP comm_power=Communications.power
INP is_over_gnd_sta=Orbit.is_over_gnd_sta
INP is_over_exp_zone=Orbit.is_over_exp_zone
OUT satellite_power_draw=0.0
OUT on_state='off',computer_string
OUT power=0.0
OUT radar_command='off',radar_string
OUT harddrive_command='off',harddrive_string
OUT communications_command='off',communications_string

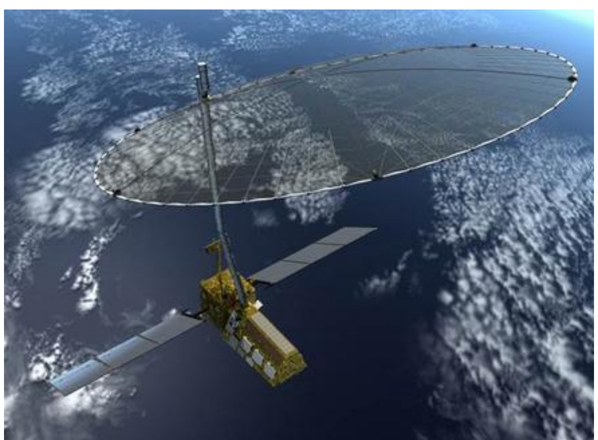
Battery
PAR capacity_rating=360000.0
PAR voltage_rating=12.0
PAR total_energy_charge_init=2160000.0
PAR con_state='connected',battery_string
INP satellite_power_draw=Computer.satellite_power_draw
OUT total_energy_charge=0.0

Radar
PAR power_on=300.0
PAR power_standby=200.0
PAR power_warmup=100.0
PAR power_off=0.0
INP command=Computer.radar_command
OUT power_state='off',radar_string
OUT power=0.0

HardDrive
PAR storage_capacity=650.0
PAR store_speed=0.5
PAR erase_speed=1.0
PAR power_rating=10.0
PAR amt_used_init=300.0
INP command=Computer.harddrive_command
OUT on_state='off',harddrive_string
OUT store_rate=0.0
OUT erase_rate=0.0
OUT power=0.0
OUT amt_used=0.0

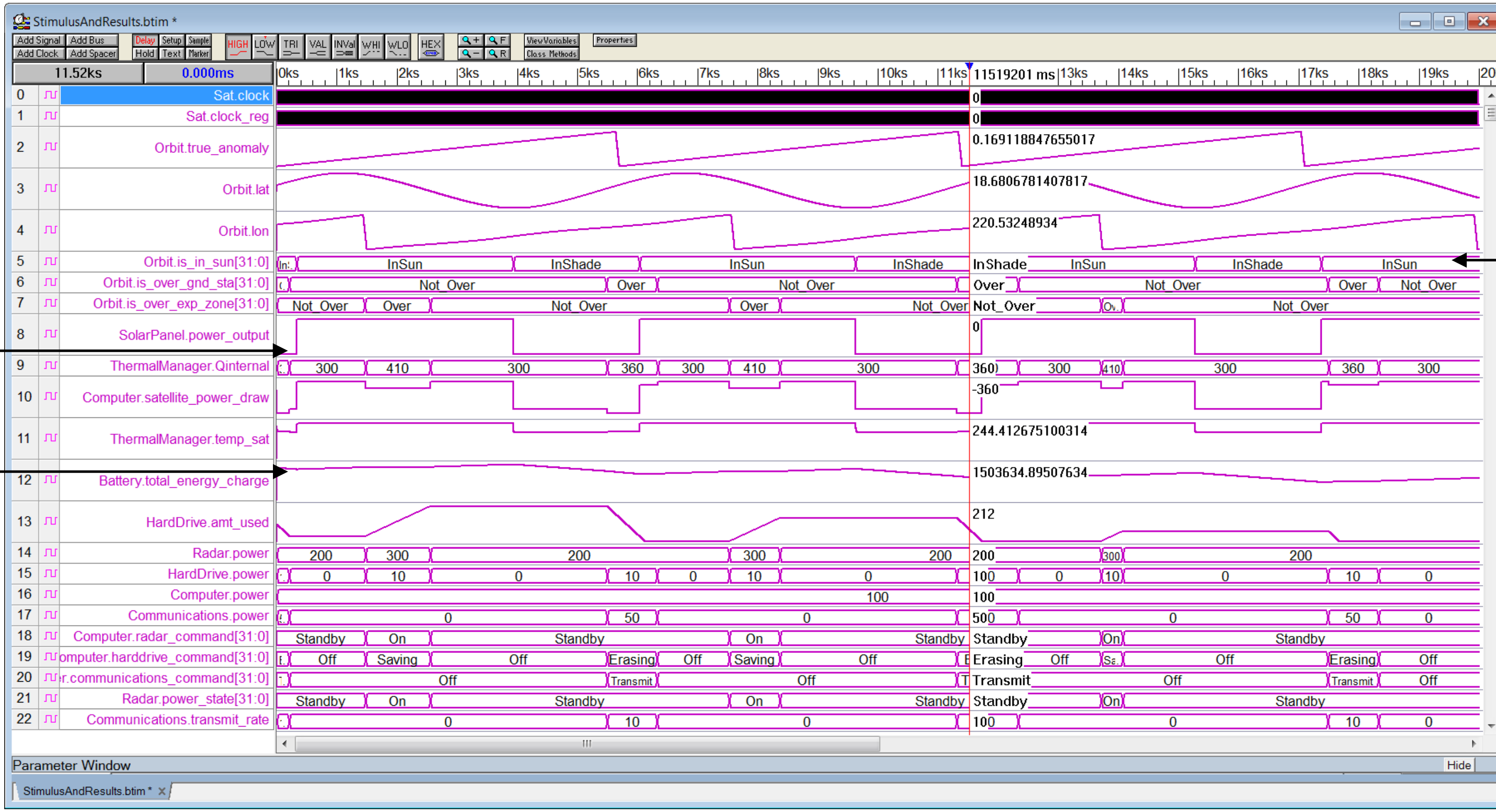
Communications
PAR transmit_speed=10.0
PAR receive_speed=20.0
PAR power_rating=50.0
INP command=Computer.communications_command
OUT on_state='off',communications_string
OUT transmit_rate=0.0
OUT receive_rate=0.0
OUT power=0.0

ThermalManager
PAR earth_albedo=0.3
PAR solar_intensity=1388.0
PAR stefan_boltzmann_const=5.67e-8
PAR temp_earth=290.0
PAR temp_sun=5800.0
PAR temp_space=2.7
PAR radius_earth=6378.1*1000.0
PAR sat_diameter=1.0
PAR sat_absorptivity=0.7
PAR sat_emissivity=0.9
PAR earth_emissivity=0.5
PAR sat_thermal_capacity=50.0
PAR temp_sat_init=300.0
PAR sat_weight=10.0
INP is_in_sun=Orbit.is_in_sun
INP sat_altitude=Orbit.altitude
INP radar_power=Radar.power
INP computer_power=Computer.power
INP harddrive_power=HardDrive.power
INP comm_power=Communications.power
OUT Qinternal=0.0
OUT temp_sat=0.0



NASA / JPL

Results



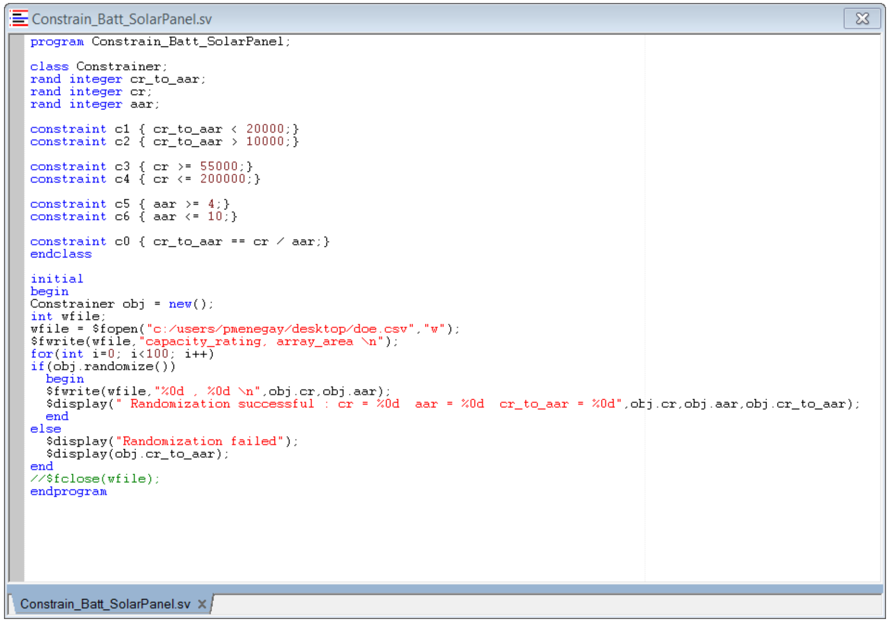
Battery slowly drains to 0

Solar Panel does not recharge it when exposed to sun

Ie, the Solar Panel is undersized. Battery is oversized.

Results, cont.

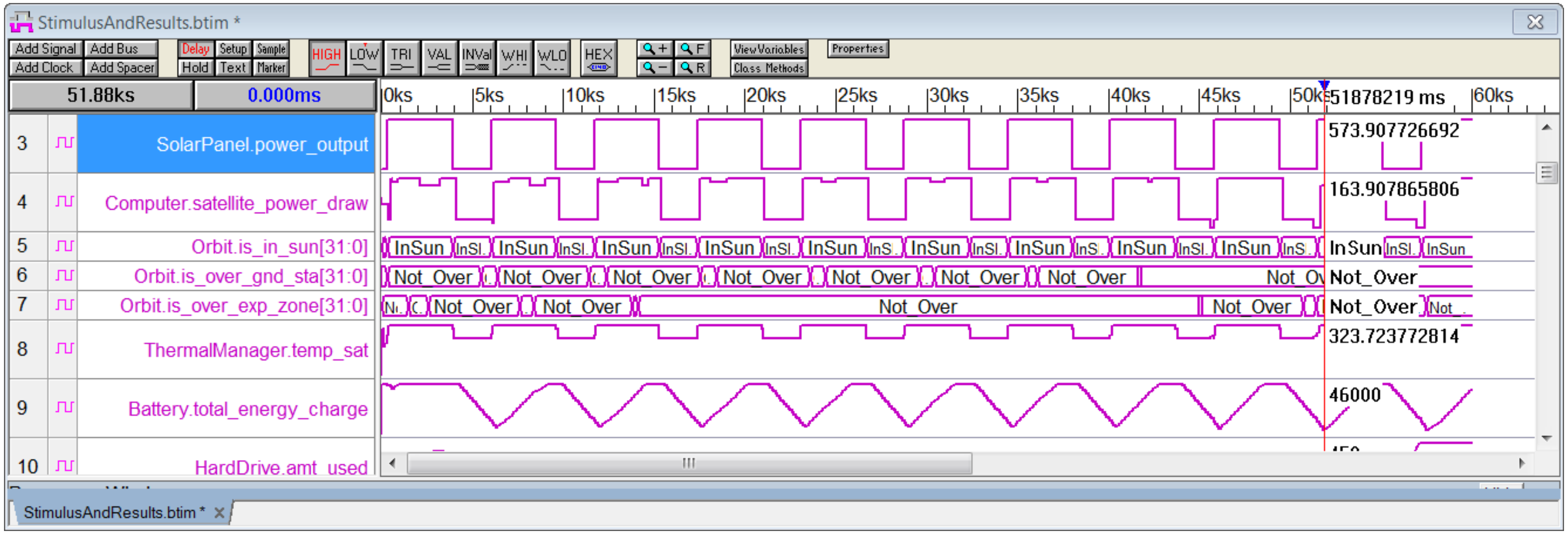
- One way to vary the solar panel / battery size is to use constrained randomization.
- Solution was to increase the solar panel area from 3.0 to 4.0 m**2 and decrease the battery capacity from 360,000 to 60,000 amp-sec.



Constrain_Batt_SolarPanel.sv

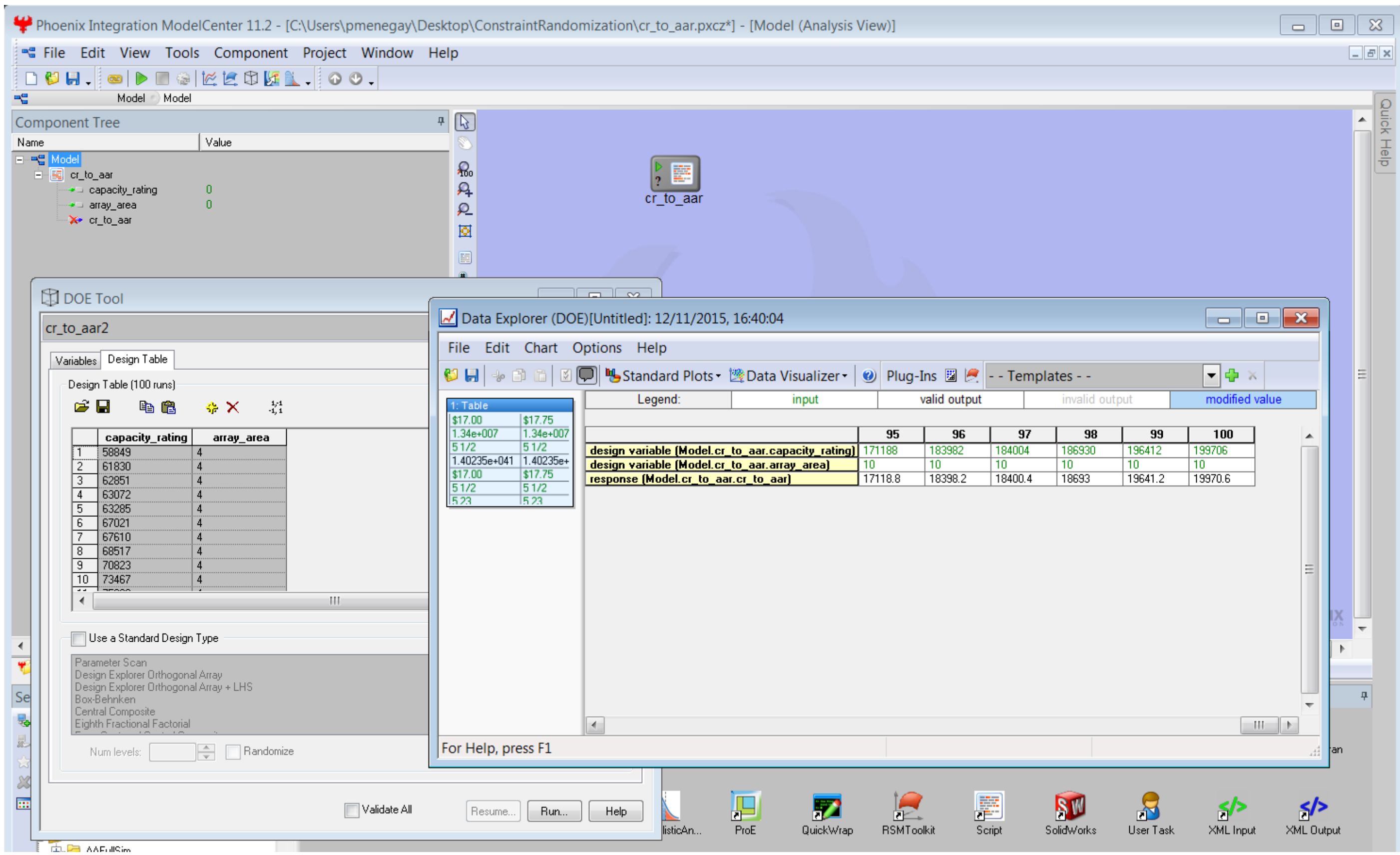
```
program Constrain_Batt_SolarPanel;

class Constrainer;
rand integer cr_to_aar;
rand integer cr;
rand integer aar;

constraint c1 { cr_to_aar < 20000;}
constraint c2 { cr_to_aar > 10000;}

constraint c3 { cr >= 55000;}
constraint c4 { cr <= 200000;}

constraint c5 { aar >= 4;}
constraint c6 { aar <= 10;}

constraint c0 { cr_to_aar == cr / aar;}
endclass

initial
begin
Constrainer obj = new();
int wfile;
wfile = $fopen("c:/users/pmenegay/desktop/doe.csv","w");
$fwrite(wfile,"capacity_rating, array_area \n");
for(int i=0; i<100; i++)
if(obj.randomize())
  begin
  $fwrite(wfile,"%0d , %0d \n",obj.cr,obj.aar);
  $display(" Randomization successful : cr = %0d  aar = %0d  cr_to_aar = %0d",obj.cr,obj.aar,obj.cr_to_aar);
  end
else
  $display("Randomization failed");
  $display(obj.cr_to_aar);
end
//$fclose(wfile);
endprogram
```

Constrain_Batt_SolarPanel.sv



Results, cont.

- This could also have been achieved by driving the simulator from a ModelCenter DOE.



Overall Results

- Once engineering models were made, system integration was fast, 1-2 days for this case.
  - Model libraries were key.
- Provision for multi-fidelity model switching allowed project to remain within a single environment throughout its life.
- Scalability tests on a simple vehicle object lends credence to the SystemVerilog approach.
  - SystemVerilog can simulate up to memory limits of computer. 18 million vehicles for 32-bit and 40 million for 64 bit.
  - SimPy by contrast could simulate 900,000 such objects.
- Runs could be made faster by using event-driven simulation. A 10 fold speed up was achieved this way.
  - Important for long run times over the life of the system.

We thank the NASA SBIR program for sponsoring this work.
Contract NNX15CP26P.

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